

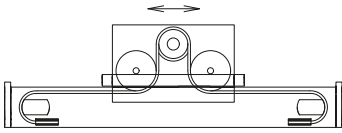
# Linear system **DSSZ 120, 160, 200**

## BELT DRIVE

 OMEGA SYSTEM

 HORIZONTAL INSTALLATION POSITION

 OFF-CENTER LOADS



### Function:

This linear unit consists of a rectangular aluminium profile with integrated rail guides. The carriage, which has runner blocks, is driven by a timing belt. Each standard pulley includes a coupling claw on one side and is equipped with maintenance-free ball bearings. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel.

### Fitting position:

As required. Max. length 6.000 mm without joints.

### Carriage mounting:

By T-slots.

### Unit mounting:

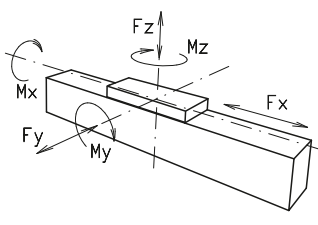
By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt performance:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 4 runner blocks which can be serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.

Forces and torques	Size	120		160		200	
	permitted dyn. Forces*	5000 km	10000 km	5000 km	10000 km	5000 km	10000 km
	$F_x$ (N)	1900	1800	4000	3800	5900	5750
	$F_y$ (N)	1776	1405	5570	3900	15600	11080
	$F_z$ (N)	2090	1650	7050	5020	20600	14600
	$M_x$ (Nm)	81	64	358	255	1285	915
	$M_y$ (Nm)	97	77	369	262	1375	980
	$M_z$ (Nm)	96	76	364	258	1345	960
<b>All forces and torques related to the following:</b>							
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
<b>No-load torque</b>							
	(Nm)	1,4		1,8		2,2	
<b>Speed</b>							
	(m/s) max	5		5		5	
<b>Tensile force</b>							
	permanent (N)	1900		4000		5900	
	0,2 s (N)	2090		4300		6350	
<b>Geometrical moments of inertia of aluminium profile</b>							
	$I_x$ mm <sup>4</sup>	5,61x10 <sup>5</sup>		2,13x10 <sup>6</sup>		48,07 x10 <sup>5</sup>	
	$I_y$ mm <sup>4</sup>	34,19x10 <sup>5</sup>		12,33x10 <sup>6</sup>		259,99 x10 <sup>5</sup>	
	Elastic modulus N/mm <sup>2</sup>	70000		70000		70000	

For life-time calculation use our homepage.

\* referred to life-time

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

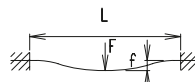
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 Si = safety factor 1,2 ... 2  
 Mn = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 Mo = driving torque (Nm)  
 Po = motor power (KW)

Deflection:

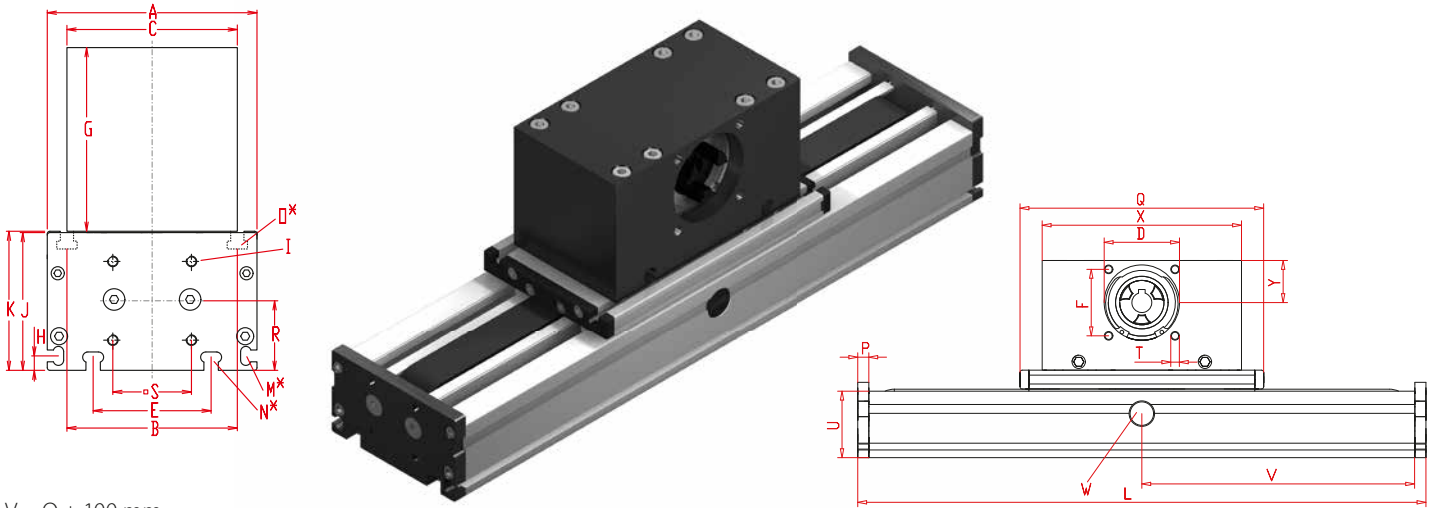
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **DSSZ 120, 160, 200**

Dimensions (mm)



$V = Q + 100 \text{ mm}$

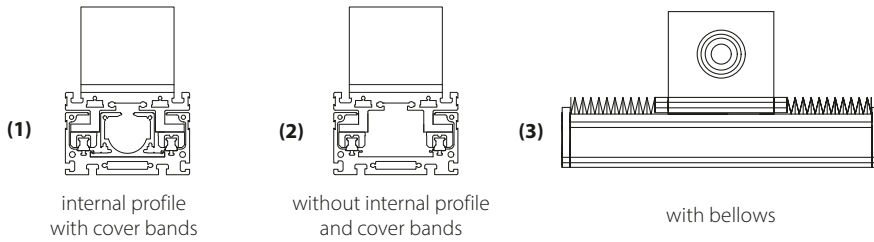
W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

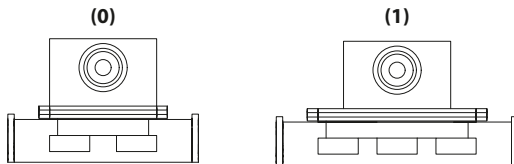
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	I for	M for	N for	O for	P	Q	R	S	T	U	X	Y	Basic weight	Weight per 100 mm
DSSZ 120	230	120	96	100	68	78	60	100	10	68	79	M 6	M 5	M 6	M 6	10	200	39	42	M 8	60	180	39	12,0 kg	1,2 kg
DSSZ 160	330	160	130	130	90	90	80	130	11	105	106	M 8	M 6	M 8	M 8	12	290	53	60	M 10	80	270	60	27,8 kg	1,8 kg
DSSZ 200	380	200	160	160	110	140	100	143	15	128	129	M 10	M 8	M 10	M 10	15	340	62,5	95	M 10	100	310	62	53,0 kg	2,6 kg

**1 Choice of guide body profile:** Stainless versions upon request.

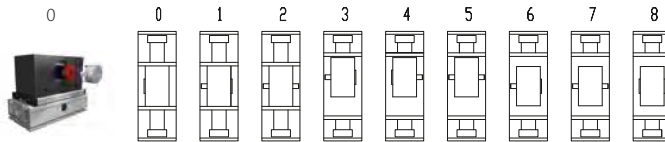


**0 Choice of carriages:**



Size	Version 0		Version 1	
	Q	L	Q	L
120	200	230	200	230
160	290	330	290	330
200	340	380	340	380

**0 Drive version:**



8 is as 0, but with coupling claws on both sides. The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 200).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 7	120	8M30	192	24
0 9	160	8M50	256	32
1 0	200	8M70	304	38

**Shaft dimensions:**

Size	Shaft $\varnothing$ h6 x length	Key
120	18 x 45	6x6x40
160	22 x 45	6x6x40
200	30 x 55	8x7x50

**DSSZ 160 1 1 0 0 0 9 1 1500**

Pos. 1 2 3 4 5 6 7

Basic length + stroke = total length

Sample ordering code:

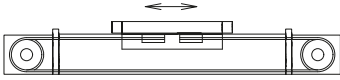
DSSZ160, body profile with internal profile without cover bands, standard carriage, coupling claws on one side, 1170 mm stroke

# Linear system **DSZ 120, 160, 200**

## BELT DRIVE

↔ UNIVERSAL SYSTEM

🌀 LONG TRAVERSE PATH > 6000 MM



### Function:

This unit consists of a rectangular aluminium profile with 2 integrated rail guidess. The carriage is moved by a belt drive. Each standard pulley has got one coupling claw on one side. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. The openings of the guide body are sealed with 3 stainless steel cover bands to protect the guide from splash water and dust. Alternatively, it can also be supplied without cover bands. With this series, multi-part assembled units with long strokes can be realized.

### Fitting position:

As required. Max. length 6.000 mm without joints.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 4 runner blocks which can be serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.

9.1

Forces and torques	Size	120		160		200	
	permitted dyn. Forces*	5000 km	10000 km	5000 km	10000 km	5000 km	10000 km
$F_x$ (N)		894	800	1900	1800	4000	3800
$F_y$ (N)		1776	1405	5570	3900	15600	11080
$F_z$ (N)		2090	1650	7050	5020	20600	14600
$M_x$ (Nm)		81	64	358	255	1285	915
$M_y$ (Nm)		97	77	369	262	1375	980
$M_z$ (Nm)		96	76	364	258	1345	960
<b>All forces and torques related to the following:</b>							
existing values	$\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$						
table values							
<b>No-load torque</b>							
Nm without cover bands		1,2		1,5		2,0	
Nm with cover bands		1,6		2,1		4	
<b>Speed</b>							
(m/s) max		5		5		5	
<b>Tensile force</b>							
permanent (N)		900		1900		4000	
0,2 s (N)		1000		2090		4300	
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_y$ mm <sup>4</sup>		5,61x10 <sup>5</sup>		2,13x10 <sup>6</sup>		4,81 x10 <sup>6</sup>	
$I_z$ mm <sup>4</sup>		34,19x10 <sup>5</sup>		12,33x10 <sup>6</sup>		26,0 x10 <sup>6</sup>	
Elastic modulus N/mm <sup>2</sup>		70000		70000		70000	

For life-time calculation use our homepage.

\* referred to life-time

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

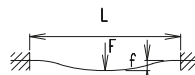
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

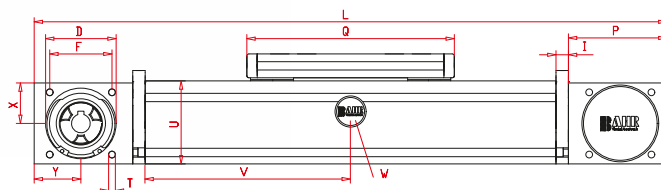
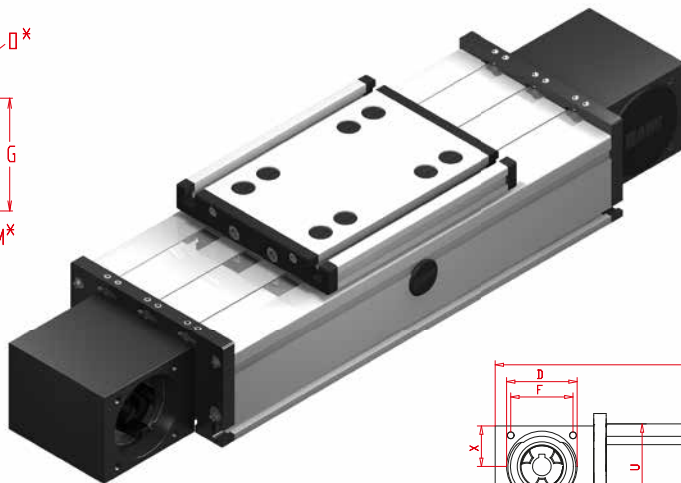
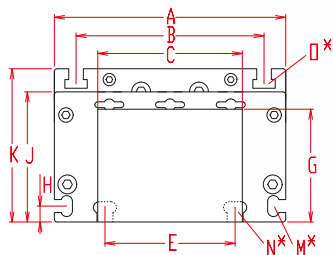
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **DSZ 120, 160, 200**

Dimensions (mm)



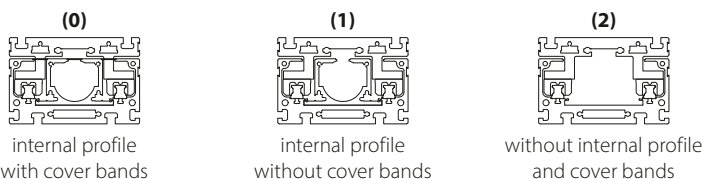
V = Q + 100 mm  
W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

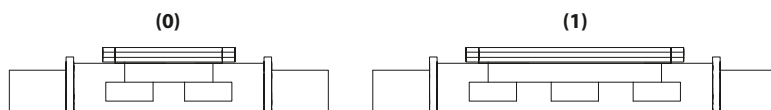
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	I	J	K	M for	N for	O for	P	Q	T	U	X	Y	Basic weight	Weight per 100 mm
DSZ 120	330	120	96	80	47	78	42	58	10	10	68	79	M 5	M 6	M 6	70	156	M 6	60	28	35	5,1 Kg	0,85 Kg
DSZ 160	440	160	130	100	68	90	60	78	11	12	90	106	M 6	M 8	M 8	95	200	M 8	80	39	45	12,0 kg	1,9 kg
DSZ 200	530	200	160	130	90	140	80	97	15	15	110	129	M 8	M 10	M 10	110	270	M 10	100	49	50	21,3 kg	2,9 kg

**0 Choice of guide body profile:** Stainless versions upon request.

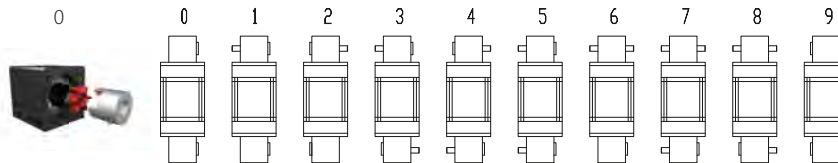


**0 Choice of carriages:**



Size	Version 0		Version 1	
	Q	L	Q	L
120	156	330	156	330
160	200	440	>230	>470
200	270	530	>310	>570

**0 Drive version:**



9 is as 0, but with coupling claws on both sides.  
The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 200).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	120	5M25	130	26
0 7	160	8M30	176	22
0 9	160	8M50	176	22
0 9	200	8M50	224	28
1 0	200	8M70	224	28

**Shaft dimensions / Coupling:**

Size	Shaft ø h6 x length	Key	Coupling
120 (5M25)	14 x 35	5x5x28	14
160 (8M30)	18 x 45	6x6x40	19
160 (8M50)	25 x 35	8x7x32	----*
200 (8M50)	22 x 45	6x6x40	24
200 (8M70)	30 x 55	8x7x50	----*

\* Coupling claw not possible with belt widening.

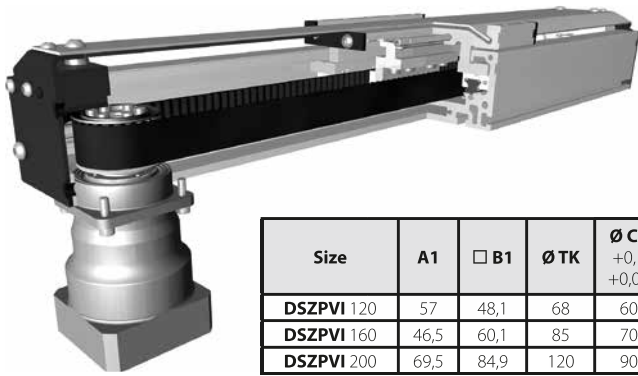
**DSZ 160 1 0 0 0 0 7 1 1500** — Basic length + stroke = total length  
Pos. 1 2 3 4 5 6 7

Sample ordering code:

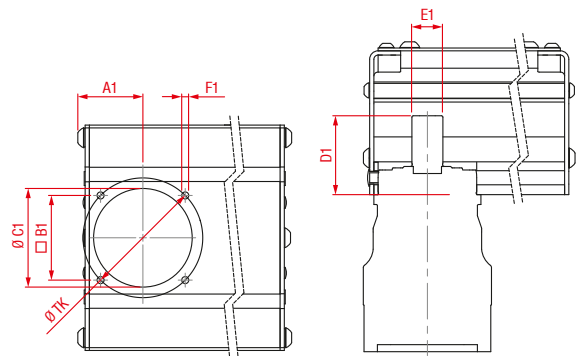
DSZ160 with internal profile and cover bands, standard carriage, coupling claw on one side, 1060 mm stroke.

# Linear system **DSZPVI 120, 160, 200**

## BELT DRIVE



Size	A1	□ B1	Ø TK	Ø C1 +0,1 +0,05	D1	E1	F1
<b>DSZPVI 120</b>	57	48,1	68	60	48	16	M5
<b>DSZPVI 160</b>	46,5	60,1	85	70	56	22	M6
<b>DSZPVI 200</b>	69,5	84,9	120	90	88	32	M8



### Function:

This unit consists of a rectangular aluminium profile with 2 integrated rail guides. The carriage is moved by a belt drive. On the drive side the pulley is beared on the shaft of a planetary gear. Belt tension can be readjusted by a simple screw adjustment at the opposite side of the drive. A special curved aluminium sheet is covering the carriage side. There is only a small gap between carriage and aluminium sheet. Because of its special design it is possible to drive the carriage over the pulley areas. This fact is making the unit very compact.

### Fitting position:

As required, max. length DSZPVI 120 / 1600mm, DSZPVI 160 / 1800mm, DSZPVI 200 / 2000mm

### Carriage mounting:

By tapped holes.

### Unit mounting:

T-slots

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 4 runner blocks which can be serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.

9.1

Forces and torques	Size	120		160		200	
	permitted dyn. Forces*	5000 km	10000 km	5000 km	10000 km	5000 km	10000 km
$F_x$ (N)	894	800	1900	1800	4000	3800	
$F_y$ (N)	1776	1405	5570	3900	15600	11080	
$F_z$ (N)	2090	1650	7050	5020	20600	14600	
$M_x$ (Nm)	81	64	358	255	1285	915	
$M_y$ (Nm)	97	77	369	262	1375	980	
$M_z$ (Nm)	96	76	364	258	1345	960	
<b>All forces and torques related to the following:</b>							
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
<b>No-load torque</b>							
Nm without cover bands		1,2		1,5		2,0	
<b>Speed</b>							
(m/s) max		5		5		5	
<b>Tensile force</b>							
permanent (N)		900		1900		4000	
0,2 s (N)		1000		2090		4300	
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup>		5,61x10 <sup>5</sup>		2,32 x 10 <sup>5</sup>		48,07 x 10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		34,19x10 <sup>5</sup>		123,36 x 10 <sup>5</sup>		259,99 x 10 <sup>5</sup>	
Elastic modulus N/mm <sup>2</sup>		70000		70000		70000	

For life-time calculation use our homepage.

\* referred to life-time

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

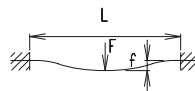
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 Si = safety factor 1,2 ... 2  
 Mn = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 Mo = driving torque (Nm)  
 Po = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

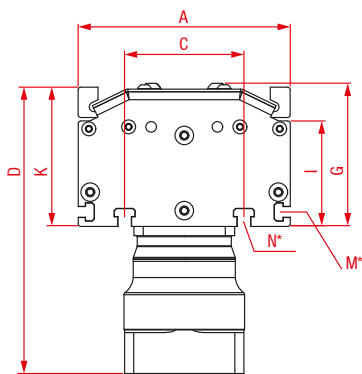
f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



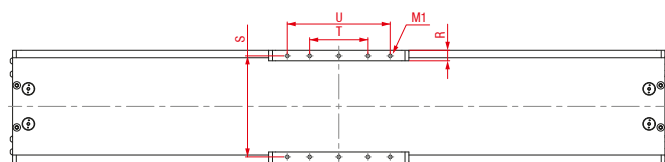
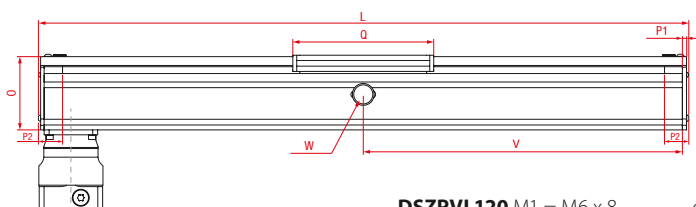
# Linear system **DSZPVI 120, 160, 200**

Dimensions (mm)

Increasing the carriage length will increase the basic length by the same amount.



Optionally available with angular planetary gearbox



**DSZPVI 120** M1 = M6 x 8      only 8 threaded holes in the carriage

\*For slide nuts refer to chapter 2.2 page 2

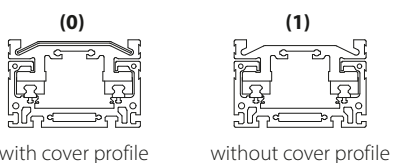
**DSZPVI 160** M1 = M8 x 12      **DSZPVI 200** M1 = M10 x 12

W = servicing position

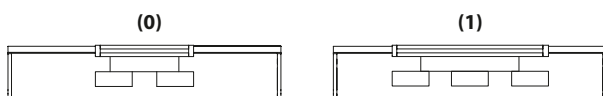
Size	Basic length L	A	C	D	G	I	K	M for	N for	O	P1	P2	Q	R	S	T	U	Basic weight without gearbox	Weight per 100 mm
<b>DSZPVI 120</b>	225	120	78	169	82,5	60	79,5	M5	M6	78	6	35	152	11,5	106	40	120	3,45 kg	0,87 kg
<b>DSZPVI 160</b>	285	160	90	217,5	108,5	80	106	M6	M8	104	8,25	43,5	196	15	144	80	160	10,27 kg	1,55 kg
<b>DSZPVI 200</b>	350	200	140	251	132,5	100	129	M8	M10	128	10	45,5	248	17	180	100	200	18,20 kg	2,14 kg

9.1

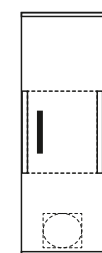
**0** Choice of guide body profile: Stainless versions upon request.



**0** Choice of carriages:

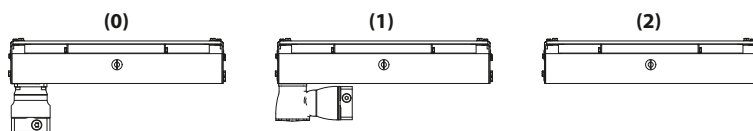


Size	Version 1	
	Q	L
<b>120</b>	>152	>225
<b>160</b>	>228	>330
<b>200</b>	>290	>430



belt connection

**0** Drive version:



- (0) planetary gearbox
- (1) angular planetary gearbox
- (2) without gearbox

**Belt table:**

Code-No.	Size	Belt	mm/rev.	Number of teeth
<b>0 4</b>	<b>120</b>	5M25	130	26
<b>0 7</b>	<b>160</b>	8M30	176	22
<b>0 9</b>	<b>200</b>	8M50	224	28

**Gearbox variants:**

Gearbox	DSZPVI 120	DSZPVI 160	DSZPVI 200
<b>Neugart</b>	(0) PLN 70 (1) WPLN 70	PLN 90 WPLN 90	PLN 115 WPLN 115
<b>SEW</b>	(0) PSKC 221	PSKC 321	PSKC 521
<b>Wittenstein</b>	(0) SP+060 (1) SK+060	SP+075 SK+075	SP+100 SK+100

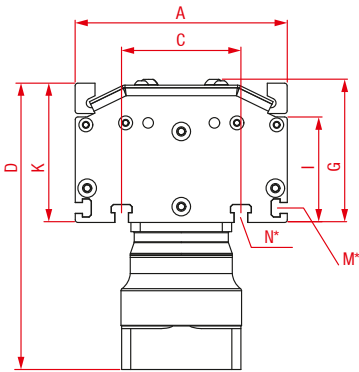
**DSZPVI 160 1 0 0 0 0 7 1 1500**      Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

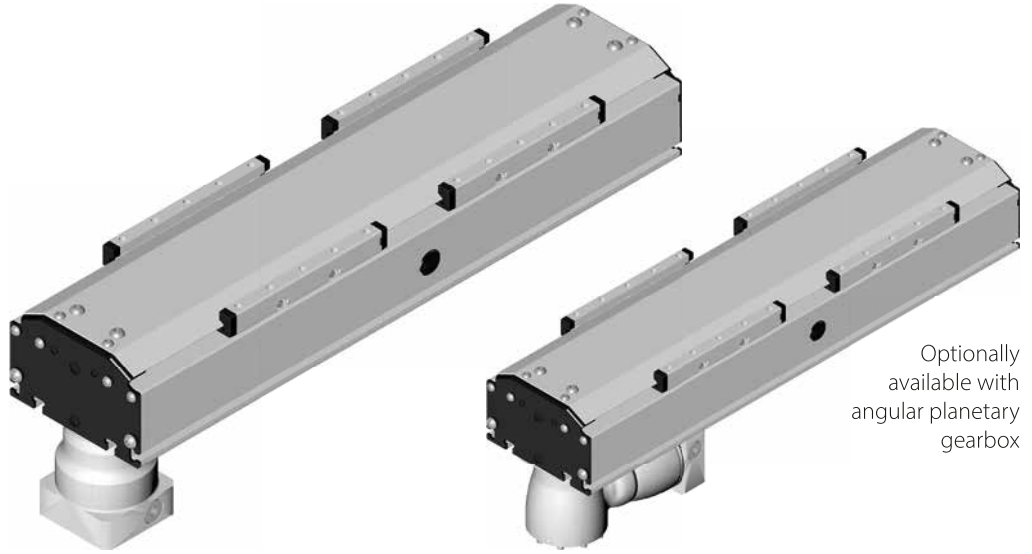
Sample ordering code:  
DSZPVI 160 with cover profile, standard carriage, with planetary gearbox, 1202 mm stroke.

# Linear system **DSZPVI 120, 160, 200**

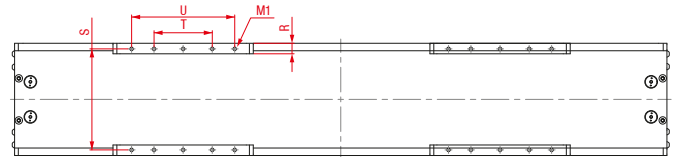
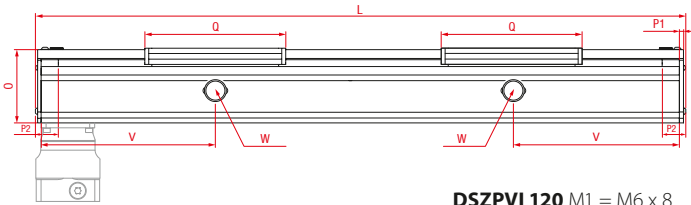
## BELT DRIVE, WITH TWO DRIVEN CARRIAGES



Increasing the carriage length will increase the basic length by the same amount.



Optionally available with angular planetary gearbox



**DSZPVI 120** M1 = M6 x 8

only 8 threaded holes in the carriage

**DSZPVI 160** M1 = M8 x 12

**DSZPVI 200** M1 = M10 x 12

V = Q + 100

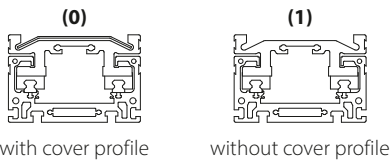
W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

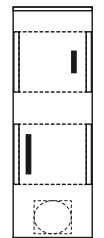
Size	Basic length L	A	C	D	G	I	K	M for	N for	O	P1	P2	Q	R	S	T	U	Basic weight without gearbox	Weight per 100 mm
<b>DSZPVI 120</b>	380	120	78	169	82,5	60	79	M5	M6	78	2	35	152	11,5	106	40	120	4,3 kg	0,9 kg
<b>DSZPVI 160</b>	485	160	90	217,5	108,5	80	106	M6	M8	104	3	43,5	196	15	144	80	160	12,1 kg	2,3 kg
<b>DSZPVI 200</b>	600	200	140	251	132,5	100	129	M8	M10	128	3	45,5	248	17	180	100	200	22,1 kg	3,2 kg

9.1

**0** Choice of guide body profile: Stainless versions upon request.

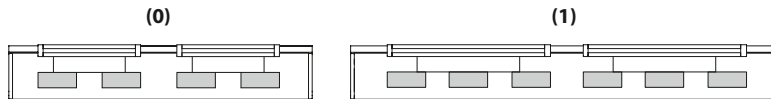


Baugröße	Ausführung 1	
	Q	L
<b>120</b>	>152	>380
<b>160</b>	>228	>549
<b>200</b>	>290	>684

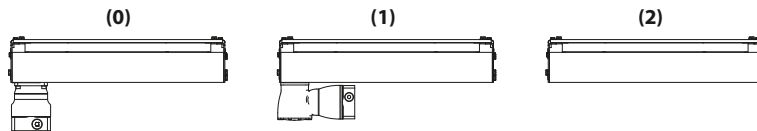


belt connection

**0** Choice of carriages:



**0** Drive version:



- (0) planetary gearbox
- (1) angular planetary gearbox
- (2) without gearbox

**Belt table:**

Code-No.	Size	Belt	mm/rev.	Number of teeth
<b>0 4</b>	<b>120</b>	5M25	130	26
<b>0 7</b>	<b>160</b>	8M30	176	22
<b>0 9</b>	<b>200</b>	8M50	224	28

**Gearbox variants:**

Gearbox	DSZPVI 120	DSZPVI 160	DSZPVI 200
<b>Neugart</b>	(0) PLN 70 (1) WPLN 70	PLN 90 WPLN 90	PLN 115 WPLN 115
<b>SEW</b>	(0) PSKC 221	PSKC 321	PSKC 521
<b>Wittenstein</b>	(0) SP+060 (1) SK+060	SP+075 SK+075	SP+100 SK+100

**DSZPVI 160 1 0 0 0 0 7 1 1500**

Basic length + stroke = total length

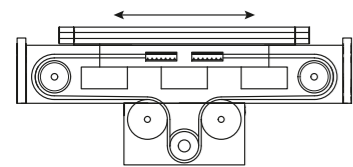
Pos. 1 2 3 4 5 6 7

Sample ordering code:

DSZPVI 160, right - left version, with cover profile, standard carriage, with planetary gearbox, 1015 mm stroke

BELT DRIVE

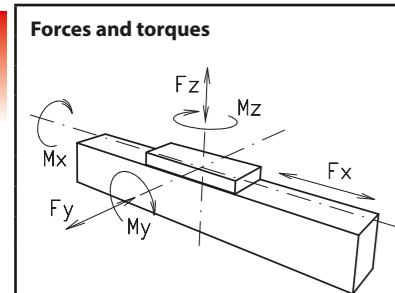
- INDEPENDENT INSTALLATION POSITION
- OMEGA SYSTEM
- LIFTING SYSTEM



**Function:**

This unit consists of a rectangular aluminium profile with 2 integrated rail guidess. The carriage is moved by a belt drive. An innovation is that the toothed belt is diverted within a drive block positioned centrally. The result is an enormous compactness with regard to the overall system length. The toothed drive pulley has a coupling claw in the standard version. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. The openings of the guide body are sealed with 3 stainless steel cover bands to protect the guide from splash water and dust. Alternatively, the opening can also delivered without cover bands.

- Fitting position:** As required. Max. length 6.000 mm without joints.
- Carriage mounting:** By T-slots.
- Unit mounting:** By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.
- Belt type:** HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.
- Carriage support:** In the standard version, the carriage runs on 4 runner blocks which can be serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.



Size	160		200	
	permitted dyn. Forces*			
F <sub>x</sub> (N)	1900	1800	4000	3800
F <sub>y</sub> (N)	5570	3900	15600	11080
F <sub>z</sub> (N)	7050	5020	20600	14600
M <sub>x</sub> (Nm)	358	255	1285	915
M <sub>y</sub> (Nm)	369	262	1375	980
M <sub>z</sub> (Nm)	364	258	1345	960
<b>All forces and torques related to the following:</b>				
existing values	$\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$			
table values				
<b>No-load torque</b>				
Nm without cover bands	1,5		2,0	
Nm with cover bands	2,1		4	
<b>Speed</b>				
(m/s) max	5		5	
<b>Tensile force</b>				
permanent (N)	1900		4000	
0,2 s (N)	2090		4300	
<b>Geometrical moments of inertia of aluminium profile</b>				
I <sub>x</sub> mm <sup>4</sup>	21,32x10 <sup>5</sup>		4,81 x10 <sup>6</sup>	
I <sub>y</sub> mm <sup>4</sup>	123,36x10 <sup>5</sup>		26,0 x10 <sup>6</sup>	
Elastic modulus N/mm <sup>2</sup>	70000		70000	

For life-time calculation use our homepage.

\* referred to life-time

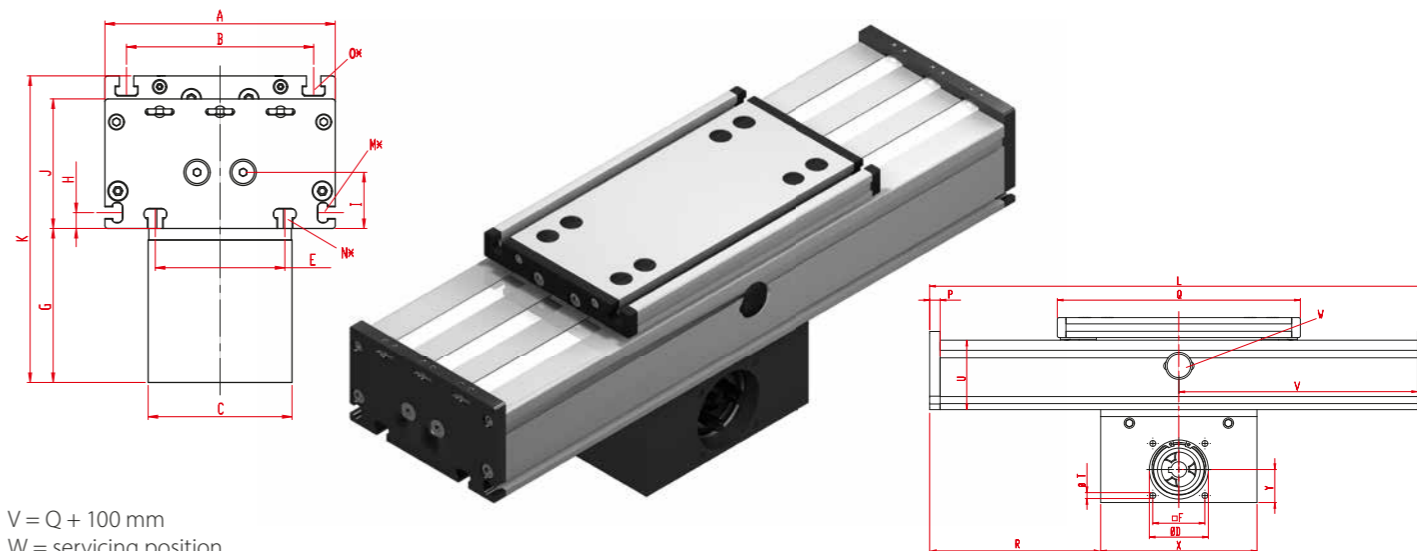
Driving torque:  $M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$

Deflection:  $f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$

$P_o = \frac{M_o \cdot n}{9550}$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



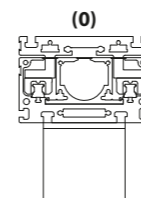
V = Q + 100 mm  
 W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

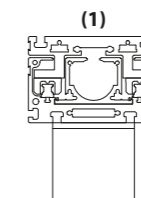
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length	A	B	C	D -0,05	E	F	G	H	I	J	K	M for	N for	O for	P	Q	R	T	U	X	Y	Basic weight	Weight per 100 mm
DSZS 120	230	120	96	80	47	78	42	84,5	10	28,7	68	167	M5	M6	M6	10	156	50	M6	60	130	30	6,2 kg	0,9 kg
DSZS 160	310	160	130	100	68	90	60	107	11	39	90	213	M6	M8	M8	12	280	65	M8	80	180	39	23,0 kg	1,9 kg
DSZS 200	380	200	160	130	90	140	80	146	15	48,5	110	275	M8	M10	M10	15	340	60	M10	100	270	60	33,0 kg	2,4 kg

**0** Choice of guide body profile: Stainless versions upon request.

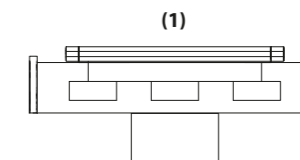
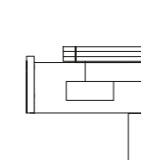


internal profile with cover bands



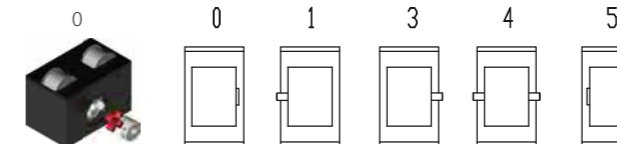
internal profile without cover bands

**0** Choice of carriages:



Size	Version 0		Version 1	
	Q	L	Q	L
120	156	230	156	230
160	280	310	280	310
200	340	380	380	420

**0** Drive version:



5 is as 0, but with coupling claws on both sides. The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 200).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	120	5M 25	130	26
0 7	160	8M 30	192	24
0 9	200	8M 50	256	32

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
120	14 x 35	5x5x28	14
160	18 x 45	6x6x40	19
200	22 x 45	6x6x40	24

**DSZS160 1 0 0 0 0 7 1 1500** Basic length + stroke = total length

Sample ordering code: DSZS160 with internal profile and cover bands, standard carriage, coupling claw on one side, 1190 mm stroke.



# Linear system **DSZS 120 P, 160 P, 200 P**

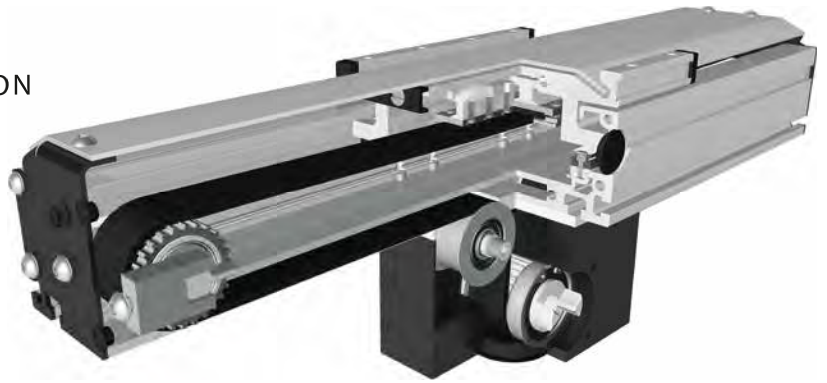
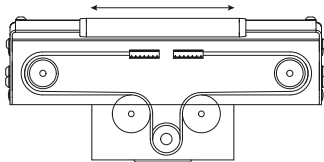
## BELT DRIVE

⊕ INDEPENDENT INSTALLATION POSITION

Ω OMEGA SYSTEM

⊞ LIFTING SYSTEM

👤 COVER PROFILE



### Function:

The guide body consists of a rectangular aluminium profile with two integrated rail guides. The carriage, which is running on four runner blocks, is driven by a revolving timing belt. The novelty is that the timing belt is diverted into a drive block positioned centrally. This results in an extraordinary compactness with regard to the overall length of the system. The driving toothed pulley is provided with a coupling claw as a standard. The belt tension can be easily readjusted via a tensioning device within the bearing block. The openings in the guide body are closed by an aluminium profile, leaving only small slits open on the sides. The cover profile can be adjusted according to the mounting position.

**The advantages compared to the DSZS positioning system are:** The number of components prone to wear such as cover bands and sliding blocks is reduced and the fact that there is no friction makes it possible to use smaller motors. In addition, the cover profile, which is fixed with only a few screws, improves the serviceability and maintainability.

### Fitting position:

As required. Max. length DSZS 120P / 1600mm, DSZS 160P / 1800mm, DSZS 200P / 2000mm

### Carriage mounting:

By tapped holes.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 4 runner blocks which can be serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.

9.1

Forces and torques	Size	120		160		200	
	permitted dyn. Forces*	5000 km	10000 km	5000 km	10000 km	5000 km	10000 km
$F_x$ (N)		894	800	1900	1800	4000	3800
$F_y$ (N)		1776	1405	5570	3900	15600	11080
$F_z$ (N)		2090	1650	7050	5020	20600	14600
$M_x$ (Nm)		81	64	358	255	1285	915
$M_y$ (Nm)		97	77	369	262	1375	980
$M_z$ (Nm)		96	76	364	258	1345	960
<b>All forces and torques related to the following:</b>							
existing values	$\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$						
table values							
<b>No-load torque</b>							
Nm without cover bands		1,2		1,5		2,0	
<b>Speed</b>							
(m/s) max		5		5		5	
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup>		5,61 x 10 <sup>5</sup>		21,32 x 10 <sup>5</sup>		48,07 x 10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		34,19 x 10 <sup>5</sup>		123,36 x 10 <sup>5</sup>		259,99 x 10 <sup>5</sup>	
Elastic modulus N/mm <sup>2</sup>		70.000		70.000		70.000	

For life-time calculation use our homepage.

\* referred to life-time

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

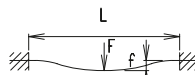
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

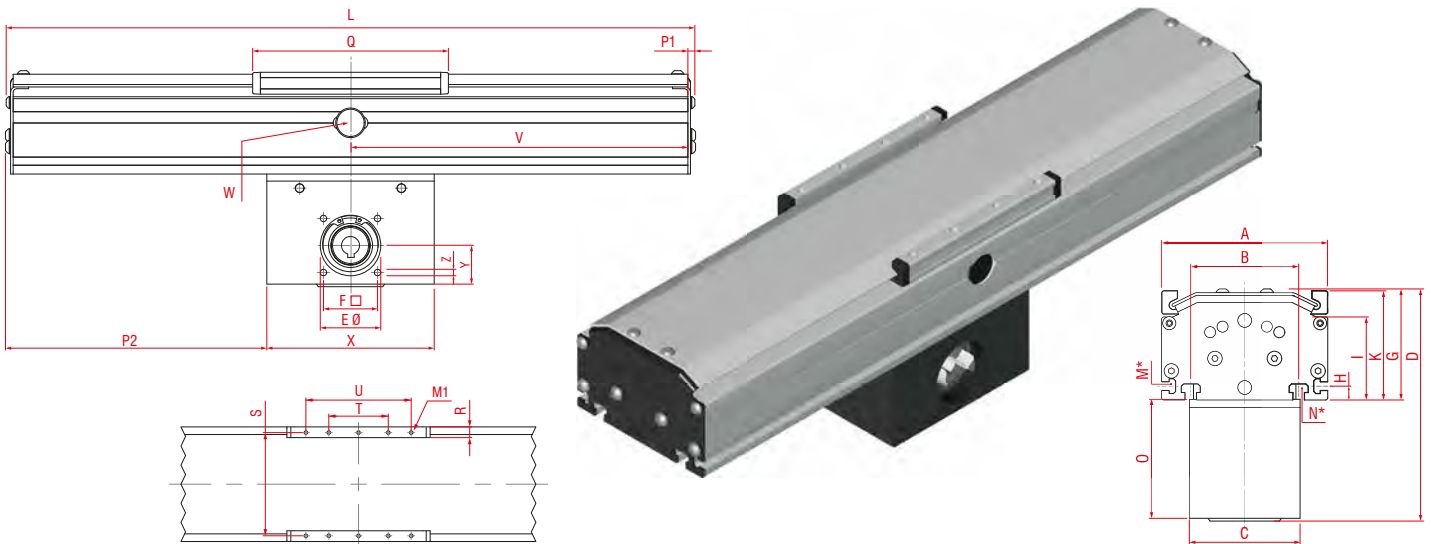
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system DSZS 120 P, 160 P, 200 P

Dimensions (mm)



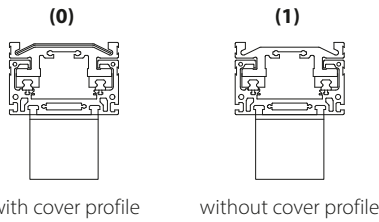
\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size	A	B	C	D	E Ø	F □	G	H	I	K	M for	N for	O	P1	P2	R	S	T	U	X	Y	Z	Basic weight	Weight per 100 mm
DSZS 120 P	120	78	80	169	47	42	80,5	10	60	79	M5	M6	85,5	6	32	11,5	106	40	120	130	30	M6	5,4 kg	0,87 kg
DSZS 160 P	160	90	100	219	68	60	108,5	11	80	106	M6	M8	107	8,25	51,5	15	144	80	160	180	38	M8	13,7 kg	1,55 kg
DSZS 200 P	200	140	130	281	90	80	132,5	15	100	129	M8	M10	146	10	33,5	17	180	100	200	270	60	M10	28,7 kg	2,14 kg

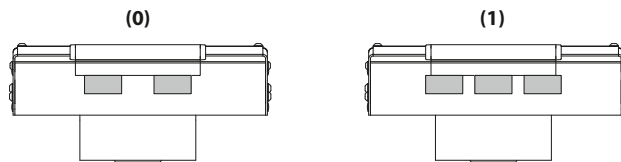
**0 Choice of guide body profile:** Stainless versions upon request.

$V = Q + 100 \text{ mm}$     $W = \text{servicing position}$



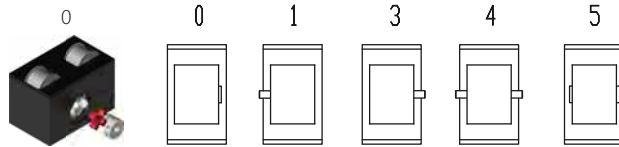
DS 120 M1 = M6 x 8  
only 8 threaded holes in the carriage  
DS 160 M1 = M8 x 12   DS 200 M1 = M10 x 12

**0 Choice of carriages:**



Size	Version 0		Version 1	
	Q	L	Q	L
120	152	192	152	192
160	196	283	228	315
200	248	338	296	386

**0 Drive version:**



5 is as 0, but with coupling claws on both sides.  
The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 200).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	120	5M 25	130	26
0 7	160	8M 30	192	24
0 9	200	8M 50	256	32

**Shaft dimensions / Coupling claw:**

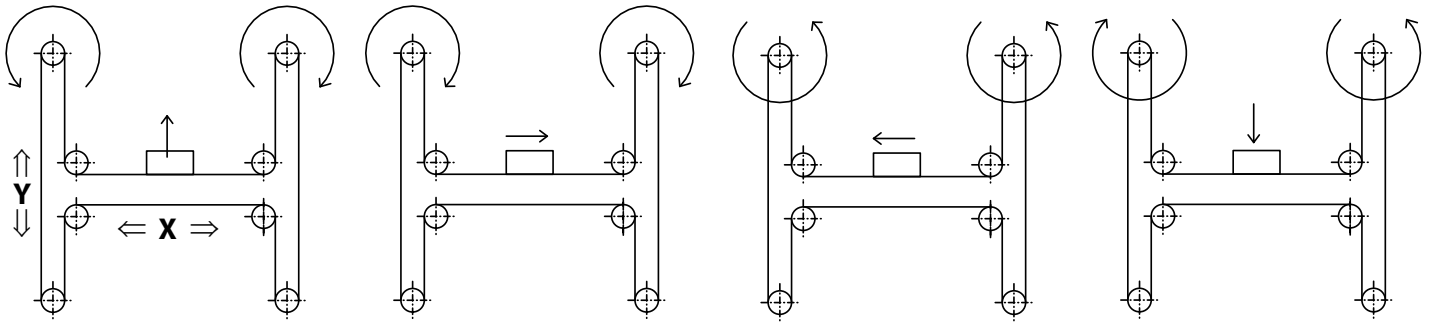
Size	Shaft ø h6 x length	Key	Coupling
120	14 x 35	5 x 5 x 28	14
160	18 x 45	6 x 6 x 40	19
200	22 x 45	6 x 6 x 40	24

**DSZS 120 P 1 0 0 0 0 4 1 1500**   Basic length + stroke = total length  
Pos. 1 2 3 4 5 6 7

Sample ordering code:  
DSZS120 P with cover profile, standard carriage, coupling claw on one side, 1308 mm stroke.

# Linear system **DSZU 120, 160, 200**

## SURFACE PORTAL - STABLE DESIGN - RAIL GUIDE



### Function:

Surface portal with an integrated rail guide, which consists of two Y-axes and one X-axis. Due to the stable rectangular profile, high torques and loads can be absorbed; in addition, very high stability and low deflection are ensured for long axis systems. The drive is provided by a revolving belt, which remains connected by various deflection points. The adjustment is made by two motors. The coordinate is diagonal to the deflection points of the X-axis. Advantage: Only small weights are moved and thus high accelerations are achieved. Very compact design. Can be easily positioned and used with our matching mounting sets in the accessories section.

### Fitting position:

As required. Max. length and width 3.000 mm.

### Carriage mounting:

By T-slots

### Unit mounting:

By T-slots or mounting sets.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability:  $\pm 0,1$  mm.

9.1

Forces/Torques	Size	120		160		200	
	permitted dyn. Forces*	5000 km	10000 km	5000 km	10000 km	5000 km	10000 km
$F_x$ (N)		894	800	1900	1800	4000	3800
$F_y$ (N)		1776	1405	5570	3900	15600	11080
$F_z$ (N)		2090	1650	7050	5020	20600	14600
$M_x$ (Nm)		81	64	358	255	1285	915
$M_y$ (Nm)		97	77	369	262	1375	980
$M_z$ (Nm)		96	76	364	258	1345	960
<b>All forces and torques relate to the following:</b>							
existing values	$\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$						
table values							
<b>No-load torque</b>							
Nm without cover bands		1,2		1,5		2	
<b>Speed</b>							
(m/s) max		5		5		5	
<b>Tensile force</b>							
permanent (N)		900		1900		4000	
0,2 s (N)		1000		2090		4300	
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup>		5,61x10 <sup>5</sup>		21,32x10 <sup>5</sup>		48,07x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		34,19x10 <sup>5</sup>		123,36x10 <sup>5</sup>		259,99x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000		70000	

For life-time calculation use our homepage.

\* referred to life-time

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

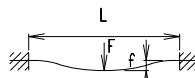
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

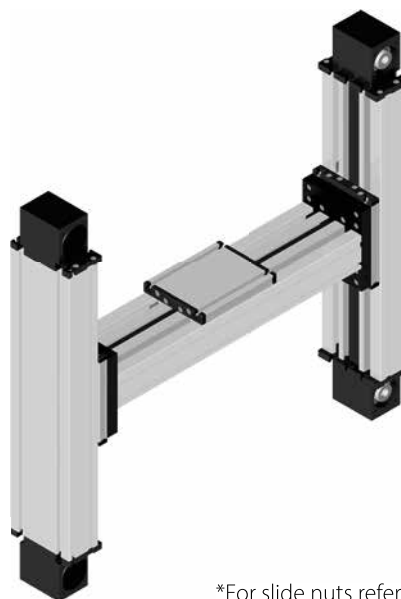
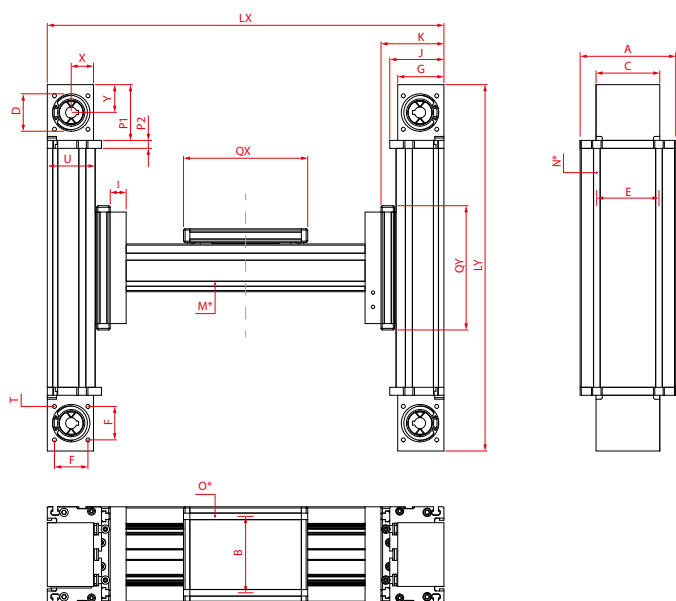
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system DSZU 120, 160, 200

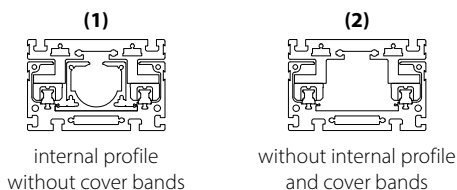
Dimensions (mm)



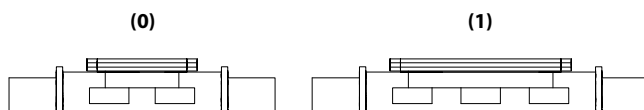
\*For slide nuts refer to chapter 2.2 page 2

Size	Basic length		A	B	C	D -0,05	E	F	G	I	J	K	M for	N for	O for	P1	P2	Qx	Qy	T	U	X	Y	Basic weight	Weight per 100 mm
	Lx	Ly																							
DSZU 120	354	316	120	96	80	47	78	42	58	20	68	79	M5	M6	M6	70	10	156	156	M6	60	28	35	14,42 kg	0,85 kg
DSZU 160	462	414	160	130	100	68	90	60	78	25	90	106	M6	M8	M8	95	12	200	200	M8	80	39	45	34,23 kg	1,69 kg
DSZU 200	648	540	200	160	130	90	140	80	97	50	110	129	M8	M10	M10	110	15	270	290	M10	100	49	50	74,11 kg	2,33 kg

**0 Choice of guide body profile:** Stainless versions upon request.

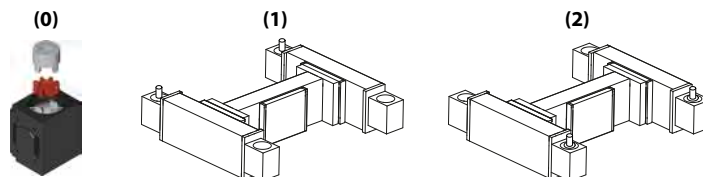


**0 Choice of carriages:**



Size	Version 0				Version 1			
	Qx	Lx	Qy	Ly	Qx	Lx	Qy	Ly
120	156	354	156	316	156	354	156	316
160	200	462	200	414	230	492	230	444
200	270	648	290	540	310	668	310	560

**0 Drive version:**



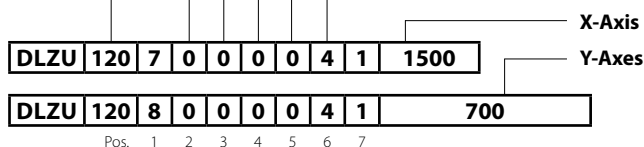
The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings.

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	120	5M25	130	26
0 7	160	8M30	176	22
0 9	200	8M50	224	28

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
120 (5M25)	14 x 35	5x5x28	14
160 (8M30)	18 x 45	6x6x40	19
200 (8M50)	22 x 45	6x6x40	24



For combination kits and connecting elements refer to chapter 2.2

Sample ordering code:

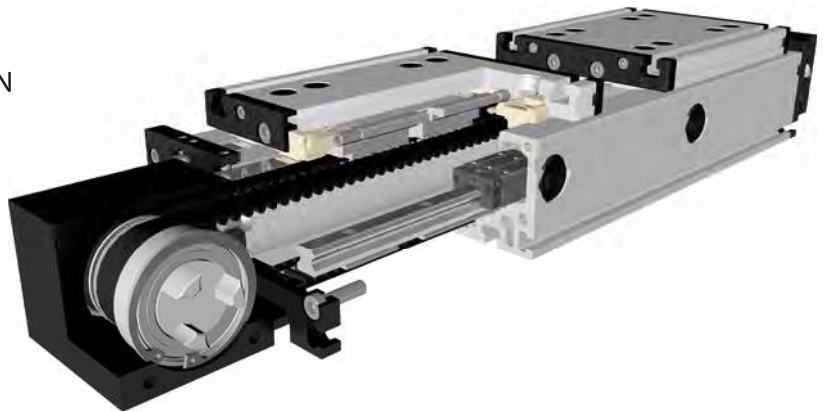
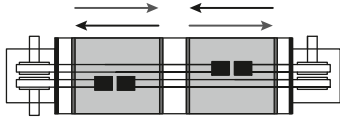
DLZU 120, with standard body profile, standard carriage, coupling claw on one side, stroke X = 1074 / Y = 370 mm

# Linear system **DSZZ 160, 200**

## BELT DRIVE - WITH TWO SEPARATELY DRIVEN CARRIAGES

☑ INDEPENDENT CARRIAGES

☒ HORIZONTAL INSTALLATION POSITION



### Function:

This unit consists of a rectangular aluminium profile with 2 integrated rail guides. The carriage is moved by a belt drive. Each carriage can be moved separately by its own drive. This unit has twin pulleys, which run on separate bearings, and two independent, parallel drive belts, one for each carriage. The openings of the guide body are sealed with 3 stainless steel cover bands to protect the guide from splash water and dust.

### Fitting position:

As required. Max. length 4.000 mm without joints.

### Carriage mounting:

By T-slots

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 4 runner blocks which can be serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.

Forces and torques	Size	160		200	
	permitted dyn. Forces*	5000 km	10000 km	5000 km	10000 km
	$F_x$ (N)	1210	1100	1900	1800
	$F_y$ (N)	5570	3900	15600	11080
	$F_z$ (N)	7050	5020	20600	14600
	$M_x$ (Nm)	358	255	1285	915
	$M_y$ (Nm)	369	262	1375	980
	$M_z$ (Nm)	364	258	1345	960
	<b>All forces and torques related to the following:</b> existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$ table values				
<b>No-load torque</b>					
Nm ohne Abdeckband		1,5		2,0	
Nm mit Abdeckband		2,1		4	
<b>Speed</b>					
(m/s) max		5		5	
<b>Tensile force</b>					
permanent (N)		1210		1900	
0,2 s (N)		1331		2090	
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_x$ mm <sup>4</sup>		21,32x10 <sup>5</sup>		48,07 x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		123,36x10 <sup>5</sup>		259,99 x10 <sup>5</sup>	
Elastic modulus N/mm <sup>2</sup>		70000		70000	

For life-time calculation use our homepage.

\* referred to life-time

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

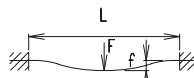
$$P_o = \frac{M_o \cdot n}{9550}$$

$F$  = force (N)  
 $P$  = pulley action perimeter (mm)  
 $S_i$  = safety factor 1,2 ... 2  
 $M_n$  = no-load torque (Nm)  
 $n$  = rpm pulley (min<sup>-1</sup>)  
 $M_o$  = driving torque (Nm)  
 $P_o$  = motor power (KW)

Deflection:

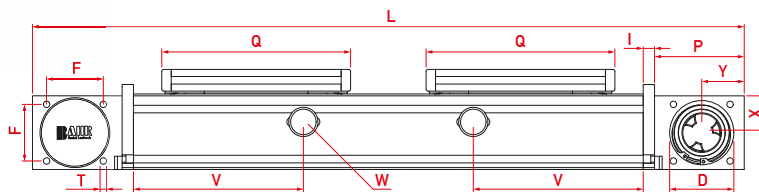
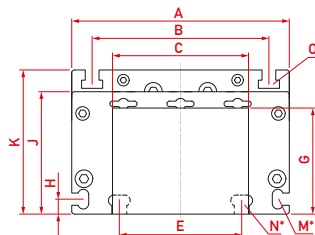
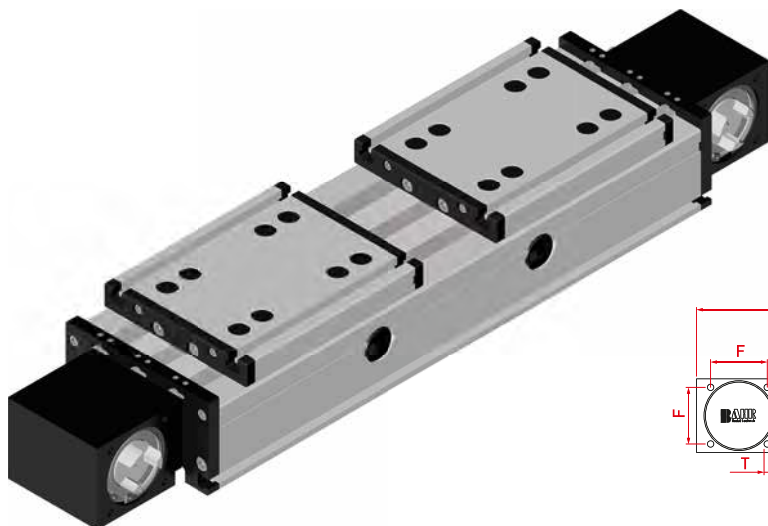
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

$f$  = deflection (mm)  
 $F$  = load (N)  
 $L$  = free length (mm)  
 $E$  = elastic modulus 70000 (N/mm<sup>2</sup>)  
 $I$  = second moment of area (mm<sup>4</sup>)



# Linear system DSZZ 160, 200

Dimensions (mm)



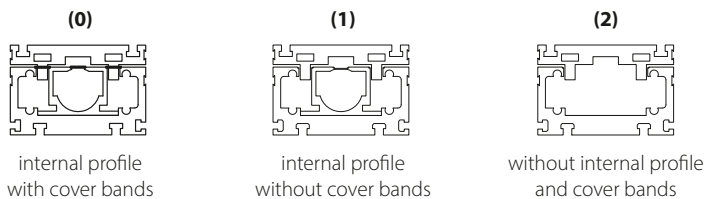
$V = Q + 100 \text{ mm}$      $W = \text{servicing position}$

\*For slide nuts refer to chapter 2.2 page 2

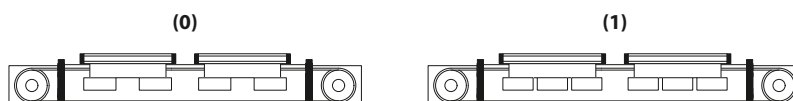
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D	E	F	G	H	I	J	K	M for	N for	O for	P	Q	T	X	Y	Basic weight	Weight per 100 mm
DSZZ 160	625	160	130	121	68	90	60	78	11	12	90	106	M6	M8	M8	95	200	M8	39	45	20,5 kg	1,95 kg
DSZZ 200	800	200	160	150	90	140	80	97	15	15	110	129	M8	M10	M10	110	270	M10	49	50	34,5 kg	2,90 kg

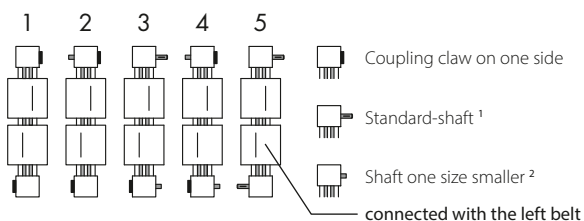
**0 Choice of guide body profile:** Stainless versions upon request.



**0 Choice of carriages:**



**0 Drive version:**



Size	Version 0		Version 1	
	Q	L	Q	L
160	200	625	230	685
200	270	800	310	880

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 6	160	8M 20	176	22
0 7	200	8M 30	224	28

**Shaft dimensions / Coupling:**

Size	Shaft $\phi$ h6 x length	Key	Coupling
DSZZ 160 <sup>1</sup>	$\phi$ 18 x 45	6x6x35	19
DSZZ 160 <sup>2</sup>	$\phi$ 14 x 35	5x5x28	19
DSZZ 200 <sup>1</sup>	$\phi$ 22 x 45	6x6x40	24
DSZZ 200 <sup>2</sup>	$\phi$ 18 x 45	6x6x40	24

DSZZ 200 4 0 0 2 0 7 1 1500 — Basic length + stroke = total length






Pos. 1 2 3 4 5 6 7

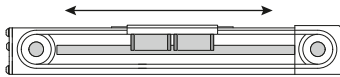
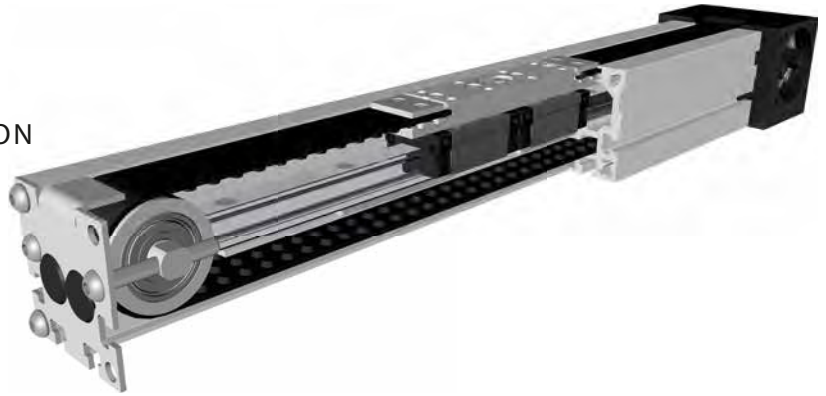
Sample ordering code:

DSZZ 200 with internal profile and cover bands, carriage version 0, drive version 2, 700 mm stroke.

# Linear system **LSN 60, 80**

## NUBBED BELT DRIVE

-  LOW OPERATING VOLUME
-  INDEPENDENT INSTALLATION POSITION
-  NUBBED BELT
-  LOW-VIBRATION RUN
-  FOR 3D PRINTING APPLICATIONS



### Function:

The guide body consists of an aluminium square profile with an integrated rail guide. The carriage is moved by a revolving interior nubbled belt. The advantage of this system: The belt is guided within the profile, so that the system is independent of the mounting position. The nubbled belt is self-tracking and has a very low operating noise level thanks to its nobs being offset by 45°. Furthermore, it is almost vibration-free in the transition sections. At the front face there is a timing belt deflection unit containing a toothed pulley with two coupling claws in the standard version. On the opposite side there is a bearing piece plate containing a tensioning device for the timing belt.

### Mounting position:

Variable, max. one-piece-length: 6.000 mm.

### Carriage connection:

By threaded holes.

### Fixation:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Timing belt:

N10 with reinforcing steel mesh, no backlash when changing direction, repeatability ± 0.1 mm.

### Carriage support:

In the standard version the carriage is positioned on two runner blocks which can be readjusted and maintained at each central servicing position. Two grease nipples at the carriage enable relubrication of the positioning system.

12.1

Forces and torques	Size	60		80	
	permitted dyn. Forces*	5000 km	10000 km	5000 km	10000 km
$F_x$ (N)		1170	1040	1900	1800
$F_y$ (N)		1410	990	3570	2550
$F_z$ (N)		3520	2500	8500	6050
$M_x$ (Nm)		33	23	107	75
$M_y$ (Nm)		104	73	310	222
$M_z$ (Nm)		100	70	296	210
<b>All forces and torques related to the following:</b>					
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$					
table values					
<b>No-load torque</b>					
Nm		0,6		1,0	
<b>Speed</b>					
(m/s) max		5		5	
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_x$ mm <sup>4</sup>		4,37x10 <sup>5</sup>		14,6x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		5,78x10 <sup>5</sup>		17,1x10 <sup>5</sup>	
E-Modul N N/mm <sup>2</sup>		70000		70000	

For life-time calculation use our homepage.

\* referred to life-time

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

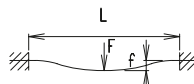
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1, 2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

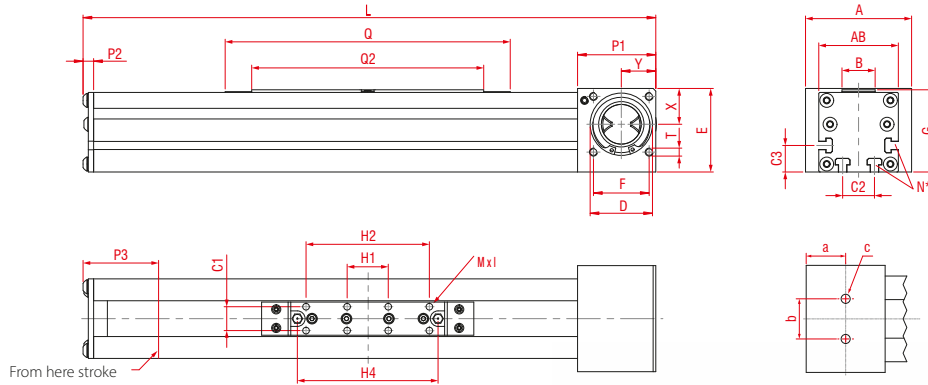
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)

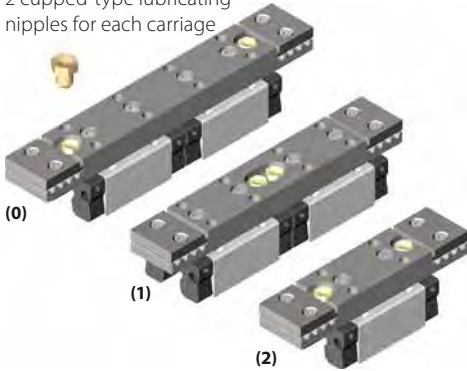


# Linear system LSN 60, 80

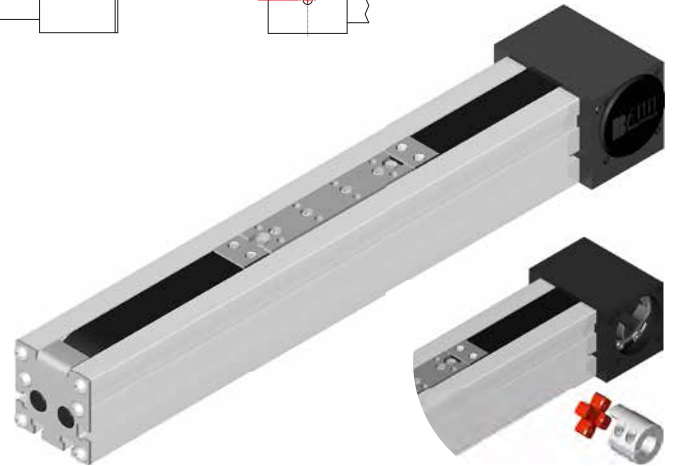
Dimensions (mm)



2 cupped-type lubricating nipples for each carriage



Hose connections available on request.



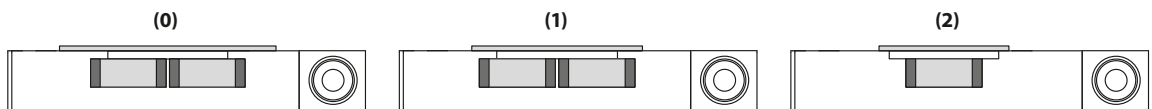
\*For slide nuts refer to chapter 2.2 page 2

Size □	A	AB □	B	C1	C2	C3	D -0,05	E	F □	G	MxI	N for	P1	P2	P3	T	X	Y	a	b	c	Weight per 100 mm
LSN 60	80	60	25	18	24	20	47	63	42	62,5	M6x10	M5	59	6	55	M6	27	26	29,5	30	M8	0,53 kg
LSN 80	100	80	25	18	30	22	68	93	60	83	M6x12	M6	90	8	73	M8	45	40	47,5	40	M10	0,87 kg

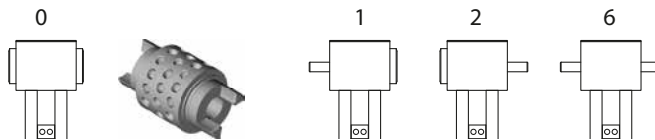
**0** Choice of guide body profile:  
(0) Standard (1) corrosion-protected screws

Carriage		L	Q	Q2	H1	H2	H4	Basic weight system
LS 60	Version (0)	274	160	116	31	93	106	3,06 kg
	Version (1)	254	140	96	32	84	10	2,62 kg
	Version (2)	214	100	56	31	--	48	2,07 kg
LS 80	Version (0)	382	219	149	40	120	133	7,69 kg
	Version (1)	367	204	134	40	120	12,5	7,41 kg
	Version (2)	310	147	77	40	--	60,5	6,39 kg

**0** Choice of carriages:



**0** Drive version:



**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 8	60	Nubbed belt N10	130	13
0 8	80	Nubbed belt N10	176	18

**Shaft dimensions / Coupling claw:**

Size	Shaft Ø h6 x length	Feather key	Coupling
60	14 x 35	5x5x28	14
80	18 x 45	6x6x40	19

**LSN 60 1 0 0 0 0 8 1 1500** — Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

LSN60, standard body profile, standard carriage, nubbed belt, double-sided coupling claw, 1226 mm stroke




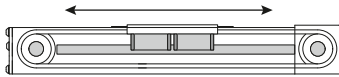
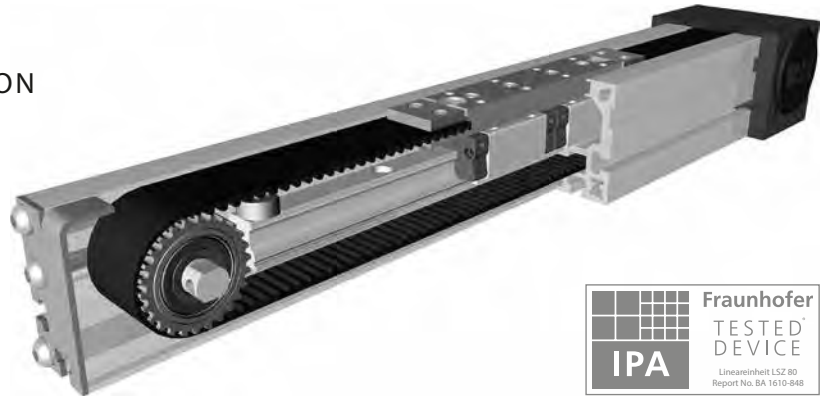
# Linear system **LSZ 60, 80, 100**

## BELT DRIVE

 INDEPENDENT INSTALLATION POSITION

 LONG TRAVERSE PATH > 6000 MM

 HIGH TORQUE ABSORPTION



**Function:**

The guide body consists of an aluminium square profile with an integrated rail guide. The carriage is moved by means of a revolving interior timing belt. At the front face there is a timing belt deflection unit with integrated coupling claws integrated on two sides. The opposite front face is provided with a plate containing a tensioning device for the timing belt. With this series, multi-part assembled units with long strokes can be realized.

**Mounting position:**

Variable, max. one-piece-length: 6.000 mm.

**Carriage connection:**

By threaded holes.

**Fixation:**

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

**Timing belt:**

HTD with reinforcing steel mesh, no backlash when changing direction, repeatability ± 0.1 mm.

**Carriage support:**

In the standard version the carriage is positioned on two runner blocks which can be readjusted and maintained at each central servicing position. Two grease nipples at the carriage enable relubrication of the positioning system.

12.1

Forces and torques	Size	60		80		100	
	permitted dyn. Forces*	5000 km	10000 km	5000 km	10000 km	5000 km	10000 km
$F_x$ (N)		1073	960	1900	1800	4000	3800
$F_y$ (N)		1410	990	3570	2550	4080	2900
$F_z$ (N)		3520	2500	8500	6050	10300	7270
$M_x$ (Nm)		33	23	107	75	142	101
$M_y$ (Nm)		104	73	310	222	439	311
$M_z$ (Nm)		100	70	296	210	412	292
<b>All forces and torques related to the following:</b>							
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
<b>No-load torque</b>							
Nm		0,6		1,0		1,8	
<b>Speed</b>							
(m/s) max		5		5		5	
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup>		4,37x10 <sup>5</sup>		14,6x10 <sup>5</sup>		35,51x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		5,78x10 <sup>5</sup>		17,1x10 <sup>5</sup>		46,41x10 <sup>5</sup>	
Elastic modulus N/mm <sup>2</sup>		70000		70000		70000	

For life-time calculation use our homepage.

\* referred to life-time

Driving torque:

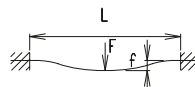
$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

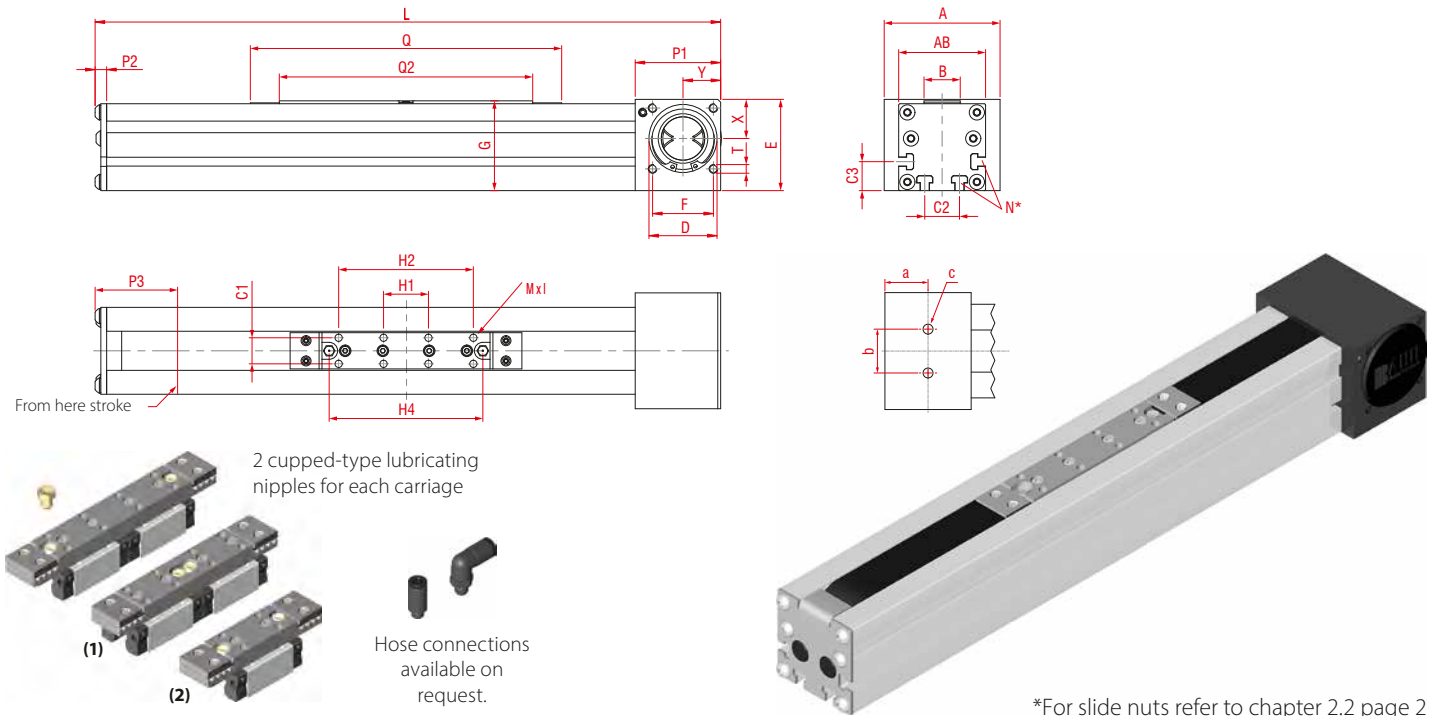
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$



- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)

# Linear system **LSZ 60, 80, 100**

Dimensions (mm)



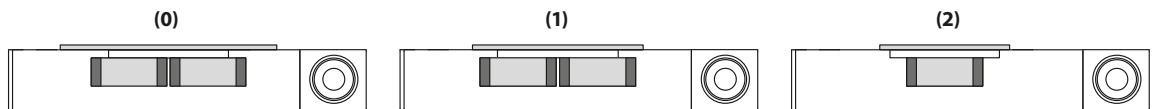
\*For slide nuts refer to chapter 2.2 page 2

Size □	A	AB □	B	C1	C2	C3	D -0,05	E	F □	G	MxI	N for	P1	P2	P3	T	X	Y	a	b	c	Weight per 100 mm
<b>LSZ 60</b>	80	60	25	18	24	20	47	63	42	62,5	M6x10	M5	59	6	55	M6	27	26	29,5	30	M8	0,53 kg
<b>LSZ 80</b>	100	80	25	18	30	22	68	93	60	83	M6x12	M6	90	8	73	M8	45	40	47,5	40	M10	0,87 kg
<b>LSZ 100</b>	130	100	42	30	40	30	90	110	80	103	M8x12	M8	110	11	109	M10	49,4	50	55	50	M12	1,35 kg

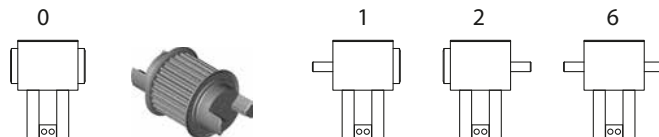
- 0 Choice of guide body profile:**  
**(0)** Standard **(1)** corrosion-protected screws  
**(4)** expanded corrosion-protected version (depending on the availability of components)

Carriage		L	Q	Q2	H1	H2	H4	Basic weight System
<b>LS 60</b>	Version (0)	274	160	116	31	93	106	3,06 kg
	Version (1)	254	140	96	32	84	10	2,62 kg
	Version (2)	214	100	56	31	--	48	2,07 kg
<b>LS 80</b>	Version (0)	382	219	149	40	120	133	7,69 kg
	Version (1)	367	204	134	40	120	12,5	7,41 kg
	Version (2)	310	147	77	40	--	60,5	6,39 kg
<b>LS 100</b>	Version (0)	470	251	180	33	99	172	12,43 kg
	Version (1)	455	235	164	83	149	18	12,20 kg
	Version (2)	370	151	80	66	--	69	10,43 kg

- 0 Choice of carriages:**



- 0 Drive version:**



**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
<b>0 3</b>	<b>60</b>	5M 30	130	26
<b>0 4</b>	<b>80</b>	8M 30	176	22
<b>0 7</b>	<b>100</b>	8M 50	224	28

**Shaft dimensions / Coupling claw:**

Size	Shaft Ø h6 x length	Feather key	Coupling
<b>60</b>	14 x 35	5x5x28	14
<b>80</b>	18 x 45	6x6x40	19
<b>100</b>	22 x 45	6x6x40	24

**LSZ 60 1 0 0 0 0 3 1 1500** — Basic length + stroke = total length  
 Pos. 1 2 3 4 5 6 7

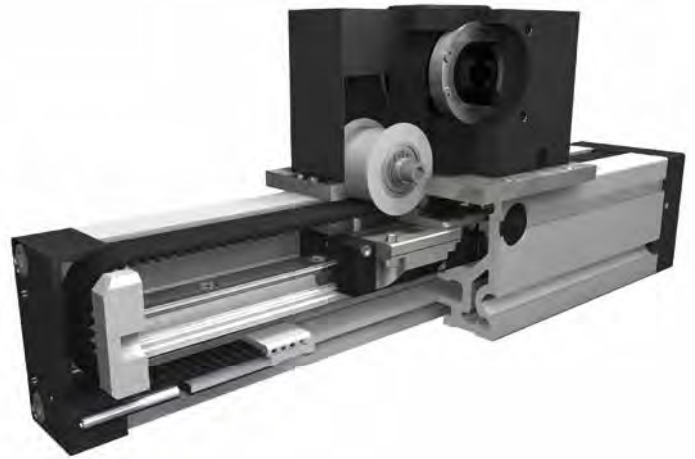
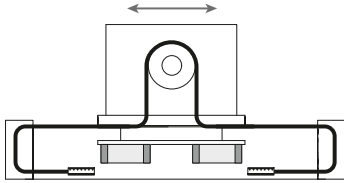
Sample ordering code:  
 LSZ60, standard body profile, standard carriage, double-sided coupling claw, 1226 mm stroke

# Linear system **QSSZ 60, 80**

## BELT DRIVE

Ω OMEGA SYSTEM

CLEAN ROOM



### Function:

This linear unit consists of a square aluminium profile with integrated rail guidance. The carriage, which has runner blocks, is driven by a timing belt. Each standard pulley includes a coupling claw on one side and is equipped with maintenance-free ball bearings. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel.

### Fitting position:

As required. Max. length 3.000 mm without joints.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt performance:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 2 runner blocks which can be serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.

7.1

Forces and torques	Size	60		80	
	permitted dyn. forces*	5000 km	10000 km	5000 km	10000 km
	$F_x$ (N)	97	87	223	200
	$F_y$ (N)	350	240	890	630
	$F_z$ (N)	880	625	2100	1500
	$M_x$ (Nm)	8	6	26	18
	$M_y$ (Nm)	26	18	77	55
	$M_z$ (Nm)	25	17	74	52
	<b>All forces and torques related to the following:</b> existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$ table values				
<b>No-load torque</b>					
Nm	1,0		1,4		
<b>Speed</b>					
(m/s) max	3		3		
<b>Tensile force</b>					
permanent (N)	Lifetime calculation see the internet				
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_y$ mm <sup>4</sup>	4,3x10 <sup>5</sup>		14,3x10 <sup>5</sup>		
$I_z$ mm <sup>4</sup>	5,8x10 <sup>5</sup>		18,7x10 <sup>5</sup>		
Elastic modulus N/mm <sup>2</sup>	70000		70000		

For life-time calculation use our homepage.

\* referred to life-time

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

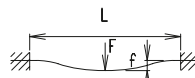
$$P_o = \frac{M_o \cdot n}{9550}$$

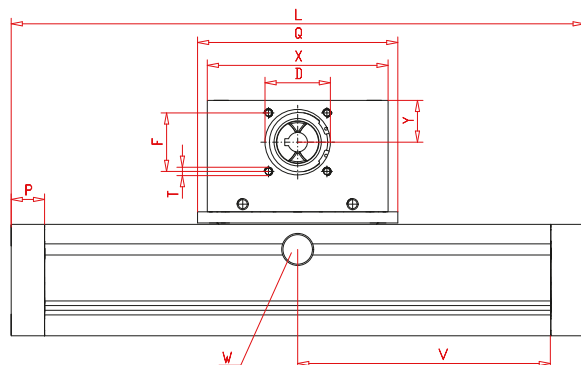
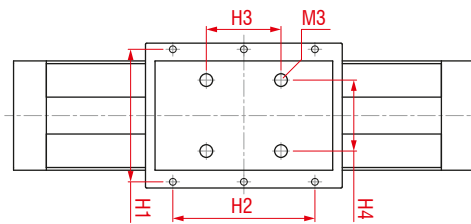
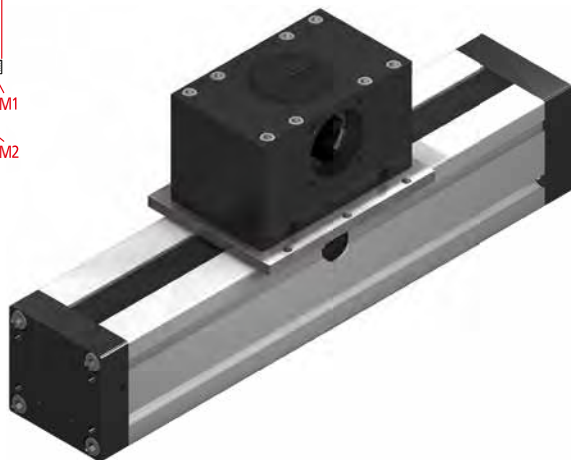
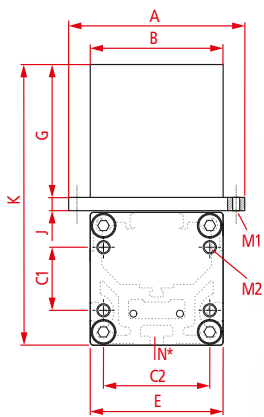
$F$  = force (N)  
 $P$  = pulley action perimeter (mm)  
 $S_i$  = safety factor 1,2 ... 2  
 $M_n$  = no-load torque (Nm)  
 $n$  = rpm pulley (min<sup>-1</sup>)  
 $M_o$  = driving torque (Nm)  
 $P_o$  = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

$f$  = deflection (mm)  
 $F$  = load (N)  
 $L$  = free length (mm)  
 $E$  = elastic modulus 70000 (N/mm<sup>2</sup>)  
 $I$  = second moment of area (mm<sup>4</sup>)





V = Q + 100 mm  
W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

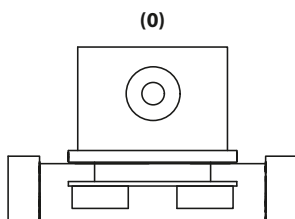
Size	Basic length L	A	B	C1	C2	D -0,05	E	F	G	J	K	N for	P	Q	T	X	Y	Basic weight	Weight per 100 mm
QSSZ 60	168	60	60	28	48	37	60	32	65	7,50	134,5	M 5	20	124	M 5	110	20	3,30 kg	0,47 kg
QSSZ 80	200	106	80	38	62	47	80	42	80	8	169	M 6	24	144	M 6	130	30	5,90 kg	1,02 kg

7.1

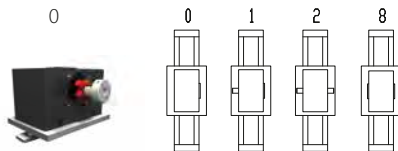
- 0** Choice of guide body profile:  
 (0) Standard (1) corrosion-protected screws  
 (4) expanded corrosion-protected version  
 (depending on the availability of components)

Size	H1	H2	H3	H4	M1	M2	M3
QSSZ 60	---	---	60	45	---	M6	M8
QSSZ 80	97	104	---	---	M6	M8	---

- 0** Choice of carriages:



- 0** Drive version:



Size	Shaft ø h6 x length	Key
60	10 x 27	3x3x25
80	14 x 35	5x5x28

8 is as 0, but with coupling claws on both sides. The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings.

**Belt table / Coupling claw:**

Code No.	Size	Belt	Pulley		Coupling
			mm/rev.	Number of teeth	
0 3	60	5M15	100	20	9
0 7	80	5M25	130	26	14

**QSSZ 80 1 0 0 0 0 7 1 1500** — Basic length + stroke = total length




Pos. 1 2 3 4 5 6 7

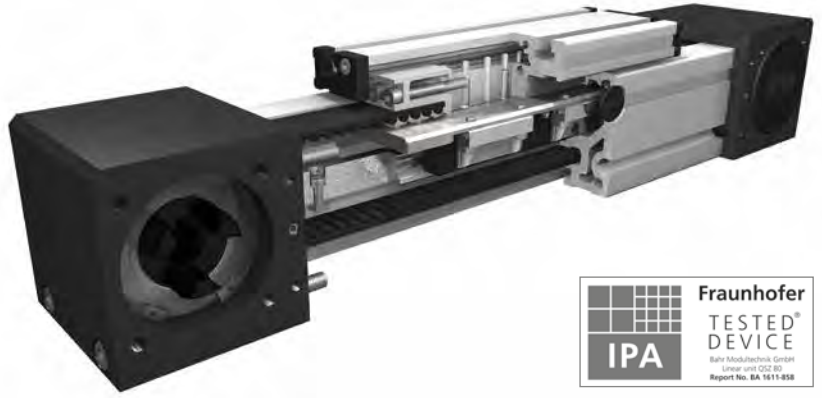
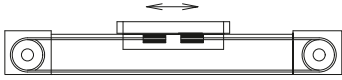
Sample ordering code:  
 QSSZ80, standard body profile, standard carriage, coupling claw on one side, 1300 mm stroke

For additional accessories refer to chapter 2.2

# Linear system **QSZ 60, 80, 100, 125**

## BELT DRIVE

-  **HIGH LOAD CAPACITY**
-  **LONG TRAVERSE PATH > 6000 MM**
-  **CLEAN ROOM**



### Function:

This unit consists of a square aluminium profile with an integrated ball rail. The carriage is moved by a belt drive. Each standard pulley includes one coupling claw on one side. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. This linear unit is suitable for application in clean rooms of clean-room classification 1.000 (corresponding to US Fed. Standard 209 E). With this series, multi-part assembled units with long strokes can be realized.

### Fitting position:

As required. Max. length 6.000 mm without joints.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt performance:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on two runner blocks which can be adjusted and serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.

7.1

Forces and torques	Size	60		80		100		125	
	permitted dyn. forces*	5000 km	10000 km	5000 km	10000 km	5000 km	10000 km	5000 km	10000 km
$F_x$ (N)		894	800	1900	1800	4000	3800	5900	5750
$F_y$ (N)		1410	990	3570	2550	4080	2900	6892	5470
$F_z$ (N)		3520	2500	8500	6050	10300	7270	17205	13659
$M_x$ (Nm)		33	23	107	75	142	101	288	228
$M_y$ (Nm)		104	73	310	222	439	311	1110	881
$M_z$ (Nm)		100	70	296	210	412	292	1012	803
<b>All forces and torques related to the following:</b>									
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$									
table values									
<b>No-load torque</b>									
Nm		1,0		1,4		1,8			
<b>Speed</b>									
(m/s) max		5		5		5		5	
<b>Tensile force</b>									
permanent (N)		900		1900		4000		5900	
0,2 s (N)		1000		2090		4300		6350	
<b>Geometrical moments of inertia of aluminium profile</b>									
$I_x$ mm <sup>4</sup>		4,3x10 <sup>5</sup>		14,3x10 <sup>5</sup>		31,8x10 <sup>5</sup>		74,9x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		5,8x10 <sup>5</sup>		18,7x10 <sup>5</sup>		46,5x10 <sup>5</sup>		106,5x10 <sup>5</sup>	
Elastic modulus N/mm <sup>2</sup>		70000		70000		70000		70000	

For life-time calculation use our homepage.

\* referred to lifetime

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

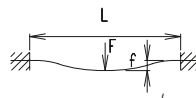
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

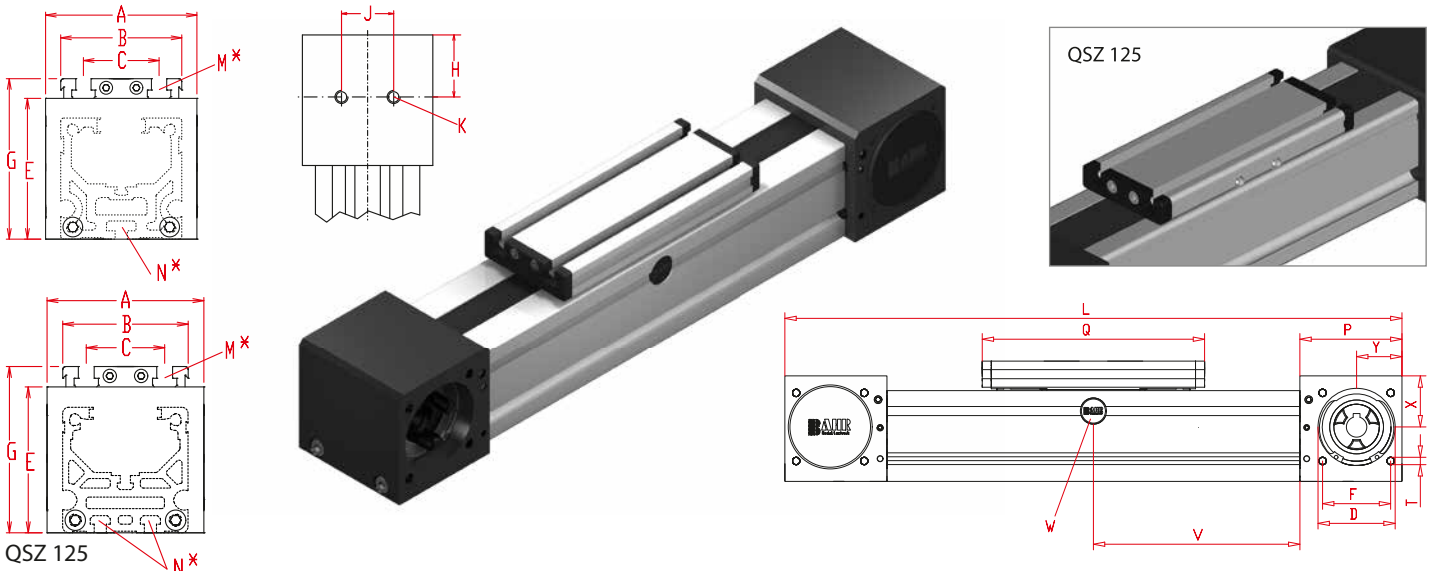
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system QSZ 60, 80, 100, 125

Dimensions (mm)



\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	N for	M for	P	Q	T	X	Y	Basic weight	Weight per 100 mm
QSZ 60	300	80	60	36	47	63	42	79	29,5	30	M 8	M 5	M 6	59	177	M 6	27	26	3,5 kg	0,55 kg
QSZ 80	430	100	80	50	68	93	60	106	47,5	40	M 10	M 6	M 8	90	232	M 8	45	40	10,4 kg	0,96 kg
QSZ 100	510	130	100	66	90	110	80	129	55	50	M 12	M 10	M 10	110	268	M 10	49	50	15,9 kg	1,47 kg
QSZ 125	570	160	125	82	110	134,5	100	157,5	65	60	M 12	M 10	M 12	130	300	M 10	60	60	30,5 kg	2,21 kg

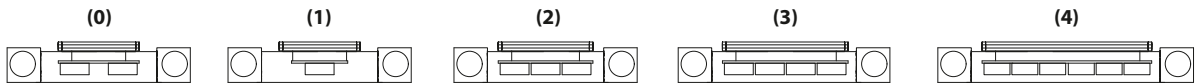
V = Q + 100 mm

W = servicing position

**0 Choice of guide body profile:**

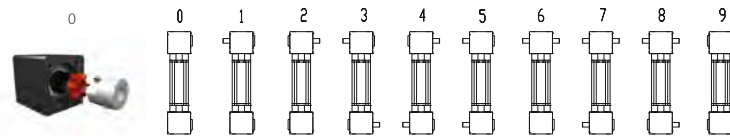
- (0) Standard (1) corrosion-protected screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 0		Version 1		Version 2		Version 3		Version 4	
	Q	L	Q	L	Q	L	Q	L	Q	L
60	177	300	152	280	242	370	302	430		
80	232	430	196	390	312	510	390	585		
100	268	510	260	500	362	610	448	690	628	860
125	300	570	260	530	365	635	467	740		

**0 Drive version:**



Size	Shaft ø h6 x length	Key
60	14 x 35	5x5x28
80	18 x 45	6x6x40
100	22 x 45	6x6x40
125	30 x 55	8x7x50

9 is as 0, but with coupling claws on both sides. The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or clamping sets (Size 100 + 125).

**Belt table / Coupling claw:**

Code No.	Size	Belt	Pulley		Coupling
			mm/rev.	Number of teeth	
0 3	60	5M25	130	26	14
0 4	80	8M30	176	22	19
0 7	100	8M50	224	28	24
0 9	125	8M70	288	36	28

**QSZ 80 1 0 0 0 0 4 1 1500** — Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

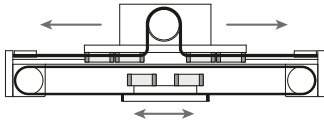
QSZ80 with standard body profile, standard carriage, coupling claw on one side, 1070 mm stroke

For additional accessories refer to chapter 2.2

# Linear system **QSZT 80, 100**

## BELT DRIVE

-  HORIZONTAL TELESCOPIC SYSTEM
-  HIGH RIGIDITY

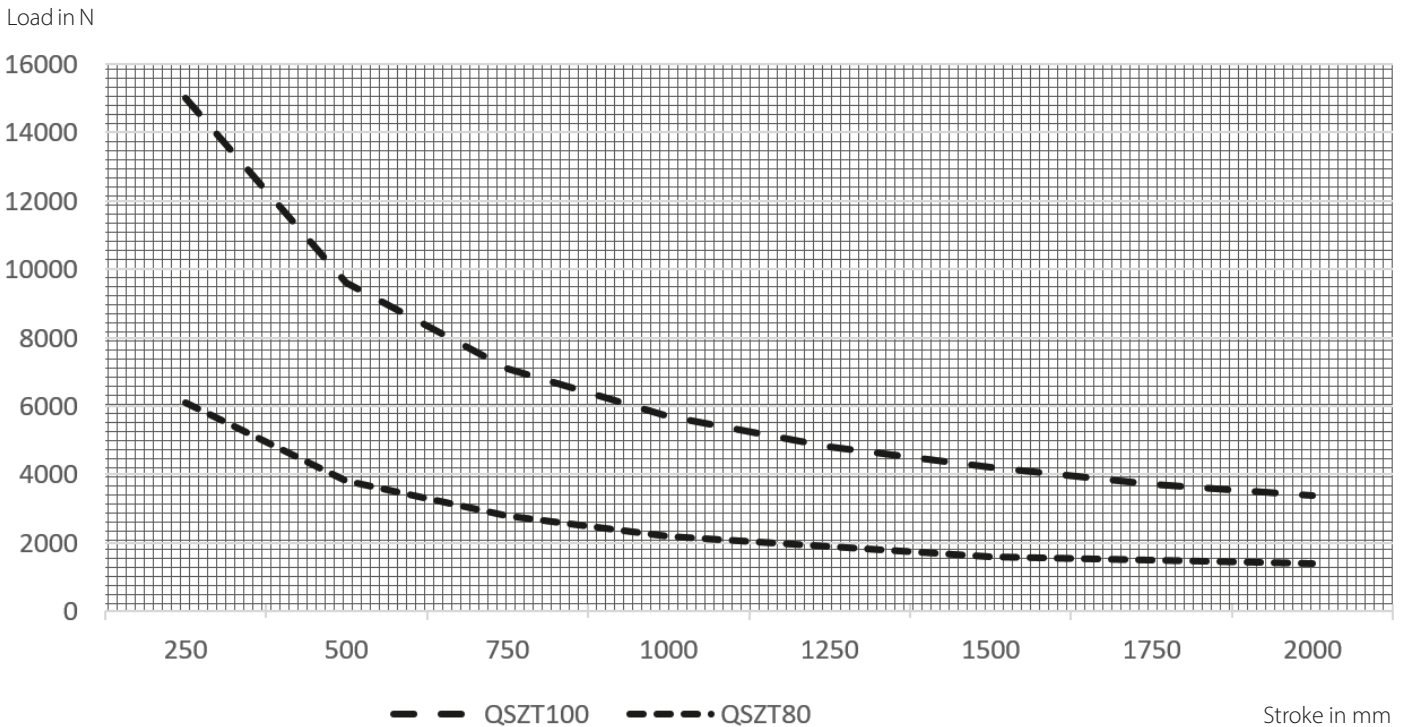


**Function:**

Linear unit consisting of two parallel QSZ axes. The carriage, which is connected to the runner blocks, is moved by means of a toothed belt. The belt tension can be easily readjusted via a tensioning device within the carriage. This device also helps to adjust the symmetry of the carriages. The system is driven by a central toothed belt with Omega deflection, and the special connection of the toothed belts results in a telescopic movement. The toothed pulley is equipped with maintenance-free ball bearings. The belt tension can be easily readjusted via a tensioning device on the bottom side. This linear system is designed for high loads.

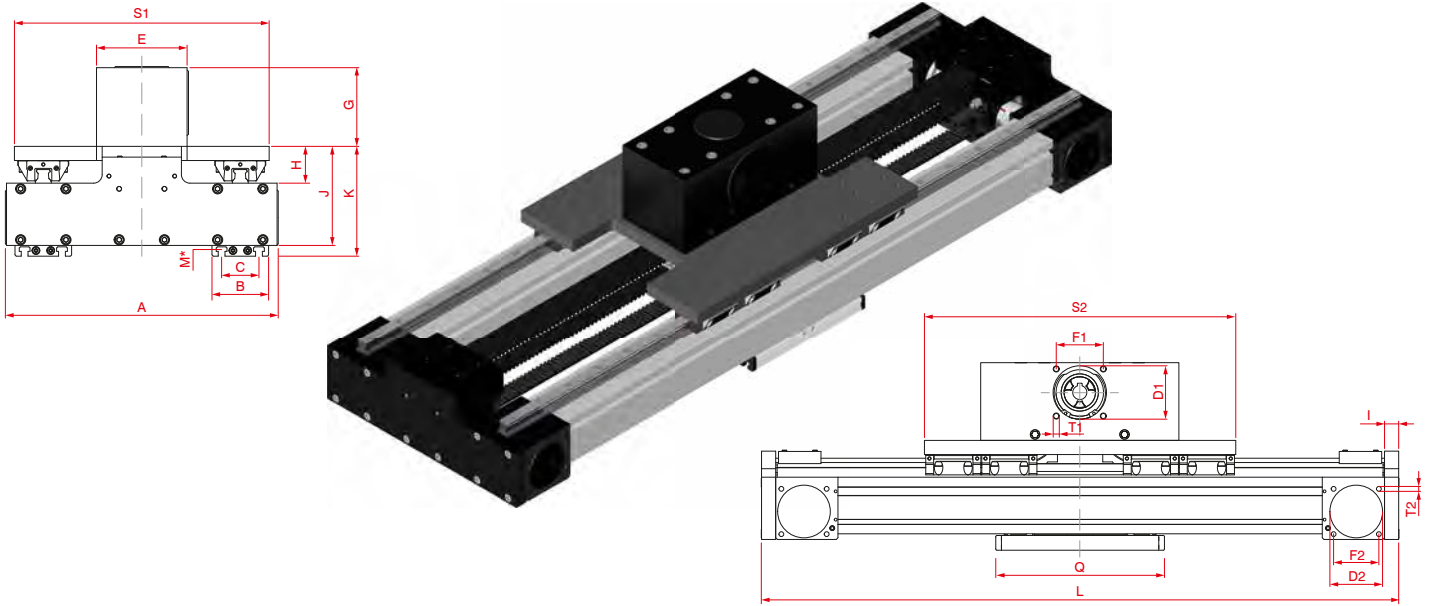
7.1

- Fitting position:** Preferably horizontal, Max. length 3.000 mm without joints.
- Carriage mounting:** By T-slots.
- Unit mounting:** By mounting sets.
- Belt performance:** HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.
- Carriage support:** In the standard version, the carriage runs on voer runner blocks which can be adjusted and serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.



# Linear system **QSZT 80, 100**

Dimensions (mm)



$V = Q + 100 \text{ mm}$       $W = \text{servicing position}$

\*For slide nuts refer to chapter 2.2 page 2

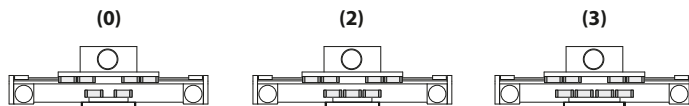
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D1	D2	E	F1	F2	G	H	I	J	K	M for	P	Q	S1	S2	T1	T2	Basic weight	Weight per 100 mm
QSZT 80	500	388	80	50	90	68	130	80	60	130	54,5	20	147,5	160,5	M8	90	262	364	450	M10	M8	56 kg	2,4 kg
QSZT 100	600	478	100	66	110	90	160	100	80	139	65	25	175	194	M10	110	298	450	550	M10	M10	96 kg	4,1 kg

7.1

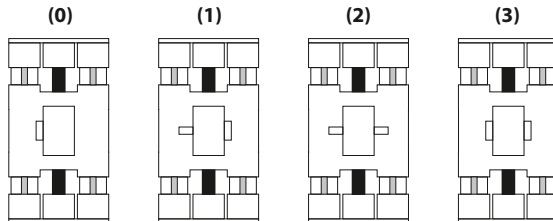
- 0 Choice of guide body profile:**  
 (0) Standard (1) corrosion-protected screws  
 (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 2		Version 3	
	Q	L	Q	L
80	356	580	504	730
100	392	700	508	790

**0 Drive version:**



Size	Shaft $\phi h6 \times \text{length}$	Key
80	22 x 45	6x6x40
100	30 x 55	8x7x40

Version 3 is the same as 0, but with double sided coupling claw.

**Belt table / Coupling claw:**

Code No.	Size	Belt	Pulley		Coupling
			mm/rev.	Number of teeth	
0 4	80	8M 30/50	256	32	24
0 7	100	8M 50/70	304	38	28

**QSZT 80 4 0 0 2 0 7 1 1500** — Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

QSZT 80 with standard body profile, carriage version 0, drive version 1, 1000 mm stroke



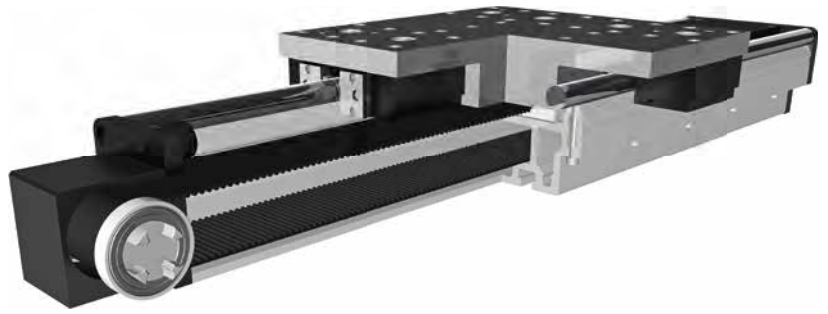
# Linear system **ALLZ 203, 204**

## BELT DRIVE

 ROLLER GUIDE

 HEAVY LOAD

 HIGH LOAD CAPACITY



### Function:

This unit consists of an aluminium profile with hardened steel guide rods mounted on top of the profile. The carriage, which has internal linear ball bearings that can be adjusted free of play, is driven along the guide rods by a timing belt. The pulleys have maintenance-free ball bearings. Opposite the driven side there is an integrated timing-belt tensioner which can be readjusted by 2 screws.

### Fitting position:

As required. Max. length 5.000 mm without joints.

### Carriage mounting:

By tapped holes.

### Unit mounting:

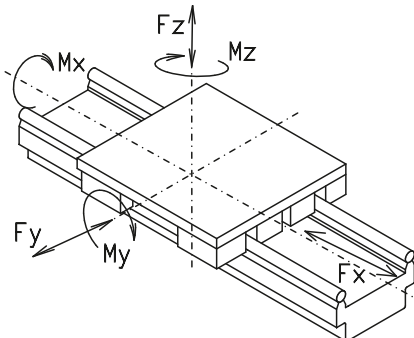
By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Carriage support:

In the standard version, the carriage runs on 8 rollers which can be adjusted and serviced at a central servicing position. For longer carriages the number of rollers can be increased. Repeatability  $\pm 0,1$ .

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability:  $\pm 0,1$  mm.

Forces and torques	Size	ALLZ 203		ALLZ 204	
	Forces/Torques	static	dynamic	static	dynamic
	$F_x$ (N)	-	5610	-	5610
	$F_y$ (N)	23000	18400	30000	24000
	$F_z$ (N)	11000	8800	16200	13000
	$M_x$ (Nm)	1180	950	1870	1500
	$M_y$ (Nm)	1870	1500	3000	2400
	$M_z$ (Nm)	3800	3100	5600	4500
	<b>All forces and torques related to the following:</b> existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$ table values				
<b>No-load torque</b>					
Nm	4		4		
<b>Speed</b>					
(m/s) max	8		8		
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_x$ mm <sup>4</sup>	2,26 x 10 <sup>7</sup>		2,98 x 10 <sup>7</sup>		
$I_y$ mm <sup>4</sup>	8,75 x 10 <sup>7</sup>		10,22 x 10 <sup>7</sup>		
Elastic modulus N/mm <sup>2</sup>	70000		70000		

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

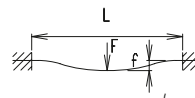
$$P_o = \frac{M_o \cdot n}{9550}$$

$F$  = force (N)  
 $P$  = pulley action perimeter (mm)  
 $S_i$  = safety factor 1,2 ... 2  
 $M_n$  = no-load torque (Nm)  
 $n$  = rpm pulley (min<sup>-1</sup>)  
 $M_o$  = driving torque (Nm)  
 $P_o$  = motor power (KW)

Deflection:

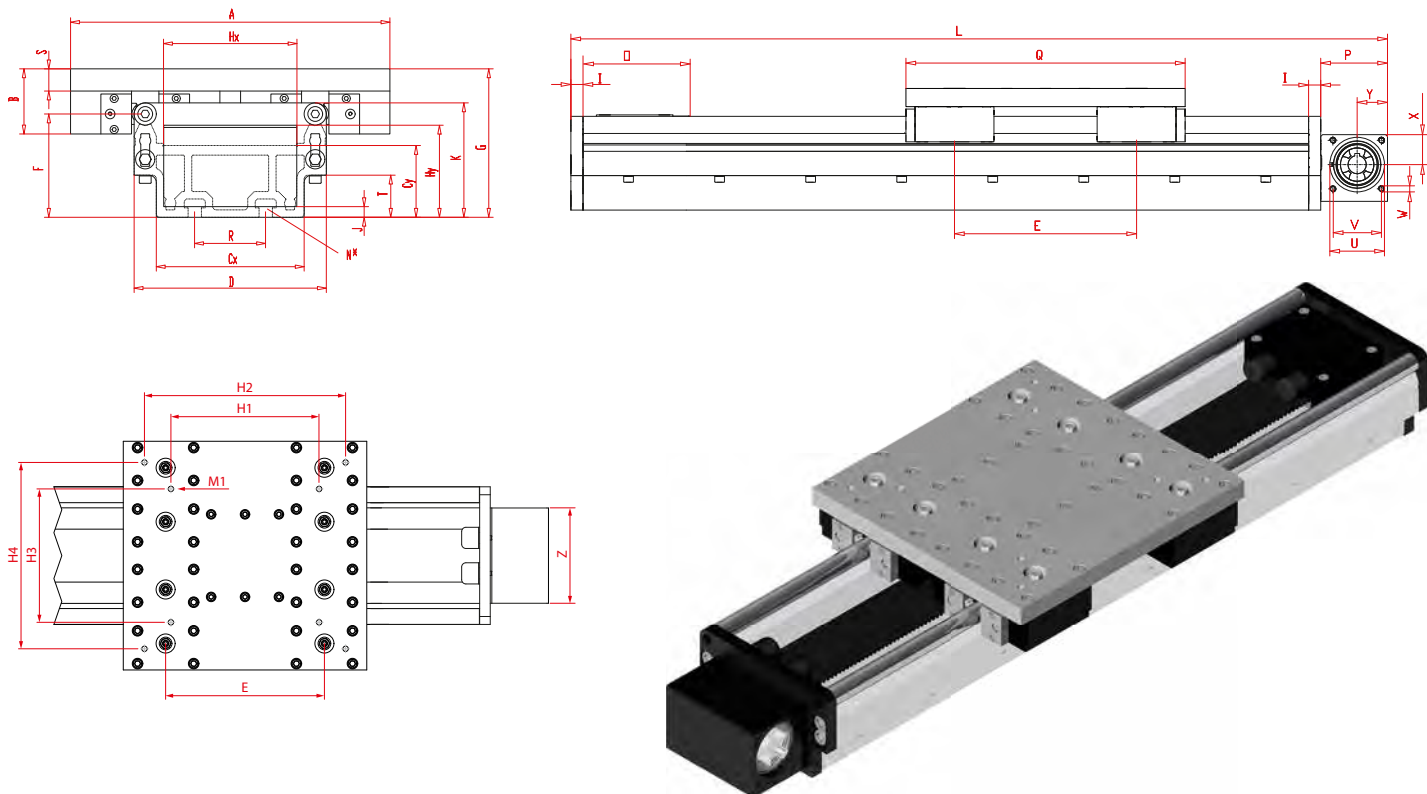
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

$f$  = deflection (mm)  
 $F$  = load (N)  
 $L$  = free length (mm)  
 $E$  = elastic modulus 70000 (N/mm<sup>2</sup>)  
 $I$  = second moment of area (mm<sup>4</sup>)



# Linear system ALLZ 203, 204

Dimensions (mm)



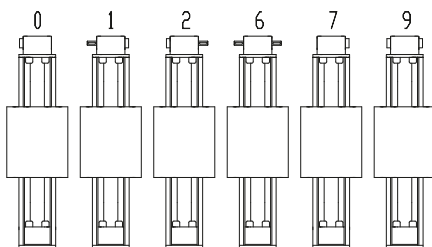
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	Cx	Cy	D	F	G	Hx	Hy	I	J	K	N for	O	P	R	S	T	U -0,05	V	W	X	Y	Z	Basic weight	Weight per 100 mm
ALLZ 203	798	432	88	200	97	260	139,6	200,5	180,5	124,5	20	14,5	154,5	M16	182	110	96	30	57	90	80	10	49,5	50	180	90 kg	4,0 kg
ALLZ 204	822	460	80	200	97	270	139,6	199	180,5	124,5	20	14,5	165	M16	182	110	96	30	57	90	80	10	49,5	50	180	92 kg	4,9 kg

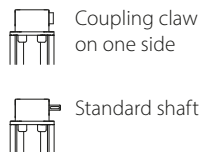
**3** Guide rod size:  
(3) Ø=30 (4) Ø=40

**0** Choice of guide body profile:  
(0) Standard (2) corrosion-protected guide rods and screws  
(4) expanded corrosion-protected version (depending on the availability of components)

**0** Drive version:



9 is as 0, but with coupling claws on both sides.



The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings.

**Belt table:**

Code No.	Belt	mm/rev.	Number of teeth
0 7	8M100	224	28

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
203	30 x 55	8x7x50	24
204	30 x 55	8x7x50	24

ALLZ 20 3 0 0 0 0 0 7 0 2000 — Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

ALLZ203, guide rods 30 mm, standard body profile, coupling claw on both side, toothed belt 8M100, 1208 mm stroke.

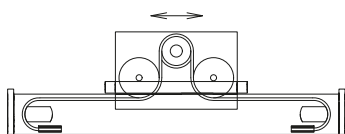
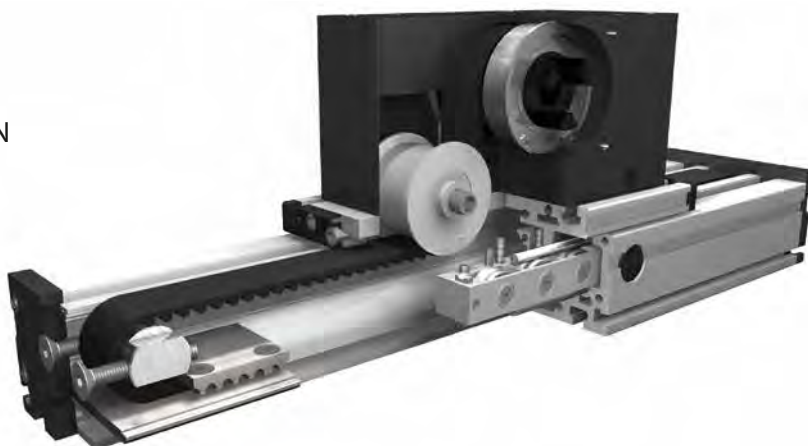
# Linear system **DLSZ 120, 160, 200**

## BELT DRIVE

OMEGA SYSTEM

HORIZONTAL INSTALLATION POSITION

OFF-CENTER LOADS



**Function:**

This linear unit consists of a rectangular aluminium profile with integrated, hardened steel guide rods. The carriage, which has linear ball bearings that can be adjusted free of play, is driven along the guide rods by a timing belt. Each standard pulley includes a coupling claw on one side and is equipped with maintenance-free ball bearings. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. Compared to conventional toothed belt drives, the drive connection is offset by 90°.

**Fitting position:**

As required. Max. length 6.000 mm without joints.

**Carriage mounting:**

By T-slots.

**Unit mounting:**

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

**Belt performance:**

HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.

**Carriage support:**

In the standard version, the carriage runs on 8 rollers which can be adjusted and serviced at a central servicing position. For longer carriages the number of rollers can be increased.

8.1

Forces and torques	Size	120		160		200	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic
$F_x$ (N)	1900	1800	4000	3800	5900	5750	
$F_y$ (N)	1100	900	3000	2000	4400	3100	
$F_z$ (N)	1250	1000	3500	2800	4900	4400	
$M_x$ (Nm)	150	125	400	320	600	510	
$M_y$ (Nm)	140	120	360	300	560	480	
$M_z$ (Nm)	100	90	180	150	310	275	
<b>All forces and torques related to the following:</b>							
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
<b>No-load torque</b>							
Nm	1,1		1,5		1,8		
<b>Speed</b>							
(m/s) max	4		6		8		
<b>Tensile force</b>							
permanent (N)	1900		4000		5900		
0,2 s (N)	2090		4300		6350		
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup>	6,6x10 <sup>5</sup>		2,22x10 <sup>6</sup>		6,38x10 <sup>6</sup>		
$I_y$ mm <sup>4</sup>	38,6x10 <sup>5</sup>		12,20x10 <sup>6</sup>		33,5x10 <sup>6</sup>		
Elastic modulus N/mm <sup>2</sup>	70000		70000		70000		

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

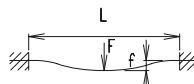
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

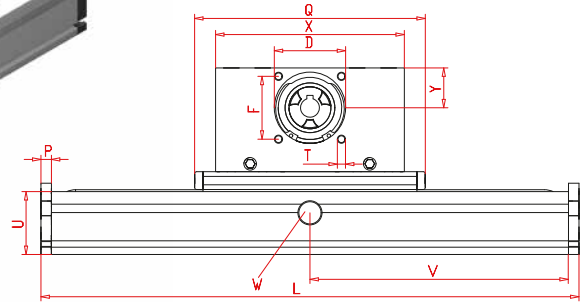
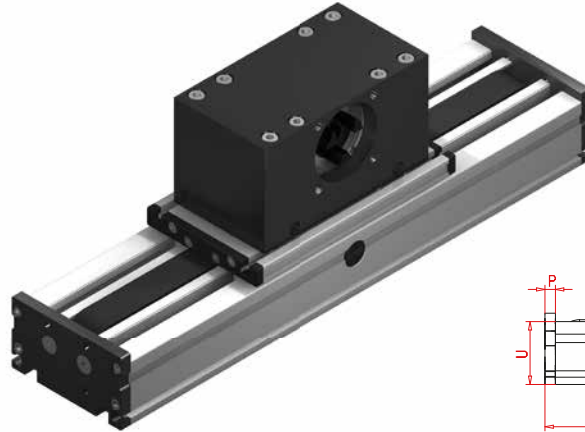
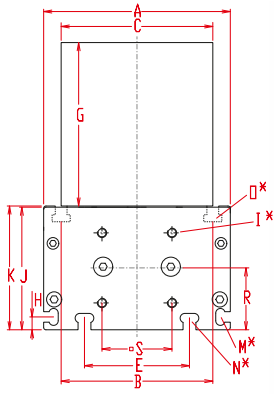
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Linear system **DLSZ 120, 160, 200**

Dimensions (mm)



$V = Q + 100 \text{ mm}$

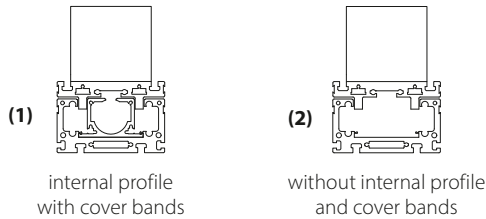
W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

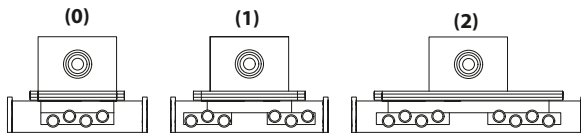
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	I for	M for	N for	O for	P	Q	R	S	T	U	X	Y	Basic weight	Weight per 100 mm
DLSZ 120	230	120	96	100	68	78	60	100	10	68	79	M 6	M 5	M 6	M 6	10	200	39	42	M 8	60	180	39	12,0 kg	1,2 kg
DLSZ 160	330	160	130	130	90	90	80	130	11	105	106	M 8	M 6	M 8	M 8	12	290	53	60	M 10	80	270	60	27,0 kg	1,8 kg
DLSZ 200	380	200	160	160	110	140	100	145	15	128	129	M 10	M 8	M 10	M 10	15	340	69	95	M 10	100	310	62	53,0 kg	2,6 kg

**1 Choice of guide body profile:** Stainless versions upon request.

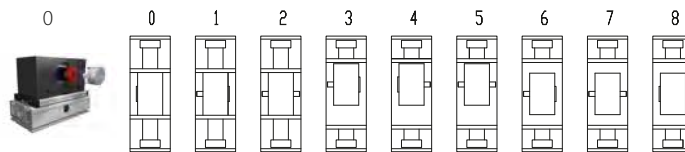


**0 Choice of carriages:**



Size	Version 0		Version 1		Version 2	
	Q	L	Q	L	Q	L
120	200	230	>280	>310	>360	>390
160	290	330	>390	>430	>490	>530
200	340	380	>480	>520	>610	>650

**0 Drive version:**



8 is as 0, but with coupling claws on both sides. The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 160 and 200).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 7	120	8M30	192	24
0 9	160	8M50	256	32
1 0	200	8M70	304	38

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
120	18 x 45	6x6x40	19
160	22 x 45	6x6x40	24
200	30 x 55	8x7x50	28




**DLSZ 120 1 1 0 0 0 7 2 1500** — Basic length + stroke = total length  
Pos. 1 2 3 4 5 6 7

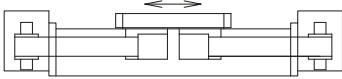
Sample ordering code:

DLSZ120, body profile with internal profile without cover bands, standard carriage, coupling claws on one side, 1270 mm stroke

# Linear system **DLVZ 120, 160**

## INTERNAL BELT DRIVE

-  INDEPENDENT INSTALLATION POSITION
-  SPECIAL DRIVE VERSION
-  SPACE SAVING



### Function:

This unit consists of a rectangular aluminium profile with 2 integrated roller guides. The carriage is moved by a belt drive. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. The openings of the guide body are sealed with 3 stainless steel cover bands to protect the guide from splash water and dust. Alternatively, it can also be supplied without cover bands.

### Fitting position:

As required. Max. length 3.000 mm without joints.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

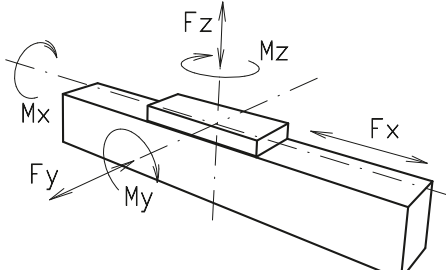
### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 8 rollers which can be adjusted and serviced at a central servicing position. For longer carriages the number of rollers can be increased.

8.1

Forces and torques	Size	DLVZ 120		DLVZ 160	
	Forces/Torques	static	dynamic	static	dynamic
	$F_x$ (N)	894	800	1000	840
	$F_y$ (N)	1100	900	3000	2000
	$F_z$ (N)	1250	1000	3500	2800
	$M_x$ (Nm)	150	125	400	320
	$M_y$ (Nm)	140	120	360	300
	$M_z$ (Nm)	100	90	180	150
<b>All forces and torques relate to the following:</b>					
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$					
table values					
<b>No-load torque</b>					
Nm		1,4		1,8	
<b>Speed</b>					
(m/s) max		3		4	
<b>Tensile force</b>					
permanent (N)		900		1000	
0,2 s (N)		1000		1150	
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_x$ mm <sup>4</sup>		6,6x10 <sup>5</sup>		22,2x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		38,6x10 <sup>5</sup>		122,0x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

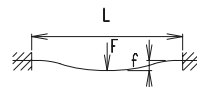
$$P_o = \frac{M_o \cdot n}{9550}$$

$F$  = force (N)  
 $P$  = pulley action perimeter (mm)  
 $S_i$  = safety factor 1,2 ... 2  
 $M_n$  = no-load torque (Nm)  
 $n$  = rpm pulley (min<sup>-1</sup>)  
 $M_o$  = driving torque (Nm)  
 $P_o$  = motor power (KW)

Deflection:

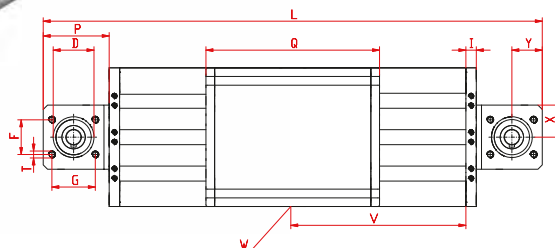
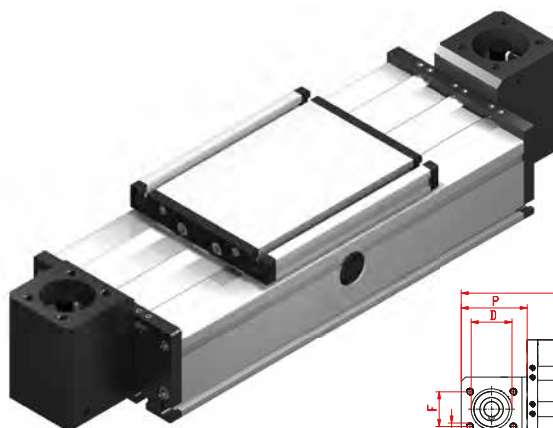
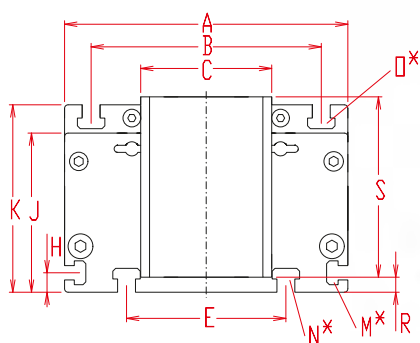
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

$f$  = deflection (mm)  
 $F$  = load (N)  
 $L$  = free length (mm)  
 $E$  = elastic modulus 70000 (N/mm<sup>2</sup>)  
 $I$  = second moment of area (mm<sup>4</sup>)



# Linear system **DLVZ 120, 160**

Dimensions (mm)



$V = Q + 100 \text{ mm}$

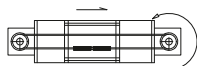
W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

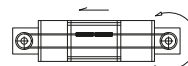
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	I	J	K	M for	N for	O for	P	Q	R	S	T	U	X	Y	Basic weight	Weight per 100 mm
DLVZ 120	300	120	96	56	37	78	30	36	10	10	68	79	M5	M6	M6	56	156	2,5	82	M6	60	28	24	4,62 kg	0,82 kg
DLVZ 160	410	160	130	74	47	90	40	50	11	12	90	106	M6	M8	M8	76	200	8,5	102	M8	80	37	35	11,23 kg	1,76 kg

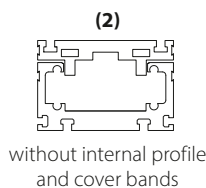
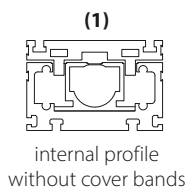
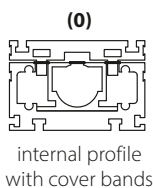
**1** (1) Belt connection right



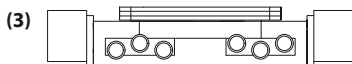
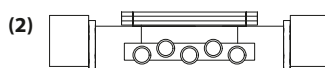
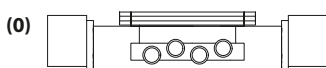
**(2)** Belt connection left



**0** Choice of guide body profile: Stainless versions upon request.

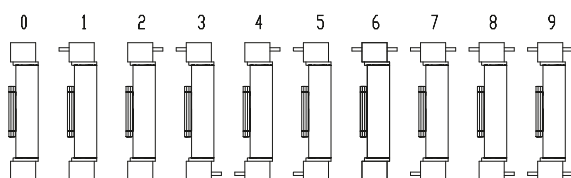


**0** Choice of carriages:



Size	Version 0		Version 2		Version 3	
	Q	L	Q	L	Q	L
120	156	300	196	340	236	380
160	200	410	250	460	>300	>510

**0** Drive version:



The standard version 0 is supplied with 4 flush mounted shafts.

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	120	5M25	80	16
0 4	160	5M25	110	22

**Shaft dimensions:**

Size	Shaft $\phi h6 \times \text{length}$	Key
120	14 x 35	5x5x28
160	18 x 45	6x6x40

**DLVZ 160 1 0 0 0 0 4 1 1500**

Pos. 1 2 3 4 5 6 7




Basic length + stroke = total length

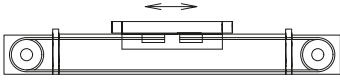
Sample ordering code:

DLVZ 160 with belt connection right, internal profile with cover bands, standard carriage and 4 flush mounted shafts, 1090 mm stroke

# Linear system **DLZ 120, 160, 200**

## BELT DRIVE

-  CLEAN ROOM
-  UNIVERSAL SYSTEM
-  LONG TRAVERSE PATH > 6000 MM



**COLANDIS**  
the clean air company

### Function:

This unit consists of a rectangular aluminium profile with 2 integrated roller guides. The carriage is moved by a belt drive. Each standard pulley has got one coupling claw on one side. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. The openings of the guide body are sealed with 3 stainless steel cover bands to protect the guide from splash water and dust. Alternatively, it can also be supplied without cover bands. With this series, multi-part assembled units with long strokes can be realized.

### Fitting position:

As required. Max. length 6.000 mm without joints.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

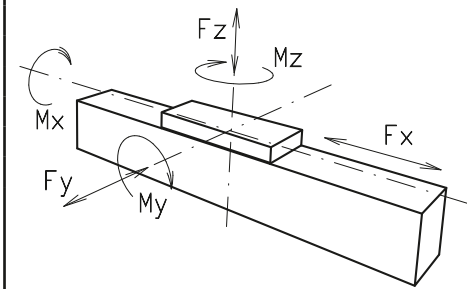
### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 8 rollers which can be adjusted and serviced at a central servicing position. For longer carriages the number of rollers can be increased.

### Forces and torques



Size	120		160		200	
	static	dynamic	static	dynamic	static	dynamic
<b>Forces/Torques</b>						
$F_x$ (N)	894	800	1900	1800	4000	3800
$F_y$ (N)	1100	900	3000	2000	4400	3100
$F_z$ (N)	1250	1000	3500	2800	4900	4400
$M_x$ (Nm)	150	125	400	320	600	510
$M_y$ (Nm)	140	120	360	300	560	480
$M_z$ (Nm)	100	90	180	150	310	275
<b>All forces and torques related to the following:</b>						
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$						
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$						
<b>No-load torque</b>						
Nm without cover bands	1,2		1,5		1,8	
Nm with cover bands	1,6		2,1		4	
<b>Speed</b>						
(m/s) max	4		6		8	
<b>Tensile force</b>						
permanent (N)	900		1900		4000	
0,2 s (N)	1000		2090		4300	
<b>Geometrical moments of inertia of aluminium profile</b>						
$I_x$ mm <sup>4</sup>	6,6x10 <sup>5</sup>		22,2x10 <sup>5</sup>		63,8x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>	38,6x10 <sup>5</sup>		122,0x10 <sup>5</sup>		335x10 <sup>5</sup>	
Elastic modulus N/mm <sup>2</sup>	70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

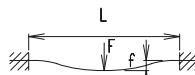
$$P_o = \frac{M_o \cdot n}{9550}$$

$F$  = force (N)  
 $P$  = pulley action perimeter (mm)  
 $S_i$  = safety factor 1,2 ... 2  
 $M_n$  = no-load torque (Nm)  
 $n$  = rpm pulley (min<sup>-1</sup>)  
 $M_o$  = driving torque (Nm)  
 $P_o$  = motor power (KW)

Deflection:

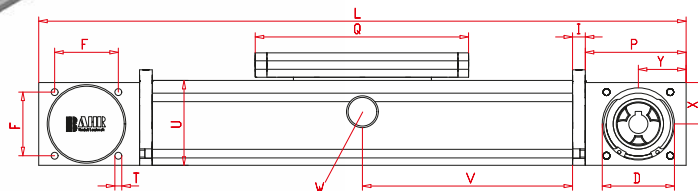
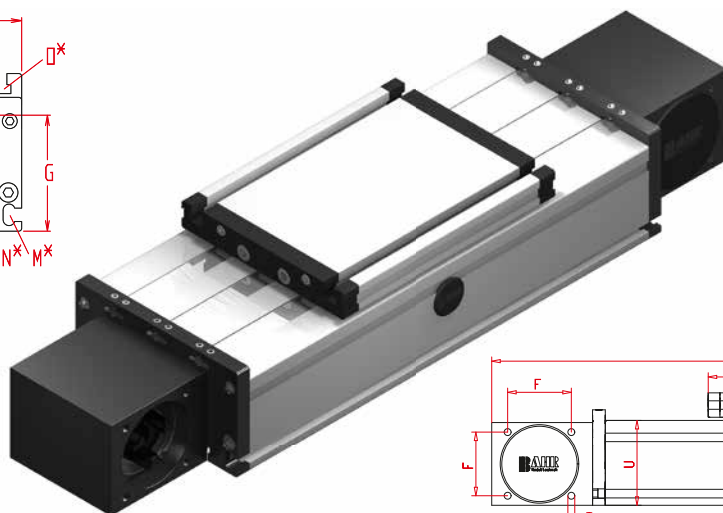
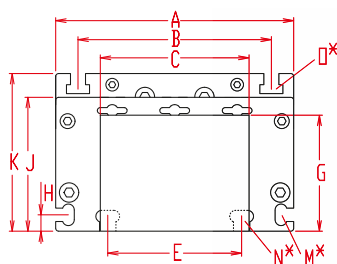
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

$f$  = deflection (mm)  
 $F$  = load (N)  
 $L$  = free length (mm)  
 $E$  = elastic modulus 70000 (N/mm<sup>2</sup>)  
 $I$  = second moment of area (mm<sup>4</sup>)



# Linear system **DLZ 120, 160, 200**

Dimensions (mm)



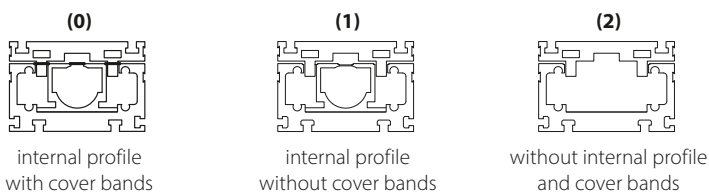
V = Q + 100 mm  
W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

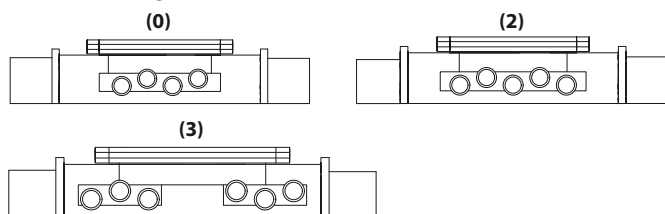
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	I	J	K	M for	N for	O for	P	Q	T	U	X	Y	Basic weight	Weight per 100 mm
DLZ 120	330	120	96	80	47	78	42	58	10	10	68	79	M 5	M 6	M 6	70	156	M 6	60	28	35	5,1 Kg	0,85 Kg
DLZ 160	440	160	130	100	68	90	60	78	11	12	90	106	M 6	M 8	M 8	95	200	M 8	80	39	45	13,0 kg	1,69 kg
DLZ 200	530	200	160	130	90	140	80	97	15	15	110	129	M 8	M10	M10	110	270	M10	100	49	50	23,4 kg	2,33 kg

**0 Choice of guide body profile:** Stainless versions upon request.

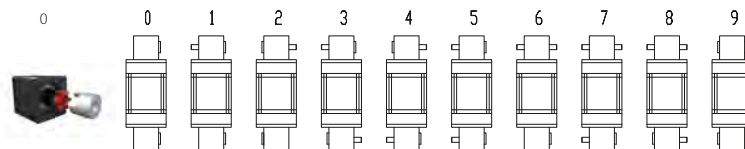


**0 Choice of carriage:**



Size	Version 0		Version 2		Version 3	
	Q	L	Q	L	Q	L
120	156	330	196	370	>236	>410
160	200	440	250	490	>300	>540
200	270	530	330	600	>410	>680

**0 Drive version:**



9 is as 0, but with coupling claws on both sides.  
The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 200).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	120	5M25	130	26
0 7	160	8M30	176	22
0 9	160	8M50	176	22
0 9	200	8M50	224	28
1 0	200	8M70	224	28

**Shaft dimensions / Coupling claw:**

Size	Shaft $\phi h6 \times$ length	Key	Coupling
120 (5M25)	14 x 35	5x5x28	14
160 (8M30)	18 x 45	6x6x40	19
160 (8M50)	25 x 35	8x7x32	----- *
200 (8M50)	22 x 45	6x6x40	24
200 (8M70)	30 x 55	8x7x50	----- *

**DLZ 160 1 0 0 0 0 7 1 1500** — Basic length + stroke = total length  
Pos. 1 2 3 4 5 6 7

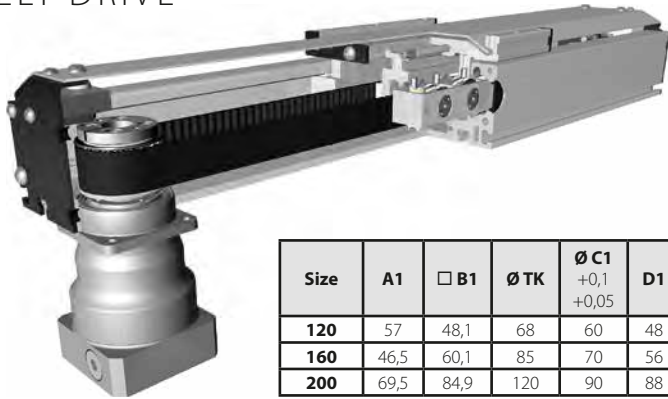
\* Coupling claw not possible with belt widening.

Sample ordering code:  
DLZ160 with internal profile and cover bands, standard carriage, coupling claw on one side, 1060 mm stroke.

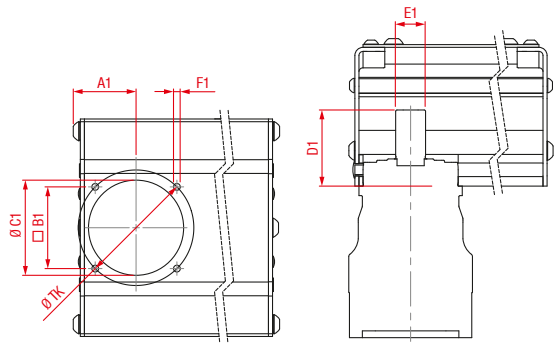


# Linear system **DLZPVI 120, 160, 200**

## BELT DRIVE



Size	A1	B1	Ø TK	Ø C1 +0,1 +0,05	D1	E1	F1
<b>120</b>	57	48,1	68	60	48	16	M5
<b>160</b>	46,5	60,1	85	70	56	22	M6
<b>200</b>	69,5	84,9	120	90	88	32	M8



### Function:

This unit consists of a rectangular aluminium profile with 2 integrated roller guides. The carriage is moved by a belt drive. On the drive side the pulley is beared on the shaft of a planetary gear. Belt tension can be readjusted by a simple screw adjustment at the opposite side of the drive. A special curved aluminium sheet is covering the carriage side. There is only a small gap between carriage and aluminium sheet. Because of its special design it is possible to drive the carriage over the pulley areas. This fact is making the unit very compact. The cover profile can be adjusted according to the mounting position.

### Fitting position:

As required, max. length DLZPVI 120 / 1600mm, DLZPVI 160 / 1800mm, DLZPVI 200 / 2000mm

### Carriage mounting:

By tapped holes.

### Unit mounting:

T-slots

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 4 runner blocks which can be serviced at a central servicing position. For longer carriages the number of runner blocks can be increased.

8.1

Forces and torques	120		160		200	
	static	dynamic	static	dynamic	static	dynamic
$F_x$ (N)	894	800	1900	1800	4000	3800
$F_y$ (N)	1100	900	3000	2000	4400	3100
$F_z$ (N)	1250	1000	3500	2800	4900	4400
$M_x$ (Nm)	150	125	400	320	600	510
$M_y$ (Nm)	140	120	360	300	560	480
$M_z$ (Nm)	100	90	180	150	310	275

**All forces and torques related to the following:**

existing values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

table values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

No-load torque			
Nm	1,2	1,5	1,8
Speed			
(m/s) max	4	6	8
Tensile force			
permanent (N)	900	1900	4000
0,2 s (N)	1000	2090	4300
Geometrical moments of inertia of aluminium profile			
$I_x$ mm <sup>4</sup>	$6,6 \times 10^5$	$22,2 \times 10^5$	$57,2 \times 10^5$
$I_y$ mm <sup>4</sup>	$38,6 \times 10^5$	$122,0 \times 10^5$	$310 \times 10^5$
Elastic modulus N/mm <sup>2</sup>	70000	70000	70000

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

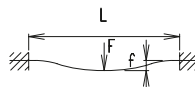
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 Si = safety factor 1,2 ... 2  
 Mn = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 Mo = driving torque (Nm)  
 Po = motor power (KW)

Deflection:

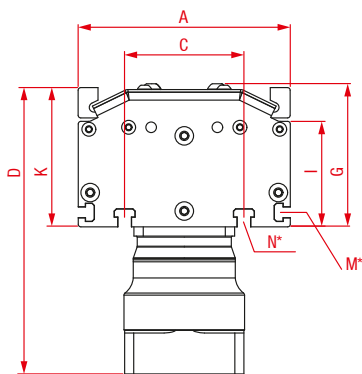
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



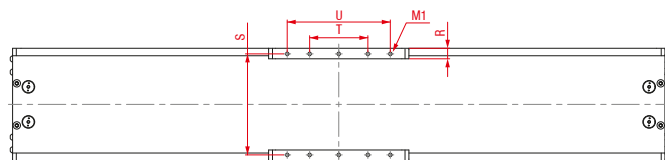
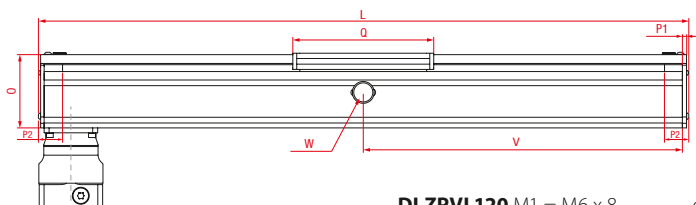
# Linear system DLZPVI 120, 160, 200

Dimensions (mm)



Optionally available with angular planetary gearbox

Increasing the carriage length will increase the basic length by the same amount.



**DLZPVI 120** M1 = M6 x 8      only 8 threaded holes in the carriage

$V = Q + 100$

**DLZPVI 160** M1 = M8 x 12      **DLZPVI 200** M1 = M10 x 12

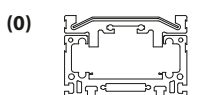
W = servicing position

\*slide nuts

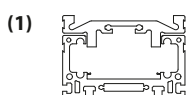
Size	Basic length L	A	C	D	G	I	K	M for	N for	O	P1	P2	Q	R	S	T	U	Basic weight without gearbox	Weight per 100 mm
<b>DLZPVI 120</b>	225	120	78	169	82,5	60	79	M5	M6	78	6	35	152	11,5	106	40	120	3,74 kg	0,65 kg
<b>DLZPVI 160</b>	285	160	90	217,5	108,5	80	106	M6	M8	104	8,25	43,5	196	15	144	80	160	10,42 kg	1,26 kg
<b>DLZPVI 200</b>	350	200	140	251	132,5	100	129	M8	M10	128	10	45,5	256	17	180	100	200	17,44 kg	2,18 kg

8.1

**0** Choice of guide body profile: Stainless versions upon request.



with cover profile

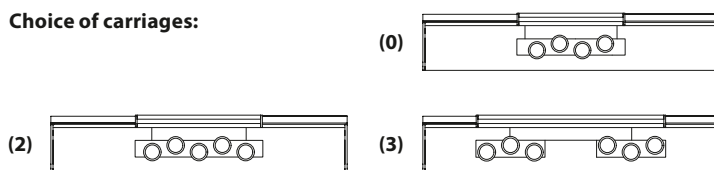


without cover profile



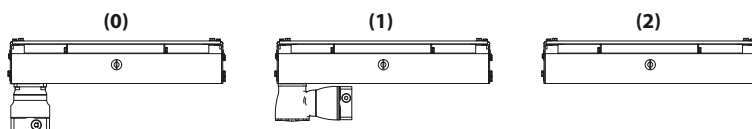
belt connection

**0** Choice of carriages:



Size	Version 2		Version 3	
	Q	L	Q	L
<b>120</b>	192	265	232	305
<b>160</b>	246	335	296	385
<b>200</b>	320	420	400	500

**0** Drive version:



(0) planetary gearbox  
(1) angular planetary gearbox  
(2) without gearbox

**Belt table:**

Code-No.	Size	Belt	mm/rev.	Number of teeth
<b>0 4</b>	<b>120</b>	5M25	130	26
<b>0 7</b>	<b>160</b>	8M30	176	22
<b>0 9</b>	<b>200</b>	8M50	224	28

**Gearbox variants:**

Gearbox	DLZPVI 120	DLZPVI 160	DLZPVI 200
<b>Neugart</b>	(0) PLN 70 (1) WPLN 70	PLN 90 WPLN 90	PLN 115 WPLN 115
<b>SEW</b>	(0) PSKC 221	PSKC 321	PSKC 521
<b>Wittenstein</b>	(0) SP+060 (1) SK+060	SP+075 SK+075	SP+100 SK+100

**DLZPVI 160 1 0 0 0 0 7 1 1500** — Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

DLZPVI 160 with cover profile, standard carriage, with planetary gearbox, 1202 mm stroke.

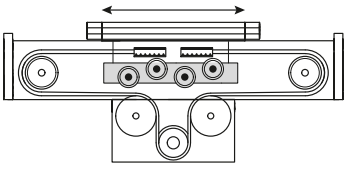
# Linear system **DLZS 120, 160, 200**

## BELT DRIVE

 OMEGA SYSTEM

 VERTICAL INSTALLATION POSITION

 LIFTING SYSTEM



### Function:

This unit consists of a rectangular aluminium profile with 2 integrated roller guides. The carriage is moved by a belt drive. An innovation is that the toothed belt is diverted within a drive block positioned centrally. The result is an enormous compactness with regard to the overall system length. The toothed drive pulley has a coupling claw in the standard version. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. The openings of the guide body are sealed with 3 stainless steel cover bands to protect the guide from splash water and dust. Use: compact and space-saving system with variable position of the drive block.

### Fitting position:

As required. Max. length 6.000 mm without joints.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 8 rollers which can be adjusted and serviced at a central servicing position. For longer carriages the number of rollers can be increased.

8.1

Forces and torques	Size	120		160		200	
	Forces/Torques	static	dynamic	static	dynamic.	static	dynamic.
$F_z$ (N)		894	800	1900	1800	4000	3800
$F_y$ (N)		1100	900	3000	2000	4400	3100
$F_x$ (N)		1250	1000	3500	2800	4900	4400
$M_x$ (Nm)		150	125	400	320	600	510
$M_y$ (Nm)		140	120	360	300	560	480
$M_z$ (Nm)		100	90	180	150	310	275
<b>All forces and torques related to the following:</b>							
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
<b>No-load torque</b>							
Nm without cover bands		1,2		1,5		1,8	
Nm with cover bands		1,6		2,1		4	
<b>Speed</b>							
(m/s) max		4		6		8	
<b>Tensile force</b>							
permanent (N)		900		1900		4000	
0,2 s (N)		1000		2090		4300	
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup>		6,6x10 <sup>5</sup>		22,2x10 <sup>5</sup>		63,8x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		38,6x10 <sup>5</sup>		122,0x10 <sup>5</sup>		335x10 <sup>5</sup>	
Elastic modulus N/mm <sup>2</sup>		70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

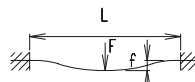
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

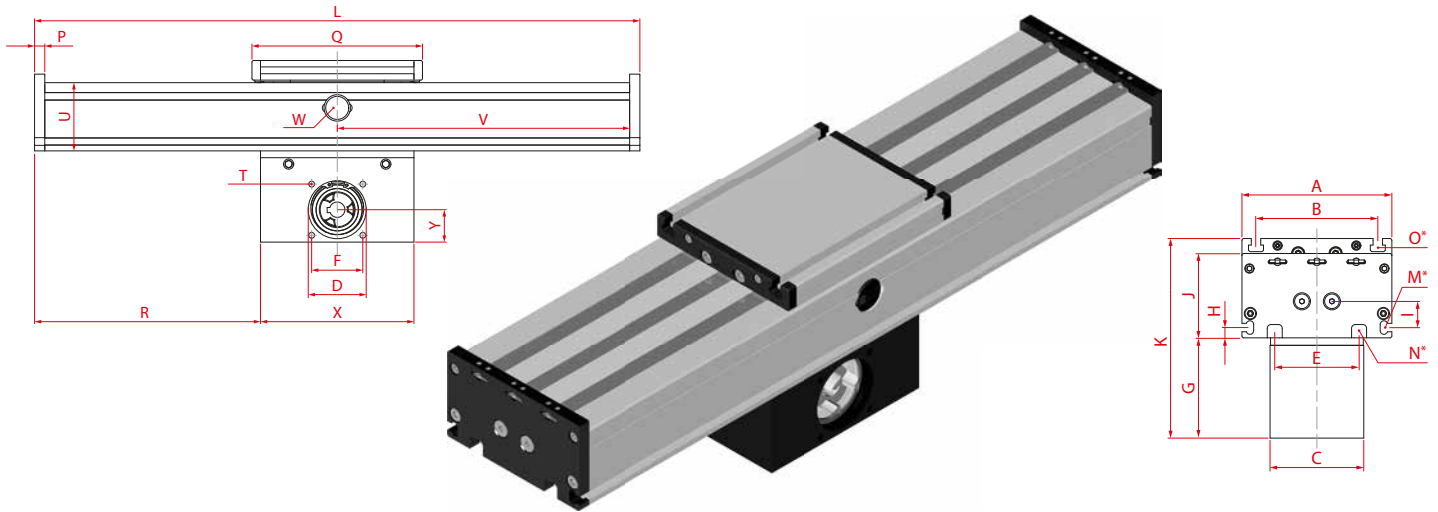
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system DLZS 120, 160, 200

Dimensions (mm)



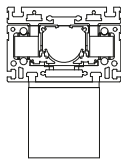
V = Q + 100 mm      W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

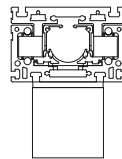
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	I	J	K	M for	N for	O for	P	Q	R	T	U	X	Y	Basic weight	Weight per 100 mm
DLZS 120	210	120	96	80	47	78	42	84,5	10	18,7	68	163	M5	M6	M6	10	156	40	M6	60	130	30	6,1 kg	0,85 kg
DLZS 160	300	160	130	100	66	90	60	107	11	39	90	213	M6	M8	M8	12	200	25	M8	80	180	38	14,9 kg	1,5 kg
DLZS 200	380	200	160	130	90	140	80	146	15	48,5	110	275	M8	M10	M10	15	270	55	M10	100	270	60	30,8 kg	2,1 kg

**0** Choice of guide body profile: Stainless versions upon request.

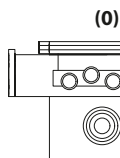


**(0)** internal profile with cover bands

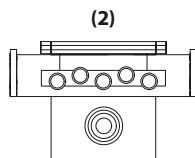


**(1)** internal profile without cover bands

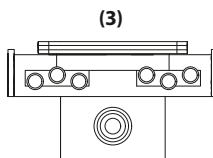
**0** Choice of carriage:



**(0)**



**(2)**



**(3)**

Size	Version 0		Version 2		Version 3	
	Q	L	Q	L	Q	L
120	156	210	196	216	236	256
160	200	300	250	300	>300	>330
200	270	380	330	380	>410	>470

**0** Drive version:



0



1



3



4



5

5 is as 0, but with coupling claws on both sides. The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 200).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	120	5M 25	130	26
0 7	160	8M 30	192	24
0 9	200	8M 50	256	32

**Shaft dimensions / Coupling claw:**

Size	Shaft $\phi$ h6 x length	Key	Coupling
120	14 x 35	5x5x28	14
160	18 x 45	6x6x40	19
200	22 x 45	6x6x40	24

**DLZS 160 1 0 0 0 0 7 1 1500** — Basic length + stroke = total length  
 Pos. 1 2 3 4 5 6 7

Sample ordering code:

DLZS160 with internal profile and cover bands, standard carriage, coupling claw on one side, 1200 mm stroke.

# Linear system **DLZS 120 P, 160 P, 200 P**

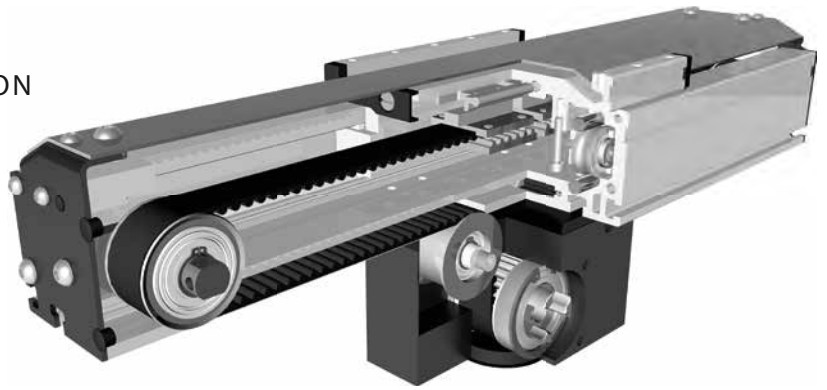
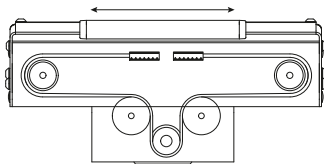
## BELT DRIVE

⊕ INDEPENDENT INSTALLATION POSITION

Ω OMEGA SYSTEM

⊞ LIFTING SYSTEM

👤 COVER PROFILE



### Function:

The guide body consists of a rectangular aluminium profile with two integrated roller guides. The carriage is moved by a belt drive. The novelty is that the timing belt is diverted into a drive block positioned centrally. This results in an extraordinary compactness with regard to the overall length of the system. The driving toothed pulley is provided with a coupling claw as a standard. The belt tension can be easily readjusted via a tensioning device within the bearing block. The openings in the guide body are closed by an aluminium profile, leaving only small slits open on the sides. The cover profile can be adjusted according to the mounting position.

**The advantages compared to the DLZS positioning system are:** The number of components prone to wear such as cover bands and sliding blocks is reduced and the fact that there is no friction makes it possible to use smaller motors. In addition, the cover profile, which is fixed with only a few screws, improves the serviceability and maintainability.

### Fitting position:

As required. Max. length DLZS 120P / 1600mm, DLZS 160P / 1800mm, DLZS 200P / 2000mm

### Carriage mounting:

By tapped holes.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 8 rollers which can be serviced at a central servicing position. For longer carriages the number of rollers can be increased.

8.1

Forces and torques	Size	120		160		200	
	Forces/Torques	static	dynamic	static	dynamic.	static	dynamic.
	$F_x$ (N)	894	800	1900	1800	4000	3800
	$F_y$ (N)	1100	900	3000	2000	4400	3100
	$F_z$ (N)	1250	1000	3500	2800	4900	4400
	$M_x$ (Nm)	150	125	400	320	600	510
	$M_y$ (Nm)	140	120	360	300	560	480
	$M_z$ (Nm)	100	90	180	150	310	275
<b>All forces and torques related to the following:</b>							
Vorhandener Wert $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
Tabellenwert							
<b>No-load torque</b>							
Nm	1,2		1,5		1,8		
<b>Speed</b>							
(m/s) max	4		6		8		
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup>	6,6 x 10 <sup>5</sup>		22,2 x 10 <sup>5</sup>		57,2 x 10 <sup>5</sup>		
$I_y$ mm <sup>4</sup>	38,6 x 10 <sup>5</sup>		122 x 10 <sup>5</sup>		310 x 10 <sup>5</sup>		
Elastic modulus N/mm <sup>2</sup>	70.000		70.000		70.000		

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

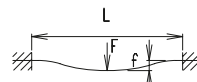
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 Si = safety factor 1,2 ... 2  
 Mn = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 Mo = driving torque (Nm)  
 Po = motor power (KW)

Deflection:

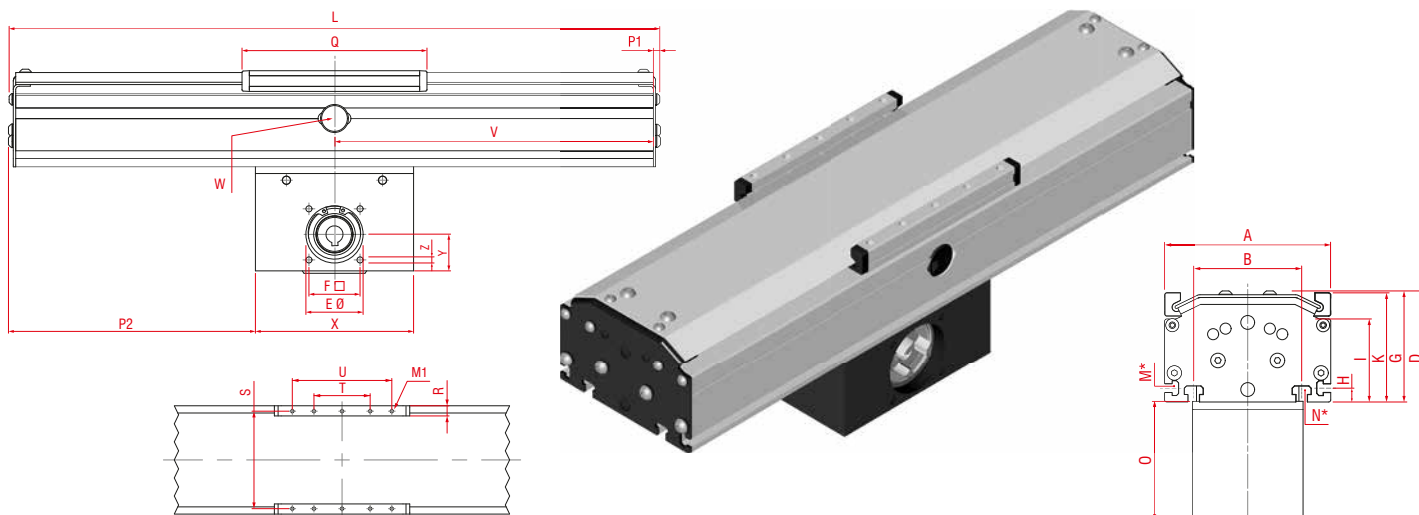
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system DLZS 120 P, 160 P, 200 P

Dimensions (mm)



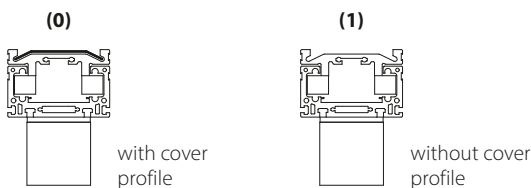
V = Q + 100 mm      W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

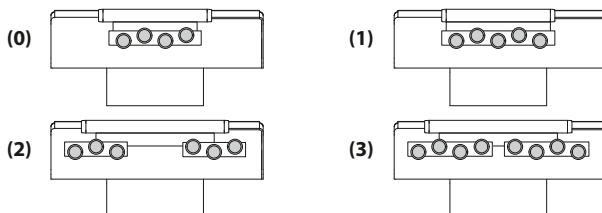
Size	A	B	C	D	E Ø	F □	G	H	I	K	M for	N for	O	P1	P2	R	S	T	U	X	Y	Z	Basic weight	Weight per 100 mm
<b>DLZS 120 P</b>	120	78	80	169	47	42	80,5	10	60	79	M5	M6	85,5	6	32	11,5	106	40	120	130	30	M6	5,5 kg	0,77 kg
<b>DLZS 160 P</b>	160	90	100	219	68	60	108,5	11	80	106	M6	M8	107	8,2	51,2	15	144	80	160	180	38	M8	14,1 kg	1,5 kg
<b>DLZS 200 P</b>	200	140	130	281	90	80	132,5	15	100	129	M8	M10	146	10	37,5	17	180	100	200	270	60	M10	30,2 kg	2,1 kg

**0** Choice of guide body profile: Stainless versions upon request.



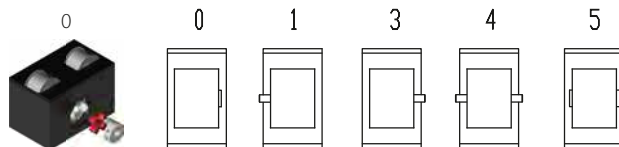
**DL 120** M1 = M6 x 8  
only 8 threaded holes in the carriage  
**DL 160** M1 = M8 x 12    **DL 200** M1 = M10 x 12

**0** Choice of carriages:



Size	Version 0		Version 1	
	Q	L	Q	L
<b>120</b>	152	192	192	232
<b>160</b>	196	282	246	332
<b>200</b>	256	345	320	409
Size	Version 2		Version 3	
	Q	L	Q	L
<b>120</b>	232	272	---	---
<b>160</b>	296	382	396	482
<b>200</b>	396	485	521	610

**0** Drive version:



5 is as 0, but with coupling claws on both sides. The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 200).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
<b>0 4</b>	<b>120</b>	5M 25	130	26
<b>0 7</b>	<b>160</b>	8M 30	192	24
<b>0 9</b>	<b>200</b>	8M 50	256	32

**Shaft dimensions / Coupling claw:**

Size	Shaft Ø h6 x length	Key	Coupling
<b>120</b>	14 x 35	5 x 5 x 28	14
<b>160</b>	18 x 45	6 x 6 x 40	19
<b>200</b>	22 x 45	6 x 6 x 40	24

**DLZS 120 P 1 0 0 0 0 4 1 1500**      Basic length + stroke = total length

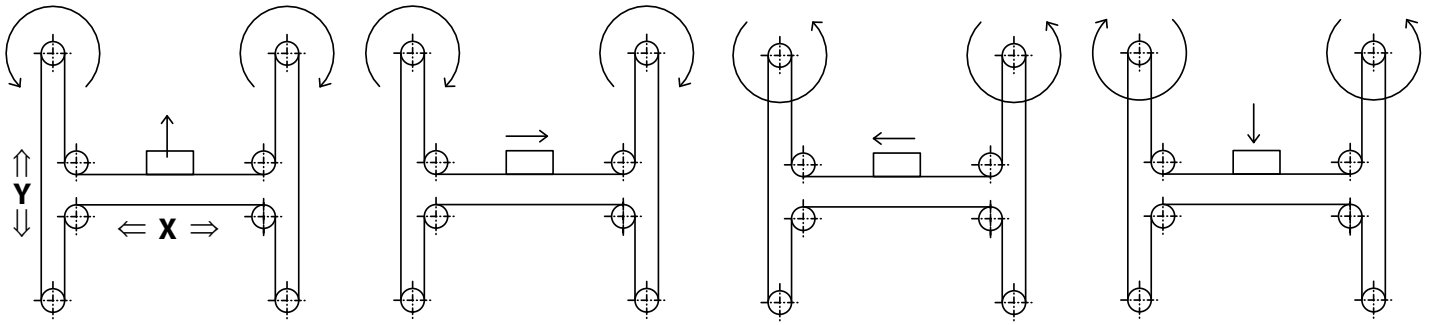
Pos. 1 2 3 4 5 6 7

Sample ordering code:

with cover profile, standard carriage, coupling claw on one side, 1308 mm stroke.

# Linear system **DLZU 120, 160, 200**

## SURFACE PORTAL - STABLE DESIGN - ROLLER GUIDE



### Function:

Surface portal, consisting of two Y-axes and one X-axis. Due to the stable rectangular profile, high torques and loads can be absorbed; in addition, very high stability and low deflection are ensured for long axis systems. The drive is provided by a revolving belt, which remains connected by various deflection points. The adjustment is made by two motors. The coordinate is diagonal to the deflection points of the X-axis. Advantage: Only small weights are moved and thus high accelerations are achieved. Very compact design. Can be easily positioned and used with our matching mounting kits in the accessories section.

### Fitting position:

As required. Max. length and width 3.000 mm.

### Carriage mounting:

By T-slots

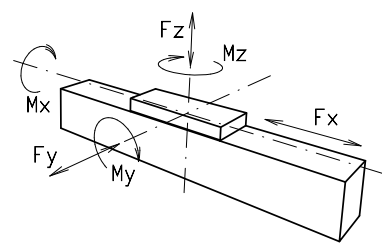
### Unit mounting:

By T-slots or mounting sets.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability:  $\pm 0,1$  mm.

8.1

Forces and torques	Size	120		160		200	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic
	$F_x$ (N)	894	800	1900	1800	4000	3800
	$F_y$ (N)	1100	900	3000	2000	4400	3100
	$F_z$ (N)	1250	1000	3500	2800	4900	4400
	$M_x$ (Nm)	150	125	400	320	600	510
	$M_y$ (Nm)	140	120	360	300	560	480
	$M_z$ (Nm)	100	90	180	150	310	275
<b>All forces and torques relate to the following:</b>							
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
<b>No-load torque</b>							
Nm without cover band		1,2		1,5		1,8	
<b>Speed</b>							
(m/s) max		4		6		8	
<b>Tensile force</b>							
permanent (N)		900		1900		4000	
0,2 s (N)		1000		2090		4300	
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup>		6,6x10 <sup>5</sup>		22,2x10 <sup>5</sup>		63,8x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		38,6x10 <sup>5</sup>		122x10 <sup>5</sup>		335x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

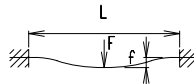
$$P_o = \frac{M_o \cdot n}{9550}$$

$F$  = force (N)  
 $P$  = pulley action perimeter (mm)  
 $S_i$  = safety factor 1,2 ... 2  
 $M_n$  = no-load torque (Nm)  
 $n$  = rpm pulley (min<sup>-1</sup>)  
 $M_o$  = driving torque (Nm)  
 $P_o$  = motor power (KW)

Deflection:

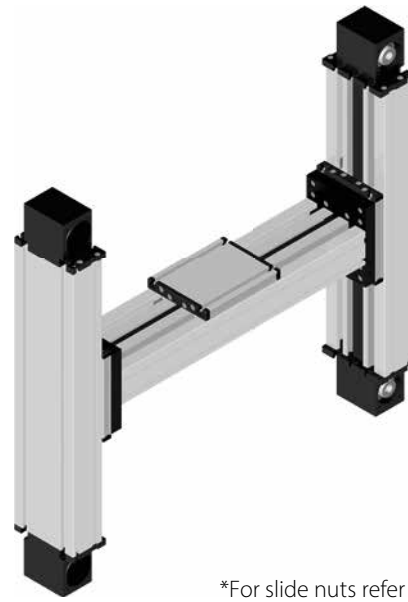
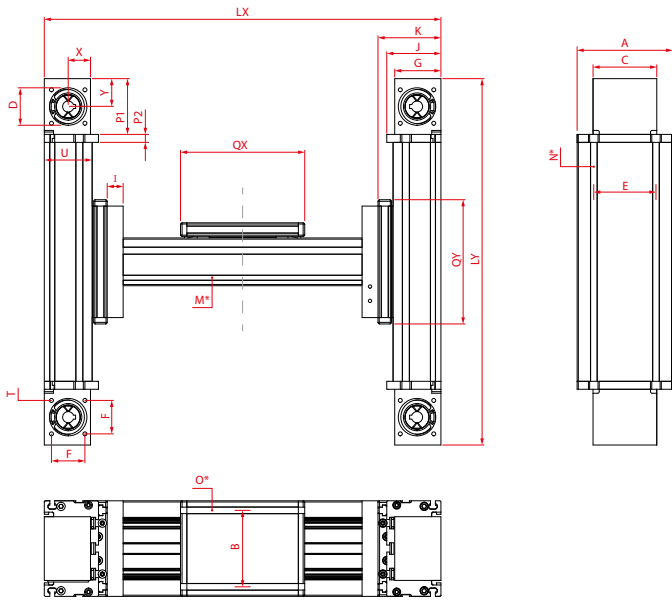
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

$f$  = deflection (mm)  
 $F$  = load (N)  
 $L$  = free length (mm)  
 $E$  = elastic modulus 70000 (N/mm<sup>2</sup>)  
 $I$  = second moment of area (mm<sup>4</sup>)



# Linear system DLZU 120, 160, 200

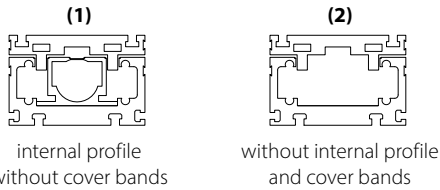
Dimensions (mm)



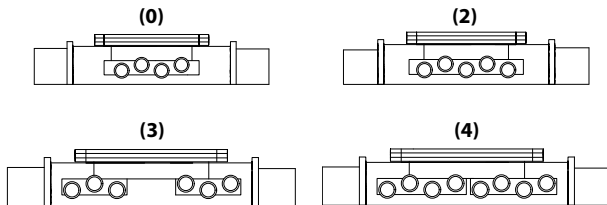
\*For slide nuts refer to chapter 2.2 page 2

Size	Basic length		A	B	C	D -0,05	E	F	G	I	J	K	M for	N for	O for	P1	P2	Qx	Qy	T	U	X	Y	Basic weight	Weight per 100 mm
	Lx	Ly																							
DLZU 120	354	316	120	96	80	47	78	42	58	20	68	79	M5	M6	M6	70	10	156	156	M6	60	28	35	14,42 kg	0,85 kg
DLZU 160	462	414	160	130	100	68	90	60	78	25	90	106	M6	M8	M8	95	12	200	200	M8	80	39	45	34,23 kg	1,69 kg
DLZU 200	648	540	200	160	130	90	140	80	97	50	110	129	M8	M10	M10	110	15	270	290	M10	100	49	50	74,11 kg	2,33 kg

**0 Choice of guide body profile:** Stainless versions upon request.

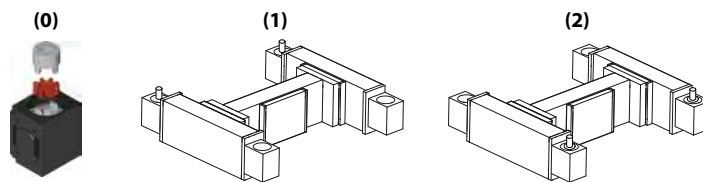


**0 Choice of carriages:**



Size	Version 0				Version 2			
	Qx	Lx	Qy	Ly	Qx	Lx	Qy	Ly
120	156	354	156	316	196	394	196	356
160	200	462	200	414	250	512	250	464
200	270	648	290	540	320	688	330	580
Size	Version 3				Version 4			
	Qx	Lx	Qy	Ly	Qx	Lx	Qy	Ly
120	236	434	236	396	300	498	300	460
160	300	562	300	514	--	--	--	--
200	410	768	410	660	--	--	--	--

**0 Drive version:**



The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings.

**Belt table:**

Code Nr.	Size	Belt	mm/rev.	Number of teeth
0 4	120	5M25	130	26
0 7	160	8M30	176	22
0 9	200	8M50	224	28

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
120 (5M25)	14 x 35	5x5x28	14
160 (8M30)	18 x 45	6x6x40	19
200 (8M50)	22 x 45	6x6x40	24

**DLZU 120 7 0 0 0 0 4 1 1500** X-Axis Basic length + stroke = total length  
**DLZU 120 8 0 0 0 0 4 1 700** Y-Axes Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

For combination kits and connecting elements refer to chapter 2.2

Sample ordering code:  
 DLZU 120, with standard body profile, standard carriage, coupling claw on one side, stroke X = 1074 / Y = 370 mm

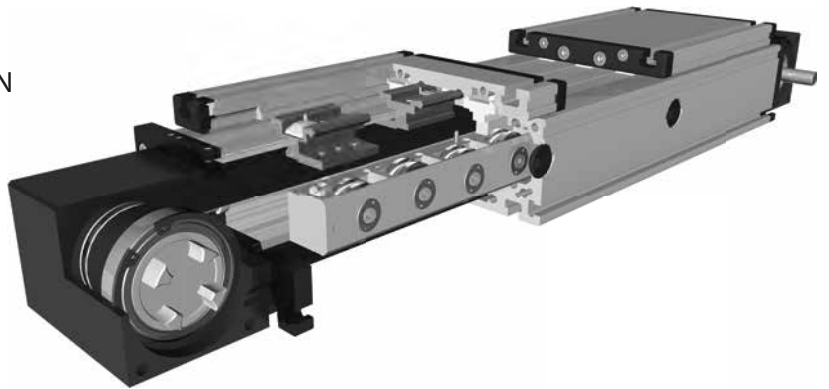
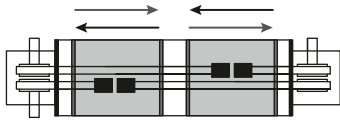


# Linear system **DLZZ 160, 200**

## BELT DRIVE WITH TWO SEPARATELY DRIVEN CARRIAGES

☑ INDEPENDENT CARRIAGES

☒ HORIZONTAL INSTALLATION POSITION



### Function:

This unit consists of a rectangular aluminium profile with 2 integrated roller guides. The carriage is moved by a belt drive. Each carriage can be moved separately by its own drive. This unit has twin pulleys, which run on separate bearings, and two independent, parallel drive belts, one for each carriage. The openings of the guide body are sealed with 3 stainless steel cover bands to protect the guide from splash water and dust.

### Fitting position:

As required. Max. length 4.000 mm without joints.

### Carriage mounting:

By T-slots

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 8 rollers which can be adjusted and serviced at a central servicing position. For longer carriages the number of rollers can be increased.

8.1

Forces and torques	Size	160		200	
	Forces/Torques	static	dynamic.	static	dynamic.
	$F_x$ (N)	1210	1100	1900	1800
	$F_y$ (N)	3000	2000	4400	3100
	$F_z$ (N)	3500	2800	4900	4400
	$M_x$ (Nm)	400	320	600	510
	$M_y$ (Nm)	360	300	560	480
	$M_z$ (Nm)	180	150	310	275
<b>All forces and torques related to the following:</b>					
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$					
table values					
<b>No-load torque</b>					
Nm without cover bands		1,5		1,8	
Nm with cover bands		2,1		4	
<b>Speed</b>					
(m/s) max		6		8	
<b>Tensile force</b>					
permanent (N)		1210		1400	
0,2 s (N)		1331		2090	
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_x$ mm <sup>4</sup>		22,2x10 <sup>5</sup>		63,8x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		122,0x10 <sup>5</sup>		335x10 <sup>5</sup>	
Elastic modulus N/mm <sup>2</sup>		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

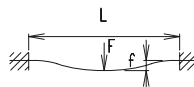
$$P_o = \frac{M_o \cdot n}{9550}$$

$F$  = force (N)  
 $P$  = pulley action perimeter (mm)  
 $S_i$  = safety factor 1,2 ... 2  
 $M_n$  = no-load torque (Nm)  
 $n$  = rpm pulley (min<sup>-1</sup>)  
 $M_o$  = driving torque (Nm)  
 $P_o$  = motor power (KW)

Deflection:

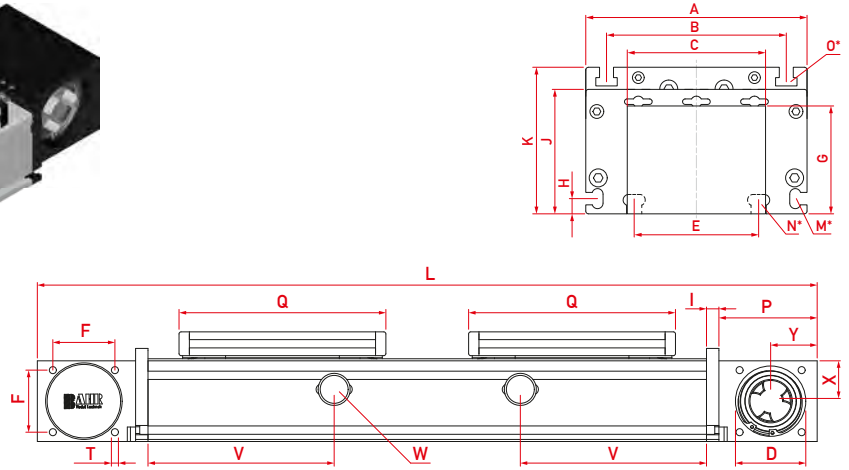
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

$f$  = deflection (mm)  
 $F$  = load (N)  
 $L$  = free length (mm)  
 $E$  = elastic modulus 70000 (N/mm<sup>2</sup>)  
 $I$  = second moment of area (mm<sup>4</sup>)



# Linear system **DLZZ 160, 200**

Dimensions (mm)



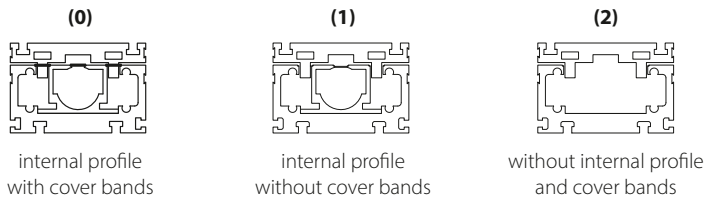
$V = Q + 100 \text{ mm}$       $W = \text{servicing position}$

\*For slide nuts refer to chapter 2.2 page 2

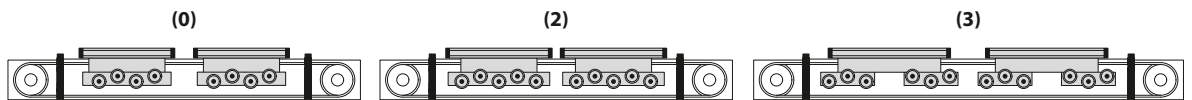
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D	E	F	G	H	I	J	K	M for	N for	O for	P	Q	T	X	Y	Basic weight	Weight per 100 mm
DLZZ 160	615	160	130	121	68	90	60	78	11	12	90	106	M6	M8	M8	95	200	M8	39	45	16,0 kg	1,69 kg
DLZZ 200	790	200	160	150	90	140	80	97	15	15	110	129	M8	M10	M10	110	270	M10	49	50	28,50 kg	2,33 kg

**0 Choice of guide body profile:** Stainless versions upon request.

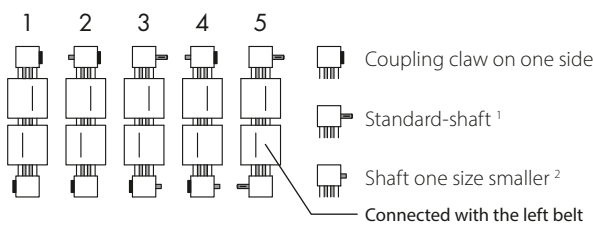


**0 Choice of carriage:**



Size	Version 0		Version 2		Version 3	
	Q	L	Q	L	Q	L
160	200	615	250	715	300	830
200	270	790	330	910	410	1070

**0 Drive version:**



**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 6	160	8M 20	176	22
0 7	200	8M 30	224	28

**Shaft dimensions / Coupling claw:**

Size	Shaft $\phi h6 \times \text{length}$	Key	Coupling
DLZZ 160 <sup>1</sup>	$\phi 18 \times 45$	6x6x35	19
DLZZ 160 <sup>2</sup>	$\phi 14 \times 35$	5x5x28	19
DLZZ 200 <sup>1</sup>	$\phi 22 \times 45$	6x6x40	24
DLZZ 200 <sup>2</sup>	$\phi 18 \times 45$	6x6x40	24

**DLZZ 200 4 0 0 2 0 7 1 1500** — Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

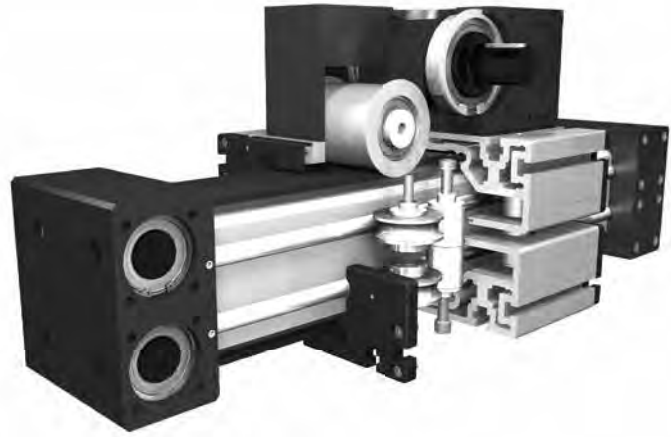
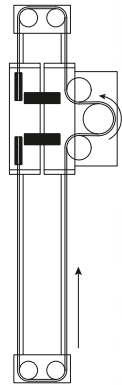
DLZZ 200 with internal profile and cover bands, carriage version 0, drive version 2, 710 mm stroke.

# Linear system **ELFZ 60S, 80S, 100, 125**

## BELT DRIVE

-  PULLEY PRINCIPLE
-  VERTICAL INSTALLATION POSITION

3.1



**Function:**

This special lifting unit consists of an aluminium square profile with hardened steel guide rods. The carriages, which have internal linear ball bearings that can be adjusted free of play, are driven along the guide rods by a timing belt. The rotating timing belt pulleys have maintenance-free ball bearings. One rotation of the drive pulley complies with 1/2 linear circumference of the drive pulley. Belt tension can be readjusted by a simple tensioning device in one of the carriages. This device can also be used for symmetrical adjustment of two or more linear units running parallel.

**Fitting position:**

As required. Max. length without joints 6.000 mm.

**Carriage mounting:**

By T-slots.

**Unit mounting:**

By T-slots or tapped holes in the bearing blocks, or mounting sets.

**Belt type:**

HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.

Forces and torques	Size	ELFZ 60S		ELFZ 80S		ELFZ 100		ELFZ 125	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic
	F <sub>x</sub> (N)	3600	3200	6200	5400	8700	7600	12000	10400
	F <sub>y</sub> (N)	8200	6200	9200	7200	16000	13000	24000	18000
	F <sub>z</sub> (N)	4320	3200	6000	3600	7200	4400	12000	9000
	M <sub>x</sub> (Nm)	176	130	340	280	600	460	1200	900
	M <sub>y</sub> (Nm)	380	280	540	460	800	540	1500	1200
	M <sub>z</sub> (Nm)	460	340	600	440	1500	1000	2700	2300
<b>All forces and torques relate to the following:</b>									
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$									
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$									
<b>No-load torque</b>									
Nm		1,3		1,5		2		2	
<b>Speed</b>									
(m/s) max		4		4		4		4	
<b>Drive torque</b>									
max (Nm)		48		120		386		500	
<b>Geometrical moments of inertia of aluminium profile</b>									
I <sub>x</sub> mm <sup>4</sup>		6,79x10 <sup>5</sup>		1,89x10 <sup>6</sup>		4,44x10 <sup>6</sup>		10,15x10 <sup>6</sup>	
I <sub>y</sub> mm <sup>4</sup>		6,9710 <sup>5</sup>		1,8910 <sup>6</sup>		4,48x10 <sup>6</sup>		10,15x10 <sup>6</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000		70000		70000	

*For life-time calculation of rollers use our homepage.*

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi \cdot 2} + M_n$$

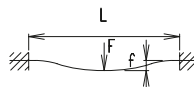
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

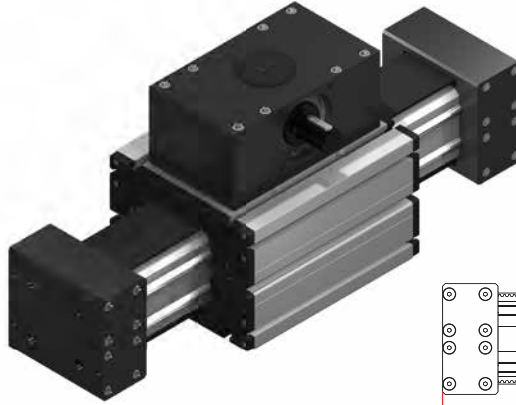
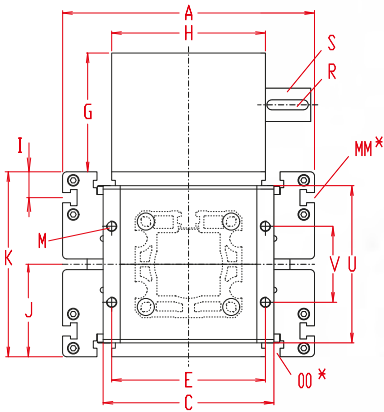
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)

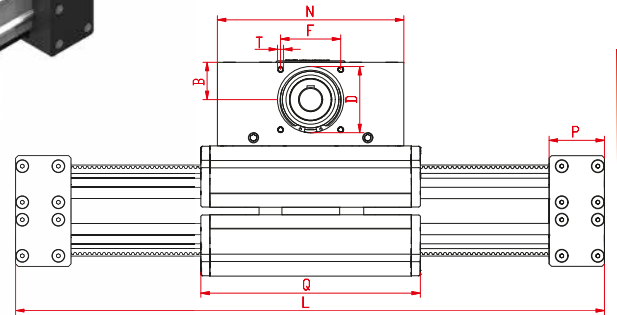


# Linear system **ELFZ 60S, 80S, 100, 125**

Dimensions (mm)



Functional principle on page 3.1 | 40



3.1

\*For slide nuts refer to chapter 2.2 page 2

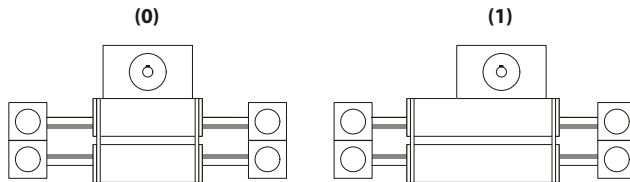
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	I	J	K	MM for	M	N	OO for	P	Q	R	S	T	U	V	Basic weight	Weight per 100 mm
<b>ELFZ 60S</b>	410	170	38	108	68	97	60	102	100	-	53	106	-	M8	180	M8	97	214	6x6x40	18x45	M8	97	60	23,1 kg	0,64 kg
<b>ELFZ 80S</b>	580	190	60	154	90	135	80	139	130	12,5	71	142	M6	M10	270	M 8	130	315	8x7x40	30x45	M10	130	70	51 kg	1,20 kg
<b>ELFZ 100</b>	530	230	62	170	110	150	100	143	160	29	89	178	M10	M10	310	M10	77	365	12x8x50	40x55	M10	150	80	69 kg	1,80 kg
<b>ELFZ 125</b>	560	295	62	200	110	180	100	139	180	30	107,5	215	M10	M12	310	M12	92	365	12x8x50	40x55	M10	186	89	87,5 kg	2,70 kg

**0 Choice of guide body profile:**

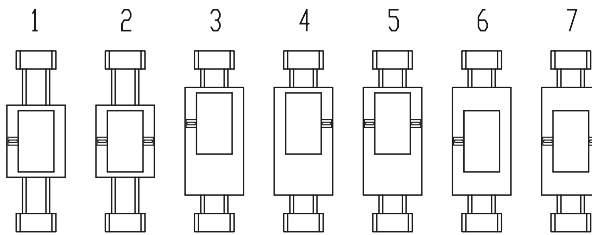
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 1	
	Q	L
<b>60S</b>	380	580
<b>80S</b>	489	750
<b>100</b>	575	740
<b>125</b>	640	830

**1 Drive version:**



**Belt table:**

Code No.	Size	Belt	mm/rev. ≈ linear	Number of teeth
<b>0 3</b>	<b>60S</b>	8M30	192 ≈ 96	24
<b>0 4</b>	<b>80S</b>	8M50	256 ≈ 128	32
<b>0 7</b>	<b>100</b>	8M70	304 ≈ 152	38
<b>0 9</b>	<b>125</b>	8M100	304 ≈ 152	38

**Shaft dimensions:**

Size	Shaft ø h6 x length	Key
<b>60S</b>	18 x 45	6x6x40
<b>80S</b>	30 x 45	8x7x40
<b>100</b>	40 x 55	12x8x50
<b>125</b>	40 x 55	12x8x50

**ELFZ 125 0 0 0 1 0 9 1 1500**

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7




Sample ordering code:

ELFZ 125 with standard body profile, standard carriage, shaft Pos. 1, 940 mm stroke

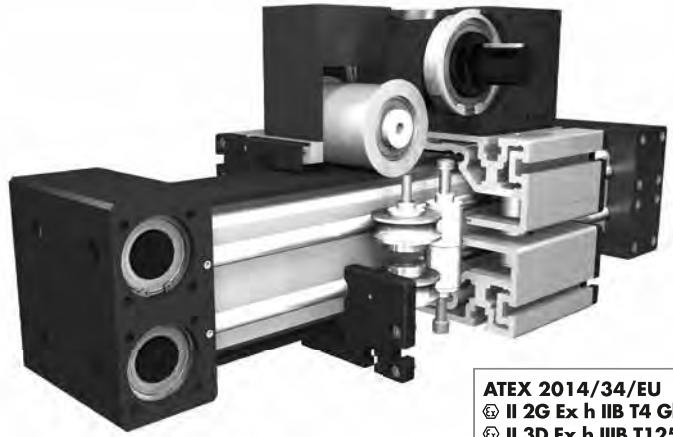
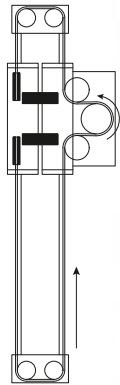
For combination kits and connecting elements refer to chapter 2.2



# Linear system **ELFZ** **60S, 80S, 100, 125**

## BELT DRIVE - EX GUIDE

-  PULLEY PRINCIPLE
-  VERTICAL INSTALLATION POSITION
-  EX-GUIDE

3.1



**ATEX 2014/34/EU**  
 **II 2G Ex h IIB T4 Gb**  
 **II 3D Ex h IIB T125 °C Dc**

**Function:**

Special lifting system with roll guides outside of profile. System is driven by one rotating timing belt with one drive. The function corresponds to a simple pulley block. The positioning system is suitable for use according to the intended purpose in potentially explosive areas (see ATEX 95 marking). An operating manual is included in the scope of delivery. The system is certified for the following areas:

**ATEX 2014/34/EU**

**II 2G Ex h IIB T4 Gb:**

All application areas except for underground mining. Gas atmosphere category 2, explosion protection category: protection due to secure construction (design security). Equipment group IIB. Temperature class T4=135 °C

**ATEX 2014/34/EU**

**II 3D Ex h IIB T125 °C Dc:**

All application areas except for underground mining. Dust atmosphere category 3. Maximum permissible surface temperature: 125 °C.

**Fitting position:**

As required. Max. length without joints 3.000 mm.

**Carriage mounting:**

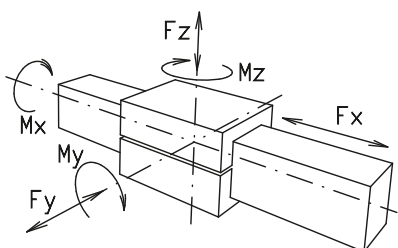
By T-slots.

**Unit mounting:**

By T-slots or tapped holes in the bearing blocks, or mounting sets.

**Belt type:**

HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.

Forces and torques	Size	ELFZex 60S		ELFZex 80S		ELFZex 100		ELFZex 125	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic
	F <sub>x</sub> (N)	1800	1550	3000	2600	4200	3650	6000	5200
	F <sub>y</sub> (N)	3820	3056	4438	3550	6200	4960	9960	7968
	F <sub>z</sub> (N)	1870	1496	1052	842	1292	1043	2190	1752
	M <sub>x</sub> (Nm)	104	82	134	108	202	162	440	352
	M <sub>y</sub> (Nm)	132	106	154	140	272	218	560	448
	M <sub>z</sub> (Nm)	274	220	364	292	652	520	1272	1018
	<b>All forces and torques relate to the following:</b> existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$ table values								
<b>No-load torque</b>									
Nm		1,2		1,5		2		2	
<b>Speed</b>									
(m/s) max		1		1		1		1	
<b>Drive torque</b>									
max (Nm)		27		62		101		145	
<b>Geometrical moments of inertia of aluminium profile</b>									
I <sub>x</sub> mm <sup>4</sup>		6,79x10 <sup>5</sup>		1,89x10 <sup>6</sup>		4,44x10 <sup>6</sup>		10,15x10 <sup>6</sup>	
I <sub>y</sub> mm <sup>4</sup>		6,97x10 <sup>5</sup>		1,89x10 <sup>6</sup>		4,48x10 <sup>6</sup>		10,15x10 <sup>6</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000		70000		70000	

*For life-time calculation of rollers use our homepage.*

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi \cdot 2} + M_n$$

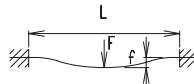
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

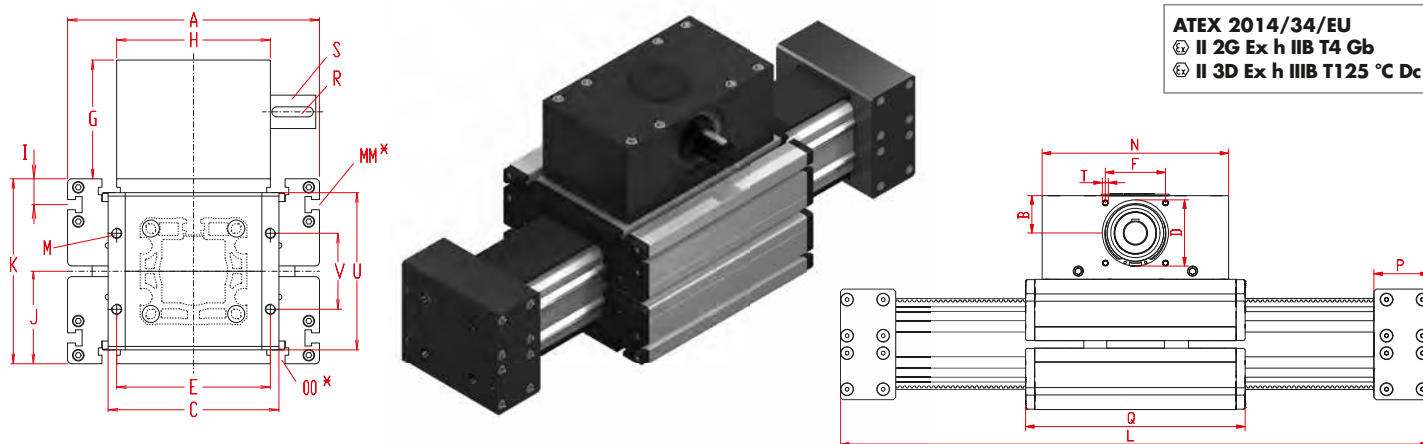
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Linear system **ELFZ** **60S, 80S, 100, 125**

Dimensions (mm)



3.1

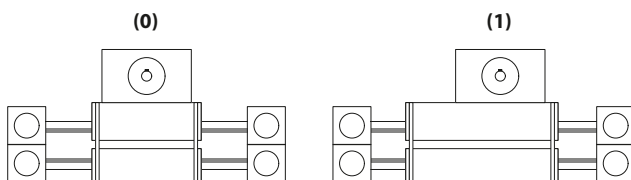
\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	I	J	K	MM for	M	N	OO for	P	Q	R	S	T	U	V	Basic weight	Weight per 100 mm
<b>ELFZex 60S</b>	430	170	38	108	68	97	60	102	100	-	53	106	-	M8	180	M8	97	214	6x6x40	18x45	M8	97	60	23,2 kg	0,64 kg
<b>ELFZex 80S</b>	600	190	60	154	90	135	80	139	130	12,5	71	142	M6	M10	270	M 8	130	315	8x7x40	30x45	M10	130	70	51 kg	1,20 kg
<b>ELFZex 100</b>	560	230	62	170	110	150	100	143	160	29	89	178	M10	M10	310	M10	77	365	12x8x50	40x55	M10	150	80	69 kg	1,80 kg
<b>ELFZex 125</b>	590	295	62	200	110	180	100	139	180	30	107,5	215	M10	M12	310	M12	92	365	12x8x50	40x55	M10	186	89	87,5 kg	2,70 kg

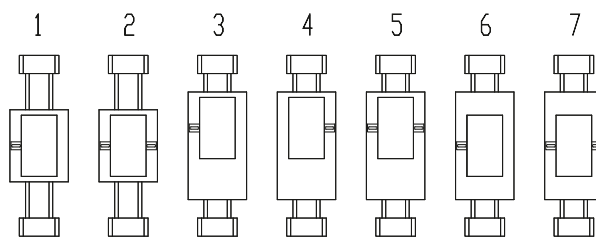
**0** Choice of guide body profile:  
(0) Standard (2) corrosion-protected guide rods and screws

**0** Choice of carriages:



Size	Version 1	
	Q	L
<b>60S</b>	380	600
<b>80S</b>	489	770
<b>100</b>	575	770
<b>125</b>	640	860

**1** Drive version:



**Belt table:**

Code No.	Size	Belt	mm/rev. ≈ linear	Number of teeth
<b>0 3</b>	<b>60S</b>	8M30	192 ≈ 96	24
<b>0 4</b>	<b>80S</b>	8M50	256 ≈ 128	32
<b>0 7</b>	<b>100</b>	8M70	304 ≈ 152	38
<b>0 9</b>	<b>125</b>	8M100	304 ≈ 152	38

**Shaft dimensions:**

Size	Shaft ø h6 x length	Key
<b>60S</b>	18 x 45	6x6x40
<b>80S</b>	30 x 45	8x7x40
<b>100</b>	40 x 55	12x8x50
<b>125</b>	40 x 55	12x8x50

**ELFZEX125 0 0 0 1 0 9 1 1500**

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7




Sample ordering code:

ELFZ 125 with standard body profile, standard carriage, shaft Pos. 1, 910 mm stroke

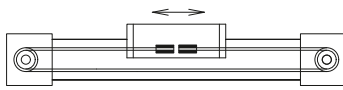
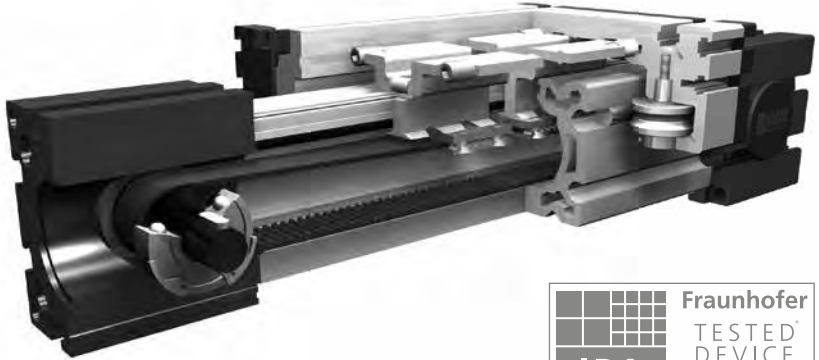
For combination kits and connecting elements refer to chapter 2.2

# Linear system **ELHZ 60, 60S, 80, 80S, 100, 125**

## INTERNAL BELT DRIVE

-  CLEAN ROOM
-  TOOTHED BELT HORIZONTAL
-  HIGH DYNAMICS

3.1



**Function:**

This linear unit consists of an aluminium square profile with integrated, hardened steel guide rods. The carriage, which has internal linear ball bearings that can be adjusted free of play, is driven along the guide rods by a timing belt. Toothed pulley has maintenance-free ball bearings. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel.

**This linear unit is suitable for application in clean rooms of clean-room classification 1.000 (corresponding to US Fed. Standard 209 E).**

- Fitting position:** As required. Max. length 3.000 mm.
- Carriage mounting:** By T-slots.
- Unit mounting:** By tapped holes or tapped holes in the bearing block, mounting sets.
- Belt type:** HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.

Forces and torques	Size	ELHZ 60		ELHZ 60 S		ELHZ 80		ELHZ 80 S		ELHZ 100		ELHZ 125	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
$F_x$ (N)	700	580	700	580	1000	840	1000	840	3100	2600	5000	4950	
$F_y$ (N)	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500	12000	9000	
$F_z$ (N)	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200	6000	4500	
$M_x$ (Nm)	67	43	88	65	90	55	170	140	300	230	600	450	
$M_y$ (Nm)	90	70	190	140	110	80	270	230	400	270	750	600	
$M_z$ (Nm)	120	100	230	170	150	120	300	220	750	500	1350	1150	

**All forces and torques relate to the following:**

existing values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

table values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

No-load torque							
Nm	0,5	0,5	0,8	1,2	1,2	1,6	
Speed							
(m/s) max	3	4	4	4	5	6	
Tensile force							
permanent (N)	700	700	1000	1000	3100	5000	
0,2 s (N)	800	800	1150	1150	3400	5450	
Geometrical moments of inertia of aluminium profile							
$I_x$ mm <sup>4</sup>	6,79x10 <sup>5</sup>	6,79x10 <sup>5</sup>	18,99x10 <sup>5</sup>	18,99x10 <sup>5</sup>	44,4x10 <sup>5</sup>	101,5x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>	6,97x10 <sup>5</sup>	6,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	44,8x10 <sup>5</sup>	101,5x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>	70000	70000	70000	70000	70000	70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

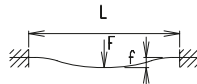
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

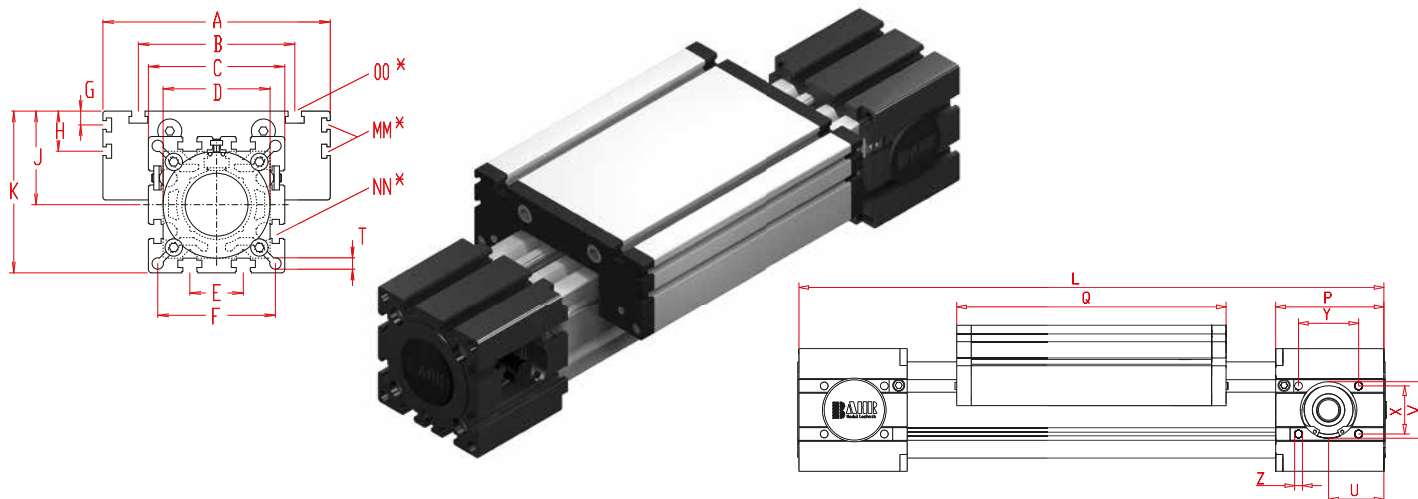
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Linear system **ELHZ 60, 60S, 80, 80S, 100, 125**

Dimensions (mm)



\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

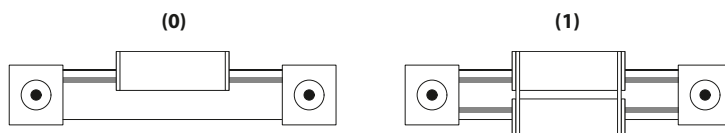
Size □	Basic length L	A	B	C	D ±0,05	E	F	G	H	J	K	MM for	NN for	OO for	P	Q	T	U	V -0,05	W'	X	Y	Z	Basic weight	Weight per 100 mm
ELHZ 60	290	144	96	82	62x1	30	69	--	-	49	90	-	M 8	M 8	59	168	8,5	23	37	14	30	36	M 6	4,8 kg	0,62 kg
ELHZ 60S	315	170	108	82	62x1	30	69	--	-	53	94	-	M 8	M 8	59	194	8,5	23	37	14	30	36	M 6	5,8 kg	0,62 kg
ELHZ 80	375	170	117	102	80x1	40	88	10,5	30,5	70	121	M 6	M10	M10	90	194	8,5	38	47	18	40	50	M 8	10,0 kg	1,00 kg
ELHZ 80S	395	190	126	102	80x1	40	88	12,5	30	71	122	M 6	M10	M 8	90	214	8,5	38	47	18	40	50	M 8	11,0 kg	1,00 kg
ELHZ 100	530	230	155	130	110x1	50	112	-	29	89	154	M10	M10	M10	110	300	10,5	45	68	19	50	64	M10	24,0 kg	1,60 kg
ELHZ 125	630	295	200	165	130x2	60	142	-	30	107,5	190	M10	M10	M12	130	365	13,0	58	90	35	60	85	M10	37,0 kg	2,10 kg

W' = standard shaft

**0 Choice of guide body profile:**

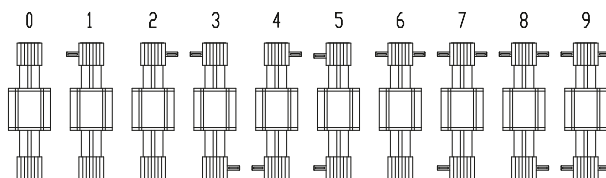
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 1	
	Q	L
60	184	306
60S	214	336
80	210	391
80S	234	415
100	316	546
125	389	649

**0 Drive version:**



The standard version 0 is supplied with 4 flush mounted shafts.

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	60 (S)	5M 25	80	16
0 4	80 (S)	5M 25	110	22
0 9	100	8M 48	144	18
0 9	125	8M 50	192	24

**Shaft dimensions:**

Size	Shaft ø h6 x length	Key
60 (S)	14 x 35	5x5x28
80 (S)	18 x 45	6x6x40
100	22 x 45	6x6x40
125	30 x 55	8x7x50

**ELHZ 60 0 0 0 0 0 4 1 1500**

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

ELHZ 60, with standard body profile, standard carriage and 4 flush mounted shafts, 1210 mm stroke.

For combination kits and connecting elements refer to chapter 2.2

3.1



# Linear system **ELSD 40, 60, 60S, 80, 80S, 100**

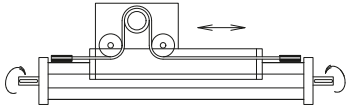
## BELT DRIVE WITH ROTARY SHAFT

Ω OMEGA SYSTEM

⊥ VERTICAL INSTALLATION POSITION

⤴ GRIPPER ADAPTATION

↻ ROTATIONAL MOVEMENT



### Function:

Same as ELSZ, but with an additional rotary shaft, fitted within the aluminium body. One end can be driven by any suitable motor, and the other end is provided with a shaft with feather key and an axial tapped hole for fitting grippers or other components.

### Fitting position:

As required. Max. length 2.000 mm.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots or tapped holes in the bearing blocks, mounting sets.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.

Forces and torques	Size	ELSD 40		ELSD 60		ELSD 60 S		ELSD 80		ELSD 80 S		ELSD 100	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
$F_x$ (N)		390	350	894	800	894	800	1900	1800	1900	1800	4000	3800
$F_y$ (N)		1200	700	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500
$F_z$ (N)		900	650	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200
$F_D$ (N)		50		150		150		250		250		400	
$M_x$ (Nm)		25	20	67	43	88	65	90	55	170	140	300	230
$M_y$ (Nm)		32	18	90	70	190	140	110	80	270	230	400	270
$M_z$ (Nm)		35	25	120	100	230	170	150	120	300	220	750	500
$M_s$ (Nm)		5		10		10		20		20		30	
<b>All forces and torques relate to the following:</b>													
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$													
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$													
<b>No-load torque</b>													
Nm		0,7		0,9		0,9		1,1		1,2		1,5	
Stiction torque $M_B$ (Nm)		0,2		0,4		0,5		0,6		0,7		0,8	
<b>Speed</b>													
(m/s) max		4		5		7		6		8		8	
<b>Tensile force</b>													
permanent (N)		390		900		900		1900		1900		4000	
0,2 s (N)		480		1000		1000		2090		2090		4300	
<b>Geometrical moments of inertia of aluminium profile</b>													
$I_x$ mm <sup>4</sup>		1,32x10 <sup>5</sup>		6,79x10 <sup>5</sup>		6,79x10 <sup>5</sup>		18,99x10 <sup>5</sup>		18,99x10 <sup>5</sup>		44,4x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		1,34x10 <sup>5</sup>		6,97x10 <sup>5</sup>		6,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		44,8x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000		70000		70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

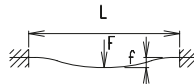
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

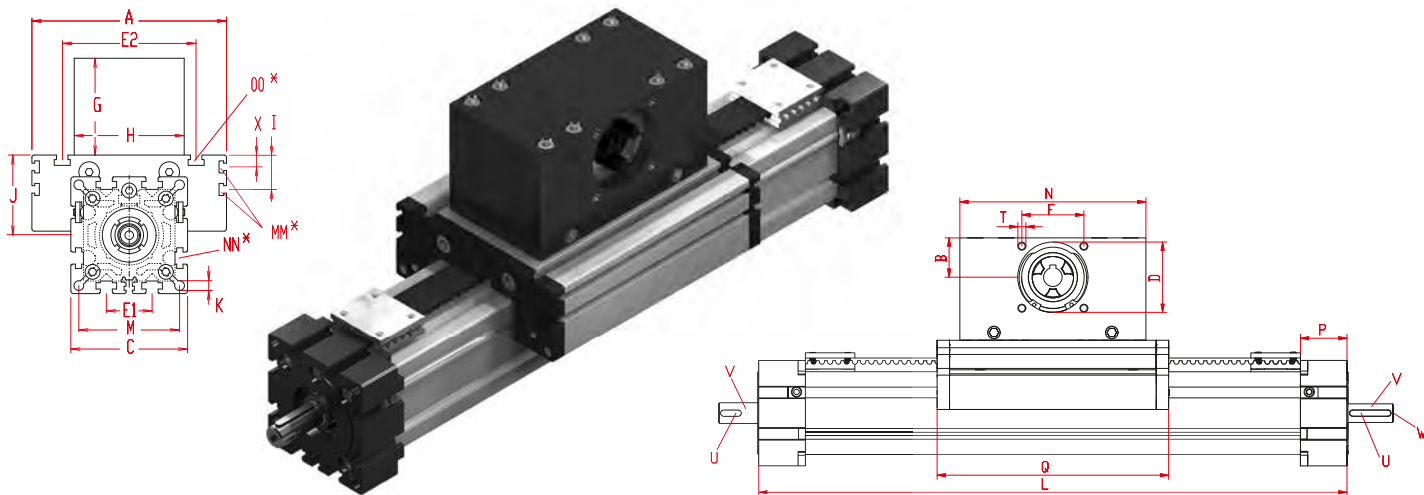
f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **ELSD 40, 60, 60S, 80, 80S, 100**

Dimensions (mm)

3.1



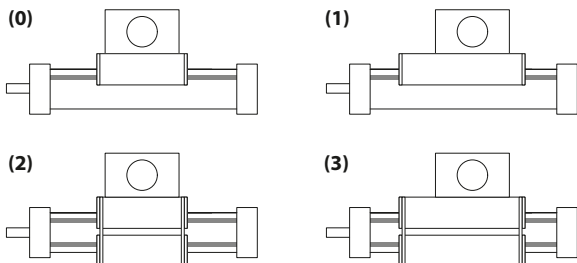
\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

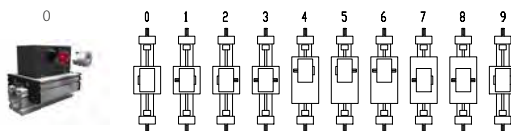
Size □	Basic length L	A	B	C	D <sub>-0,05</sub>	E1	E2	F	G	H	I	J	K	M	MM for	N	NN for	OO for	P	Q	T	X	Basic weight	Weight per 100 mm
ELSD 40	260	100	20	58	37	25	66	32	65	60	-	35	6,5	47	-	110	M 6	M 6	25	142	M 5	-	2,4 kg	0,40 kg
ELSD 60	320	144	30	82	47	30	96	42	80	80	-	49	8,5	69	-	130	M 8	M 8	35	168	M 6	-	5,9 kg	0,87 kg
ELSD 60S	345	170	30	82	47	30	108	42	80	80	-	53	8,5	69	-	130	M 8	M 8	35	194	M 6	-	6,9 kg	0,87 kg
ELSD 80	415	170	38	102	68	40	117	60	99	100	30,5	70	8,5	88	M 6	180	M 10	M 10	45	214	M 8	10,5	12,5 kg	1,30 kg
ELSD 80S	415	190	38	102	68	40	126	60	99	100	30	71	8,5	88	M 6	180	M 10	M 8	45	214	M 8	12,5	14,0 kg	1,30 kg
ELSD 100	585	230	60	130	90	50	155	80	130	130	29	89	10,5	112	M10	270	M 10	M 10	55	310	M 10	-	27,0 kg	1,70 kg

- 0 Choice of guide body profile:**  
 (0) Standard (2) corrosion-protected guide rods and screws  
 (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



**0 Drive version:**



**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 3	40	5M15	100	20
0 4	60 (S)	5M25	130	26
0 7	80 (S)	8M30	192	24
0 9	100	8M50	256	32

Size □	Shaft (drive end)		Shaft (load end)		
	Shaft ø h6 x length (V)	Key (U)	Shaft ø h6 x length (V)	Key (U)	Thread (W)
40	10 x 20	3x3x10	12 x 20	4x4x10	M 6 x 12
60 (S)	14 x 25	5x5x20	17 x 25	5x5x20	M 8 x 20
80 (S)	18 x 30	6x6x20	20 x 30	6x6x20	M 10 x 20
100	22 x 35	6x6x30	25 x 35	8x7x30	M 12 x 25

Size	Version 1		Version 2		Version 3	
	Q	L	Q	L	Q	L
40	237	355	160	276	253	371
60	303	453	184	336	319	469
60S	329	469	214	365	349	489
80	379	575	230	431	395	591
80S	399	595	245	450	419	615
100	535	810	326	601	551	826

The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 100).

Version 9 is the same as 0, but with double sided coupling claw.

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
40	10 x 27	3x3x25	9
60 (S)	14 x 35	5x5x28	14
80 (S)	18 x 45	6x6x40	19
100	22 x 45	6x6x40	24

**ELSD 60 0 0 0 0 0 4 1 1500** Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

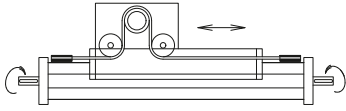
ELSD 60 with standard body profile, standard carriage and coupling claw on one side, 1180 mm stroke

For combination kits and connecting elements refer to chapter 2.2

# Linear system **ELSD 40, 60, 60S, 80, 80S, 100**

## BELT DRIVE WITH WIDENED BELT AND ROTARY SHAFT

- Ω OMEGA SYSTEM
- ✓ BELT WIDENING
- ✎ GRIPPER ADAPTATION
- ↻ ROTATIONAL MOVEMENT



### Function:

Same as ELSZ, but with an additional rotary shaft, fitted within the aluminium body. One end can be driven by any suitable motor, and the other end is provided with a shaft with feather key and an axial tapped hole for fitting grippers or other components.

### Fitting position:

As required. Max. length 2.000 mm.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots or tapped holes in the bearing blocks, mounting sets.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

Forces and torques	Size	ELSD 40		ELSD 60		ELSD 60 S		ELSD 80		ELSD 80 S		ELSD 100		
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	
	$F_x$ (N)	894	800	1900	1800	1900	1800	4000	3800	4000	3800	5900	5750	
	$F_y$ (N)	1200	700	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500	
	$F_z$ (N)	900	650	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200	
	$F_p$ (N)	50		150		150		250		250		400		
	$M_x$ (Nm)	25	20	67	43	88	65	90	55	170	140	300	230	
	$M_y$ (Nm)	32	18	90	70	190	140	110	80	270	230	400	270	
	$M_z$ (Nm)	35	25	120	100	230	170	150	120	300	220	750	500	
	$M_R$ (Nm)	5		10		10		20		20		30		
	<b>All forces and torques relate to the following:</b>													
	existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$													
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$														
<b>No-load torque</b>														
Nm	0,7		0,9		0,9		1,1		1,2		1,5			
Stiction torque $M_R$ (Nm)	0,2		0,4		0,5		0,6		0,7		0,8			
<b>Speed</b>														
(m/s) max	4		5		7		6		8		8			
<b>Tensile force</b>														
permanent (N)	900		1900		1900		4000		4000		5900			
0,2 s (N)	1000		2090		2090		4300		4300		6350			
<b>Geometrical moments of inertia of aluminium profile</b>														
$I_x$ mm <sup>4</sup>	1,32x10 <sup>5</sup>		6,79x10 <sup>5</sup>		6,79x10 <sup>5</sup>		18,99x10 <sup>5</sup>		18,99x10 <sup>5</sup>		44,4x10 <sup>5</sup>			
$I_y$ mm <sup>4</sup>	1,34x10 <sup>5</sup>		6,97x10 <sup>5</sup>		6,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		44,8x10 <sup>5</sup>			
E-Modulus N/mm <sup>2</sup>	70000		70000		70000		70000		70000		70000			

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

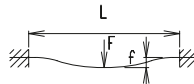
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 Si = safety factor 1,2 ... 2  
 Mn = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 Mo = driving torque (Nm)  
 Po = motor power (KW)

Deflection:

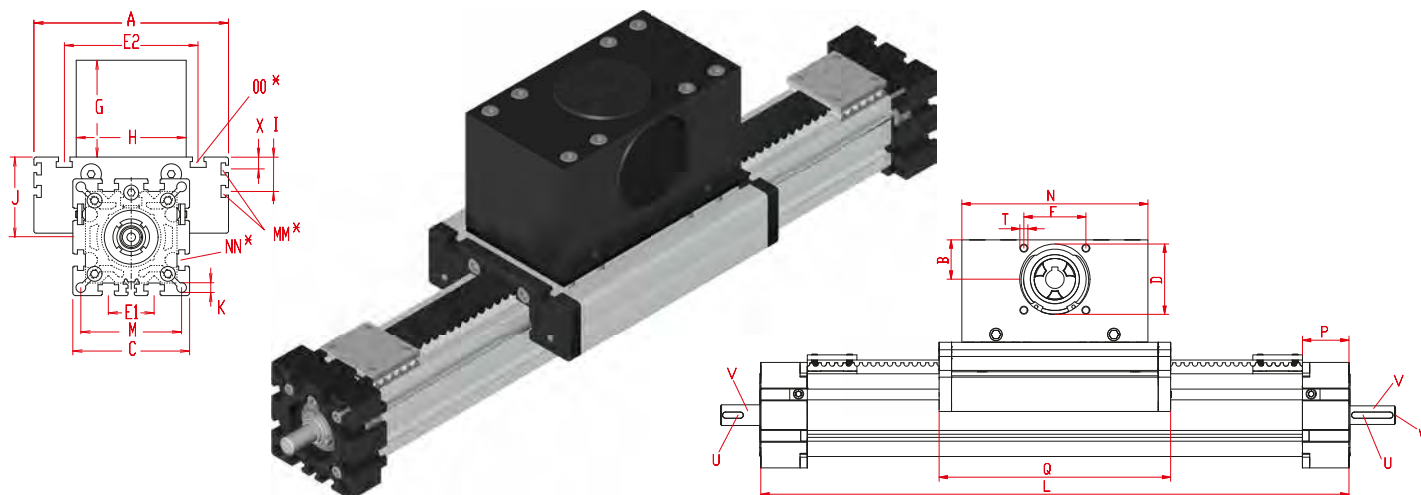
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **ELSD 40, 60, 60S, 80, 80S, 100**

Dimensions (mm)



\*For slide-nuts refer to chapter 2.2 page 2

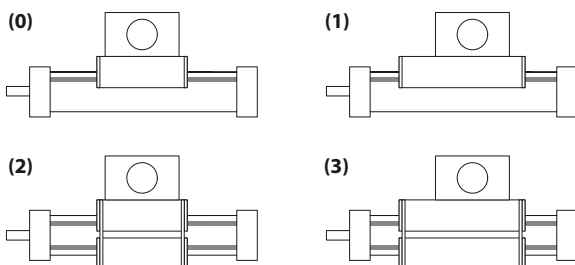
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D <sub>-0,05</sub>	E1	E2	F	G	H	I	J	K	M	MM for	N	NN for	OO for	P	Q	T	X	Basic weight	Weight per 100 mm
ELSD 40	286	100	30	58	47	25	66	42	83	80	-	35	6,5	47	-	130	M 6	M 6	25	164	M 6	-	2,7 kg	0,40 kg
ELSD 60	395	144	38	82	68	30	96	60	104	100	-	49	8,5	69	-	180	M 8	M 8	35	214	M 8	-	6,5 kg	0,87 kg
ELSD 60S	395	170	38	82	68	30	108	60	102	100	-	53	8,5	69	-	180	M 8	M 8	35	214	M 8	-	7,5 kg	0,87 kg
ELSD 80	510	170	60	102	90	40	117	80	140	130	30,5	70	8,5	88	M 6	270	M 10	M 10	45	304	M 10	10,5	13,7 kg	1,30 kg
ELSD 80S	510	190	60	102	90	40	126	80	138,4	130	30	71	8,5	88	M 6	270	M 10	M 8	45	304	M 10	12,5	15,2 kg	1,30 kg
ELSD 100	625	230	62	130	110	50	155	100	143	160	29	89	10,5	112	M10	310	M 10	M 10	55	350	M 10	-	33,4 kg	1,70 kg

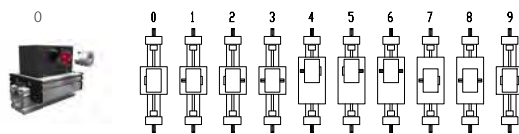
## 0 Choice of guide body profile:

- (0) Standard (2) corrosion-protected guide rods and screws  
 (4) expanded corrosion-protected version  
 (depending on the availability of components)

## 0 Choice of carriages:



## 0 Drive version:



## Belt table:

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	40	5M25	130	26
0 7	60 (S)	8M30	192	24
0 9	80 (S)	8M50	256	32
1 0	100	8M70	304	38

Size	Shaft (drive end)		Shaft (load end)		
	Shaft ø h6 x length (V)	Key (U)	Shaft ø h6 x length (V)	Key (U)	Thread (W)
40	10 x 20	3x3x10	12 x 20	4x4x10	M 6 x 12
60 (S)	14 x 25	5x5x20	17 x 25	5x5x20	M 8 x 20
80 (S)	18 x 30	6x6x20	20 x 30	6x6x20	M 10 x 20
100	22 x 35	6x6x30	25 x 35	8x7x30	M 12 x 25

Size	Version 1		Version 2		Version 3	
	Q	L	Q	L	Q	L
40	257	381	180	302	273	397
60	353	534	230	411	369	550
60S	379	560	234	415	399	580
80	469	675	320	526	485	691
80S	489	695	324	530	509	715
100	575	850	366	641	591	866

The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 80 + 100).

Version 9 is the same as 0, but with double sided coupling claw.

## Shaft dimensions / Coupling claw:

Size	Shaft ø h6 x length	Key	Coupling
40	14 x 35	5x5x28	14
60 (S)	18 x 45	6x6x40	19
80 (S)	22 x 45	6x6x40	24
100	30 x 55	8x7x40	28

**ELSD 60 0 0 0 0 0 7 1 1500** Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

ELSD 60 with standard body profile, standard carriage and coupling claw on one side, 1146 mm stroke

For combination kits and connecting elements refer to chapter 2.2

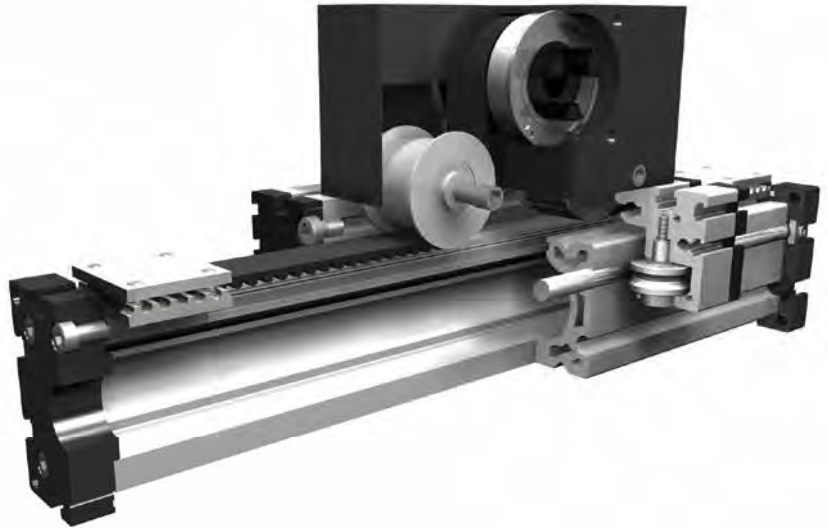
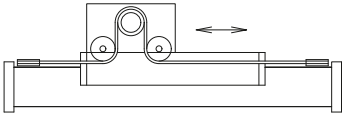
# Linear system **ELSZ 30, 40, 60, 60S, 80, 80S, 100, 125**

## WITH STANDARD BELT

### Ω OMEGA SYSTEM

### VERTICAL INSTALLATION POSITION

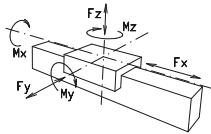
3.1



#### Function:

This linear unit consists of an aluminium square profile with hardened steel guide rods. The carriage, which has internal linear ball bearings that can be adjusted free of play, is driven along the guide rods by a timing belt. The pulley has maintenance-free ball bearings. Belt tension can be readjusted by a simple tensioning device in one of the end blocks. This device can also be used for symmetrical adjustment of two or more linear units running parallel.

#### Forces and torques



**Fitting position:** As required. Max. length without joints 6.000 mm.

**Carriage mounting:** By T-slots.

**Unit mounting:** By T-slots or tapped holes in the bearing blocks, or mounting sets.

**Belt type:** HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

Size	ELSZ 30		ELSZ 40		ELSZ 60		ELSZ 60 S		ELSZ 80		ELSZ 80 S		ELSZ 100		ELSZ 125	
Forces/Torques	static	dynam.	static	dynam.	static	dynam.	static	dynam.	static	dynam.	static	dynam.	static	dynam.	static	dynam.
$F_x$ (N)	200	180	390	350	894	800	894	800	1900	1800	1900	1800	4000	3800	5900	5750
$F_y$ (N)	90	60	1200	700	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500	12000	9000
$F_z$ (N)	90	60	900	650	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200	6000	4500
$M_x$ (Nm)	10	5	25	20	67	43	88	65	90	55	170	140	300	230	600	450
$M_y$ (Nm)	13	6	32	18	90	70	190	140	110	80	270	230	400	270	750	600
$M_z$ (Nm)	14	7	35	25	120	100	230	170	150	120	300	220	750	500	1350	1150

**All forces and torques relate to the following:**

existing values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

table values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

No-load torque	ELSZ 30		ELSZ 40		ELSZ 60		ELSZ 60 S		ELSZ 80		ELSZ 80 S		ELSZ 100		ELSZ 125	
Nm	0,2	0,2	0,7	0,7	0,9	0,9	0,9	0,9	1,1	1,1	1,2	1,2	1,5	1,5	1,8	1,8
<b>Speed</b>																
(m/s) max	2	2	4	4	5	5	5	5	6	6	8	8	8	8	10	10
<b>Tensile force</b>																
permanent (N)	200	200	390	390	900	900	900	900	1900	1900	1900	1900	4000	4000	5900	5900
0,2 s (N)	280	280	480	480	1000	1000	1000	1000	2090	2090	2090	2090	4300	4300	6350	6350
<b>Geometrical moments of inertia of aluminium profile</b>																
$I_x$ mm <sup>4</sup>	4,09x10 <sup>4</sup>	4,09x10 <sup>4</sup>	1,32x10 <sup>5</sup>	1,32x10 <sup>5</sup>	6,79x10 <sup>5</sup>	6,79x10 <sup>5</sup>	6,79x10 <sup>5</sup>	6,79x10 <sup>5</sup>	18,99x10 <sup>5</sup>	18,99x10 <sup>5</sup>	18,99x10 <sup>5</sup>	18,99x10 <sup>5</sup>	44,4x10 <sup>5</sup>	44,4x10 <sup>5</sup>	101,5x10 <sup>5</sup>	101,5x10 <sup>5</sup>
$I_y$ mm <sup>4</sup>	4,00x10 <sup>4</sup>	4,00x10 <sup>4</sup>	1,34x10 <sup>5</sup>	1,34x10 <sup>5</sup>	6,97x10 <sup>5</sup>	6,97x10 <sup>5</sup>	6,97x10 <sup>5</sup>	6,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	44,8x10 <sup>5</sup>	44,8x10 <sup>5</sup>	101,5x10 <sup>5</sup>	101,5x10 <sup>5</sup>
E-Modulus N/mm <sup>2</sup>	70000	70000	70000	70000	70000	70000	70000	70000	70000	70000	70000	70000	70000	70000	70000	70000

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

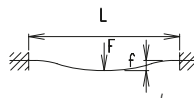
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

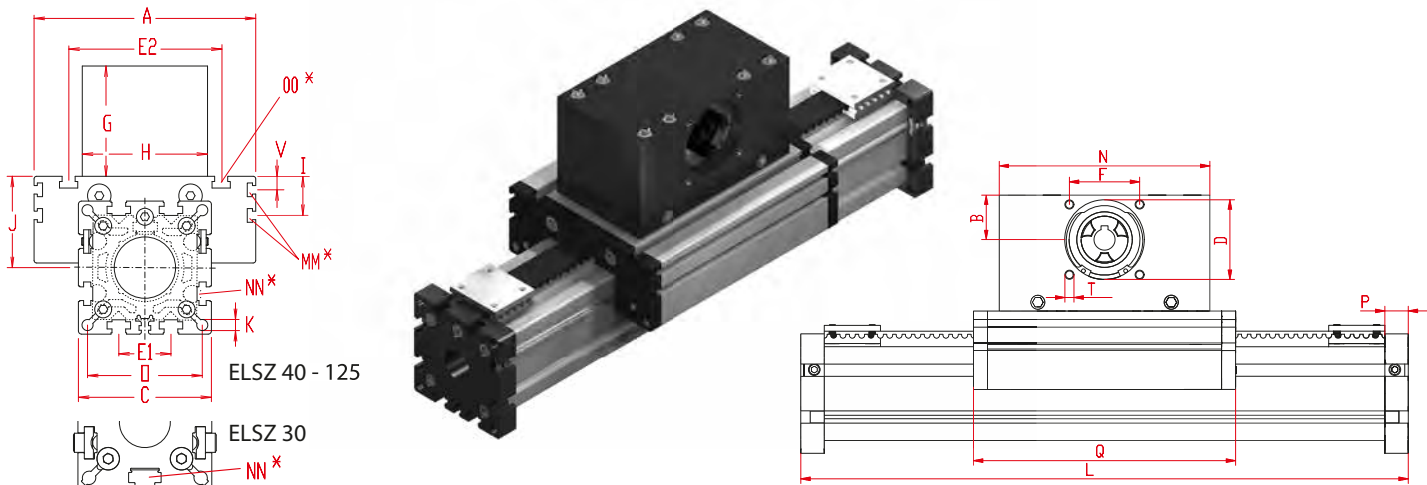
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **ELSZ 30, 40, 60, 60S, 80, 80S, 100, 125**

Dimensions (mm)



3.1

\*For slide nuts refer to chapter 2.2 page 2

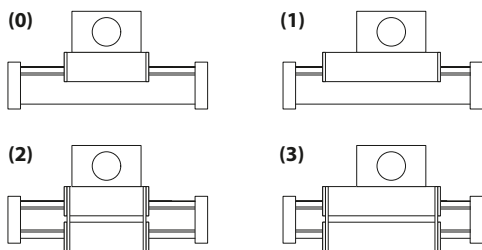
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E1	E2	F	G	H	I	J	K	MM for	N	NN for	O	OO for	P	Q	T	V	Basic weight	Weight per 100 mm
ELSZ 30	182	70	16	42	28	-	56	25	45	42	-	26	4,2	-	90	M 6	35	M 6	12	108	M 4	-	1,33 kg	0,16 kg
ELSZ 40	230	100	20	58	37	25	66	32	65	60	-	35	6,5	-	110	M 6	47	M 6	12	142	M 5	-	2,1 kg	0,24 kg
ELSZ 60	280	144	30	82	47	30	96	42	80	80	-	49	8,5	-	130	M 8	69	M 8	16	168	M 6	-	5,1 kg	0,62 kg
ELSZ 60S	305	170	30	82	47	30	108	42	80	80	-	53	8,5	-	130	M 8	69	M 8	16	194	M 6	-	6,1 kg	0,62 kg
ELSZ 80	365	170	38	102	68	40	117	60	99	100	30,5	70	8,5	M 6	180	M 10	88	M 10	20	214	M 8	10,5	11,0 kg	1,00 kg
ELSZ 80S	365	190	38	102	68	40	126	60	99	100	30	71	8,5	M 6	180	M 8	88	M 8	20	214	M 8	12,5	12,0 Kg	1,00 Kg
ELSZ 100	535	230	60	130	90	50	155	80	130	130	29	89	10,5	M10	270	M 12	112	M 10	30	310	M 10	-	25,8 kg	1,60 kg
ELSZ 125	595	295	62	165	110	60	200	100	139	160	30	107,5	M10	M10	310	M 12	140	M 12	30	365	M 10	-	54,5 kg	1,94 kg

**0 Choice of guide body profile:**

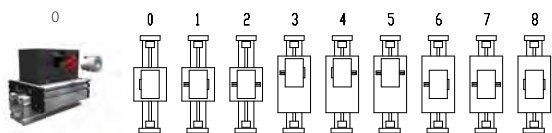
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 1		Version 2		Version 3	
	Q	L	Q	L	Q	L
30	175	245	124	194	197	267
40	237	325	158	246	253	341
60	303	415	184	296	319	431
60S	329	431	214	325	349	451
80	379	525	230	381	395	541
80S	399	545	234	395	419	565
100	535	760	326	551	551	776
125	640	870	389	619	664	894

**0 Drive version:**



Version 8 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 100 + 125).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 1	30	3M12	75	25
0 3	40	5M15	100	20
0 4	60 (S)	5M25	130	26
0 7	80 (S)	8M30	192	24
0 9	100	8M50	256	32
1 0	125	8M70	304	38

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
30	6 x 15	2x2x12	7
40	10 x 27	3x3x25	9
60 (S)	14 x 35	5x5x28	14
80 (S)	18 x 45	6x6x40	19
100	22 x 45	6x6x40	24
125	30 x 55	8x7x50	28

**ELSZ 60 0 0 0 0 0 4 1 1500**

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

ELSZ 60 with standard body profile, standard carriage and coupling claw on one side, 1220 mm stroke.

For combination kits and connecting elements refer to chapter 2.2

# Linear system **ELSZ 30, 40, 60, 60S, 80, 80S, 100, 125**

## WITH WIDENED BELT DRIVE

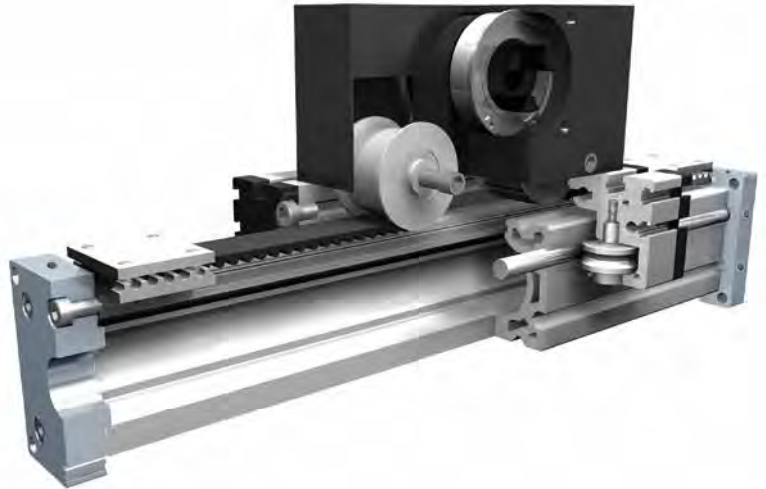
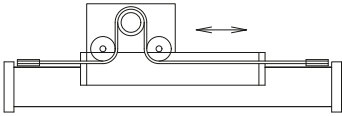
Ω OMEGA SYSTEM

⌈ VERTICAL INSTALLATION POSITION

✓ BELT WIDENING

KG HIGHER FORCE FIXTURE

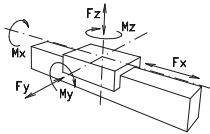
3.1



### Function:

This linear unit consists of an aluminium square profile with hardened steel guide rods. The carriage, which has internal linear ball bearings that can be adjusted free of play, is driven along the guide rods by a timing belt. The pulley has maintenance-free ball bearings. Belt tension can be readjusted by a simple tensioning device in one of the end blocks. This device can also be used for symmetrical adjustment of two or more linear units running parallel.

### Forces and torques



**Fitting position:** As required. Max. length without joints 6.000 mm.

**Carriage mounting:** By T-slots.

**Unit mounting:** By T-slots, threads or tapped holes in the bearing blocks, or mounting sets.

**Belt type:** HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

Size	ELSZ 30		ELSZ 40		ELSZ 60		ELSZ 60 S		ELSZ 80		ELSZ 80 S		ELSZ 100		ELSZ 125	
	static	dynam.	static	dynam.	static	dynam.	static	dynam.	static	dynam.	static	dynam.	static	dynam.	static	dynam.
$F_x$ (N)	390	350	894	800	1900	1800	1900	1800	4000	3800	4000	3800	5900	5750	7900	7500
$F_y$ (N)	90	60	1200	700	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500	12000	9000
$F_z$ (N)	90	60	900	650	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200	6000	4500
$M_x$ (Nm)	10	5	25	20	67	43	88	65	90	55	170	140	300	230	600	450
$M_y$ (Nm)	13	6	32	18	90	70	190	140	110	80	270	230	400	270	750	600
$M_z$ (Nm)	14	7	35	25	120	100	230	170	150	120	300	220	750	500	1350	1150

### All forces and torques relate to the following:

$$\text{existing values} \quad \frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$$

### No-load torque

Nm	0,5	0,7	0,9	0,9	1,2	1,2	1,5	1,8
----	-----	-----	-----	-----	-----	-----	-----	-----

### Speed

(m/s) max	2	4	5	7	8	8	8	8
-----------	---	---	---	---	---	---	---	---

### Tensile force

permanent (N)	390	894	1 900	1900	4000	4000	5900	7900
0,2 s (N)	480	480	2090	2090	4300	4300	6350	8500

### Geometrical moments of inertia of aluminium profile

$I_x$ mm <sup>4</sup>	4,09x10 <sup>4</sup>	1,32x10 <sup>5</sup>	6,79x10 <sup>5</sup>	6,79x10 <sup>5</sup>	18,99x10 <sup>5</sup>	18,99x10 <sup>5</sup>	44,4x10 <sup>5</sup>	101,5x10 <sup>5</sup>
$I_y$ mm <sup>4</sup>	4,00x10 <sup>4</sup>	1,34x10 <sup>5</sup>	6,97x10 <sup>5</sup>	6,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	44,8x10 <sup>5</sup>	101,5x10 <sup>5</sup>
E-Modulus N/mm <sup>2</sup>	70000	70000	70000	70000	70000	70000	70000	70000

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

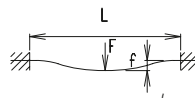
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

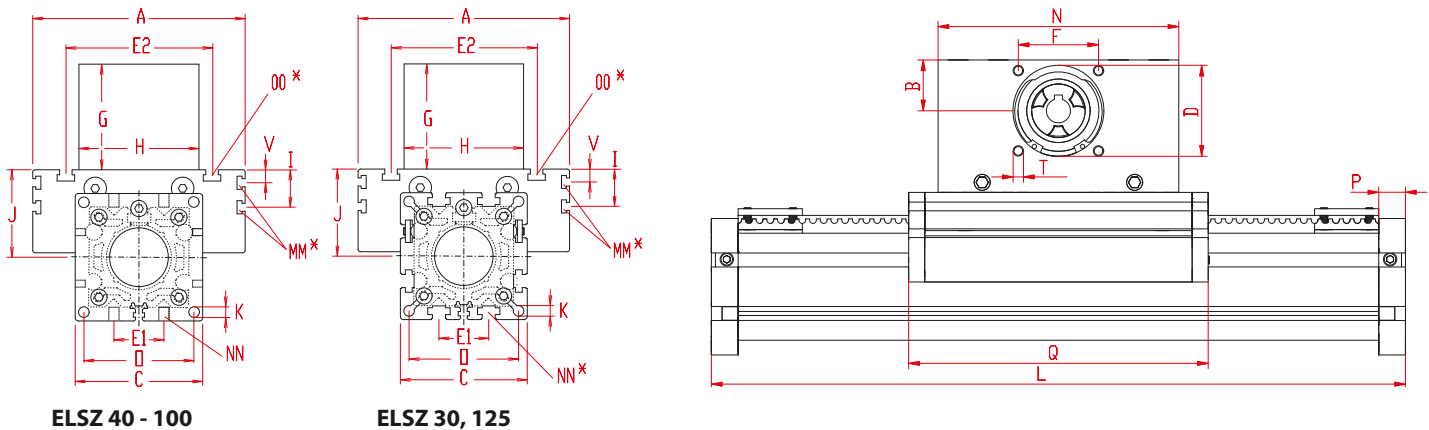
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system ELSZ 30, 40, 60, 60S, 80, 80S, 100, 125

Dimensions (mm)



3.1

\*For slide nuts refer to chapter 2.2 page 2

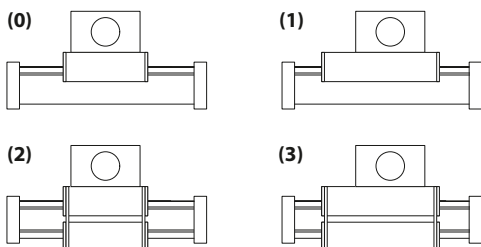
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E1	E2	F	G	H	I	J	K	MM for	N	NN for	O	OO for	P	Q	T	V	Basic weight	Weight per 100 mm
ELSZ 30	210	70	20	42	37	-	56	32	55	60	-	26	4,2	-	110	M 6	35	M 6	12	128	M 5	-	1,5 kg	0,16 kg
ELSZ 40	260	100	30	58	47	18	66	42	83	80	-	35	6,5	-	130	M 6	47	M 6	12	164	M 6	-	2,7 kg	0,24 kg
ELSZ 60	355	144	38	82	68	30	96	60	104	100	-	49	8,5	-	180	M 8	69	M 8	16	214	M 8	-	6,3 kg	0,62 kg
ELSZ 60S	355	170	38	82	68	30	108	60	102	100	-	53	8,5	-	180	M 8	69	M 8	16	214	M 8	-	7,3 kg	0,62 kg
ELSZ 80	460	170	60	102	90	40	117	80	140	130	30,5	70	8,5	M 6	270	M 10	88	M 10	20	304	M 10	10,5	14,0 kg	1,00 kg
ELSZ 80S	460	190	60	102	90	40	126	80	138,4	130	30	71	8,5	M 6	270	M 10	88	M 8	20	304	M 10	12,5	15,0 kg	1,00 kg
ELSZ 100	575	230	62	130	110	50	155	100	143	160	29	89	M12	M10	310	M 10	112	M 10	30	350	M 10	-	31,0 kg	1,60 kg
ELSZ 125	605	295	62	165	110	60	200	100	139	180	30	107,5	M12	M10	310	M 12	140	M 12	30	365	M 10	-	57,4 kg	1,96 kg

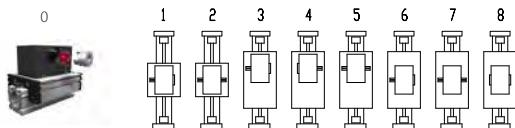
**0 Choice of guide body profile:**

- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



**0 Drive version:**



Size	Version 1		Version 2		Version 3	
	Q	L	Q	L	Q	L
30	195	279	140	222	207	291
40	257	355	180	276	273	371
60	353	494	230	371	369	510
60S	379	520	234	375	399	540
80	469	625	320	476	485	641
80S	489	645	324	480	509	665
100	575	800	366	591	591	816
125	640	870	389	619	664	894

The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 80 + 100).

Version 8 is the same as 0, but with double sided coupling claw.

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 3	30	5M15	100	20
0 4	40	5M25	130	26
0 7	60 (S)	8M30	192	24
0 9	80 (S)	8M50	256	32
1 0	100	8M70	304	38
1 4	125	8M100	304	38

**Shaft dimensions / Coupling claw:**

Size	Shaft $\phi$ h6 x length	Key	Coupling
30	10 x 27	3x3x25	9
40	14 x 35	5x5x28	14
60 (S)	18 x 45	6x6x40	19
80 (S)	22 x 45	6x6x40	24
100	30 x 55	8x7x50	28
125	40 x 55	12x8x50	-----

ELSZ 60 0 0 0 0 0 7 1 1500

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:




ELSZ 60 with standard body profile, standard carriage with widened belt and coupling claw on one side, 1170 mm stroke.

For combination kits and connecting elements refer to chapter 2.2

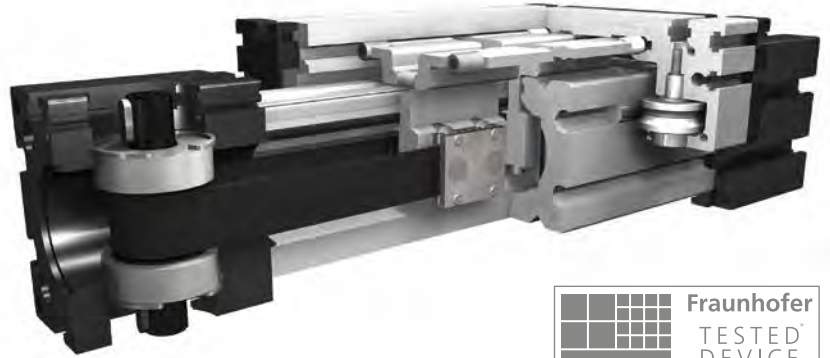
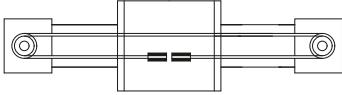


# Linear system **ELVZ 60, 60S, 80, 80S, 100, 125**

## INTERNAL BELT DRIVE

-  CLEAN ROOM
-  TOOTHED BELT VERTICAL
-  HIGH DYNAMICS

3.1



### Function:

This linear unit consists of an aluminium square profile with integrated, hardened steel guide rods. The carriage, which has internal linear ball bearings that can be adjusted free of play, is driven along the guide rods by a toothed belt. Toothed pulley has maintenance-free ball bearings. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. This linear unit is suitable for application in clean rooms of clean-room classification 1.000 (corresponding to US Fed. Standard 209 E).

### Fitting position:

As required. Max. length 3.000 mm.

### Carriage mounting:

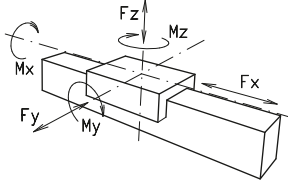
By T-slots.

### Unit mounting:

By tapped holes or tapped holes in the bearing block, mounting sets.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

Forces and torques	Size	ELVZ 60		ELVZ 60 S		ELVZ 80		ELVZ 80 S		ELVZ 100		ELVZ 125	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
	$F_x$ (N)	700	580	700	580	1000	840	1000	840	3100	2600	5000	4950
	$F_y$ (N)	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500	12000	9000
	$F_z$ (N)	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200	6000	4500
	$M_x$ (Nm)	67	43	88	65	90	55	170	140	300	230	600	450
	$M_y$ (Nm)	90	70	190	140	110	80	270	230	400	270	750	600
	$M_z$ (Nm)	120	100	230	170	150	120	300	220	750	500	1350	1150
<b>All forces and torques relate to the following:</b>													
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$													
table values													
<b>No-load torque</b>													
Nm		0,5	0,5	0,8	1,2	1,2	1,6						
<b>Speed</b>													
(m/s) max		3	4	4	4	5	6						
<b>Tensile force</b>													
permanent (N)		700	700	1000	1000	3100	5000						
0,2 s (N)		800	800	1150	1150	3400	5450						
<b>Geometrical moments of inertia of aluminium profile</b>													
$I_x$ mm <sup>4</sup>		6,79x10 <sup>5</sup>	6,79x10 <sup>5</sup>	18,99x10 <sup>5</sup>	18,99x10 <sup>5</sup>	44,4x10 <sup>5</sup>	101,5x10 <sup>5</sup>						
$I_y$ mm <sup>4</sup>		6,97x10 <sup>5</sup>	6,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	44,8x10 <sup>5</sup>	101,5x10 <sup>5</sup>						
E-Modulus N/mm <sup>2</sup>		70000	70000	70000	70000	70000	70000						

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

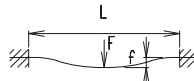
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

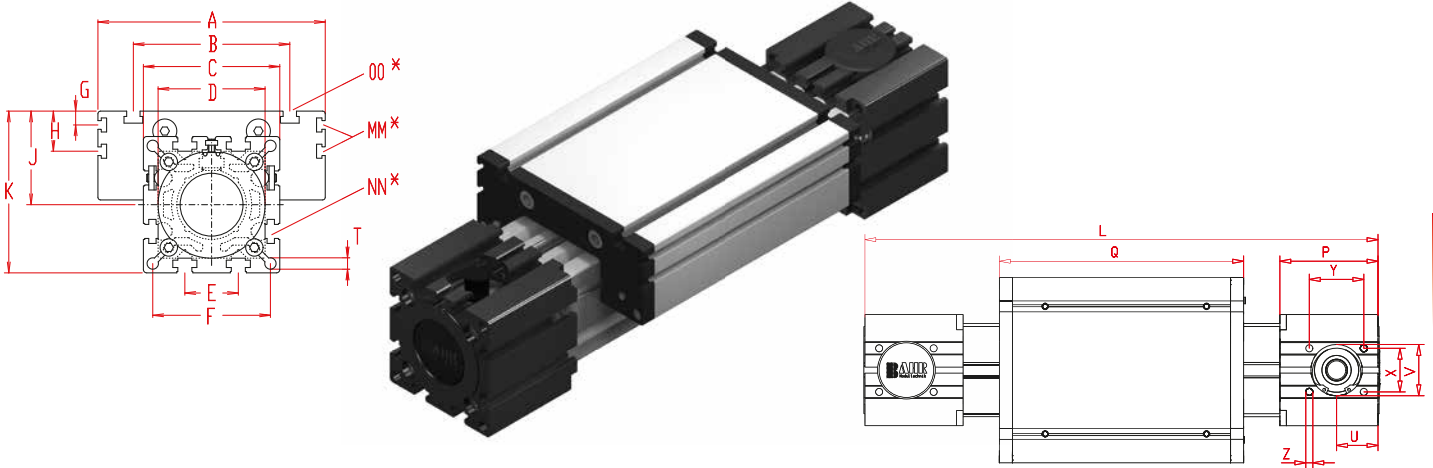
f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **ELVZ 60, 60S, 80, 80S, 100, 125**

Dimensions (mm)

3.1



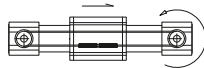
\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

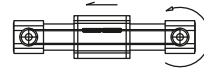
Size	Basic length L	A	B	C	D ±0,05	E	F	G	H	J	K	MM for	NN for	OO for	P	Q	T	U	V -0,05	W'	X	Y	Z	Basic weight	Weight per 100 mm
<b>ELVZ 60</b>	290	144	96	82	62x1	30	69	-	-	49	90	-	M8	M8	59	168	8,5	23	37	14	30	36	M6	4,8 kg	0,62 kg
<b>ELVZ 60S</b>	315	170	108	82	62x1	30	69	-	-	53	94	-	M8	M8	59	194	8,5	23	37	14	30	36	M6	5,8 kg	0,62 kg
<b>ELVZ 80</b>	375	170	117	102	80x1	40	88	10,5	30,5	70	121	M6	M10	M10	90	194	8,5	38	47	18	40	50	M8	10,0 kg	1,00 kg
<b>ELVZ 80S</b>	395	190	126	102	80x1	40	88	12,5	30	71	122	M6	M10	M8	90	214	8,5	38	47	18	40	50	M8	11,0 kg	1,00 kg
<b>ELVZ 100</b>	530	230	155	130	110x1	50	112	-	29	89	154	M10	M10	M10	110	300	10,5	45	68	19	50	64	M10	24,0 kg	1,60 kg
<b>ELVZ 125</b>	630	295	200	165	130x2	60	142	-	30	107,5	190	M10	M10	M12	130	365	13	58	90	35	60	85	M10	37,0 kg	2,10 kg

W' = standard shaft

**1** (1) Belt connection right



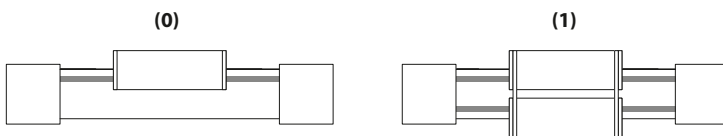
(2) Belt connection left



**0 Choice of guide body profile:**

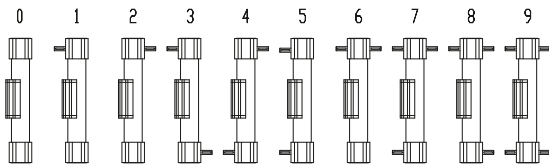
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 1	
	Q	L
<b>60</b>	184	306
<b>60S</b>	214	336
<b>80</b>	210	391
<b>80S</b>	234	415
<b>100</b>	316	546
<b>125</b>	389	649

**0 Drive version:**



The standard version 0 is supplied with 4 flush mounted shafts.

**Belt table**

Code No.	Size	Belt	mm/rev.	Number of teeth
<b>0 4</b>	<b>60 (S)</b>	5M 25	80	16
<b>0 4</b>	<b>80 (S)</b>	5M 25	110	22
<b>0 9</b>	<b>100</b>	8M 48	144	18
<b>0 9</b>	<b>125</b>	8M 50	192	24

**Shaft dimensions**

Size	Shaft ø h6 x length	Key
<b>60 (S)</b>	14 x 35	5x5x28
<b>80 (S)</b>	18 x 45	6x6x40
<b>100</b>	22 x 45	6x6x40
<b>125</b>	30 x 55	8x7x50

**ELVZ 60 1 0 0 0 0 4 1 1500**

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

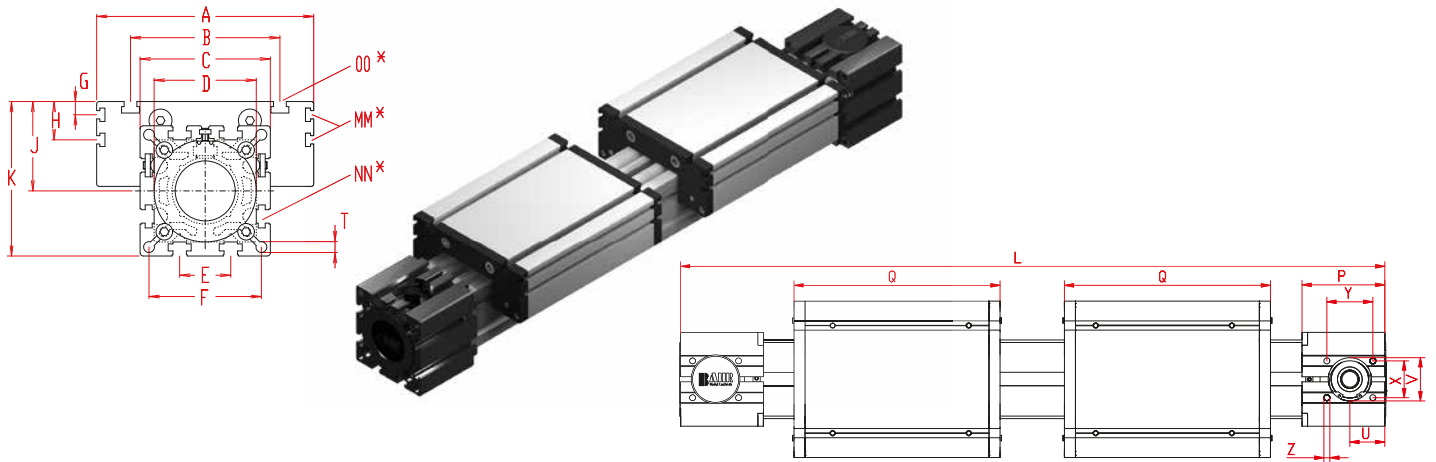
ELVZ 60 with belt connection right, standard body profile, standard carriage and 4 flush mounted shafts, 1210 mm stroke

For combination kits and connecting elements refer to chapter 2.2

# Linear system **ELVZ 60, 60S, 80, 80S, 100, 125**

## INTERNAL BELT DRIVE - TWO CARRIAGES MOVING IN OPPOSITE DIRECTIONS

3.1



\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount

Size □	Basic length L	A	B	C	D ± 0,05	E	F	G	H	J	K	MM for	NN for	OO for	P	Q	T	U	V - 0,05	W'	X	Y	Z	Basic weight	Weight per 100 mm
ELVZ 60	460	144	96	82	62x1	30	69	--	--	49	90	--	M 8	M 8	59	168	8,5	23	37	14	30	36	M 6	6,5 kg	0,62 kg
ELVZ 60S	510	170	108	82	62x1	30	69	--	--	53	94	--	M 8	M 8	59	194	8,5	23	37	14	30	36	M 6	8,5 kg	0,62 kg
ELVZ 80	570	170	117	102	80x1	40	88	10,5	30,5	70	121	M 6	M10	M10	90	194	8,5	38	47	18	40	50	M 8	13,0 kg	1,00 kg
ELVZ 80S	610	190	123	102	80x1	40	88	12,5	30	71	122	M 6	M10	M 8	90	214	8,5	38	47	18	40	50	M 8	15,0 kg	1,00 kg
ELVZ 100	830	230	155	130	110x1	50	112	--	29	89	154	M10	M10	M10	110	300	10,5	45	68	19	50	64	M10	31,0 kg	1,60 kg
ELVZ 125	990	295	200	165	130x2	60	142	--	30	107,5	190	M10	M10	M12	130	365	13	58	90	35	60	85	M10	50,5 kg	2,10 kg

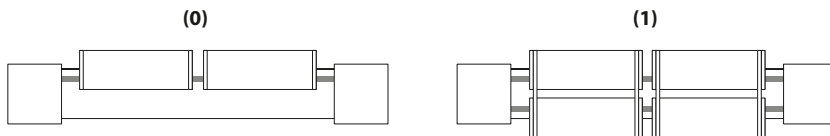
W' = standard shaft



**0** Choice of guide body profile:

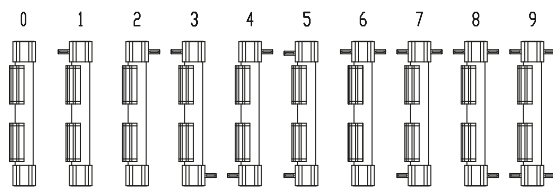
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0** Choice of carriages:



Size	Version 1	
	Q	L
60	184	492
60S	214	542
80	210	602
80S	234	650
100	316	862
125	389	1038

**0** Drive version:



The standard version 0 is supplied with 4 flush mounted shafts.

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	60 (S)	5M 25	80	16
0 4	80 (S)	5M 25	110	22
0 9	100	8M 48	144	18
0 9	125	8M 50	192	24

**Shaft dimensions:**

Size	Shaft ø h6 x length	Key
60 (S)	14 x 35	5x5x28
80 (S)	18 x 45	6x6x40
100	22 x 45	6x6x40
125	30 x 55	8x7x50

**ELVZ 60 7 0 0 0 0 4 1 1500**

Basic length + stroke = total length

For combination kits and connecting elements refer to chapter 2.2

Sample ordering code:

ELVZ 60 right-/left-hand with belt connection right, standard body profile, standard carriage and 4 flush mounted shafts, 1040 mm stroke

# Linear system **ELZ 30, 40, 60, 60S, 80, 80S, 100, 125**

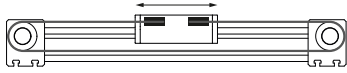
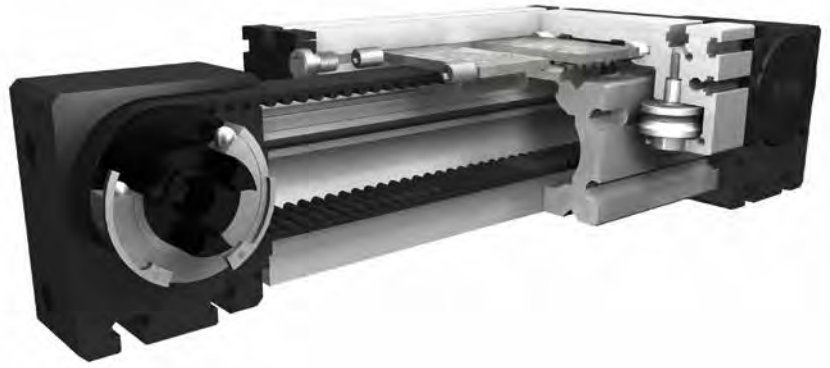
## BELT DRIVE

↔ UNIVERSAL SYSTEM

🕒 LONG SERVICE LIFE

⚙️ HIGH SPEED

📏 LONG TRAVERSE PATH > 6000 mm



3.1

### Function:

This linear unit consists of an aluminium square profile with integrated, hardened steel guide rods. The carriage, which has internal linear ball bearings that can be adjusted free of play, is driven along the guide rods by a timing belt. The pulleys have maintenance-free ball bearings. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. With this series, multi-part assembled units with long strokes can be realized.

### Fitting position:

As required. Max. length 6.000 mm without joints.

### Carriage mounting:

By T-slots.

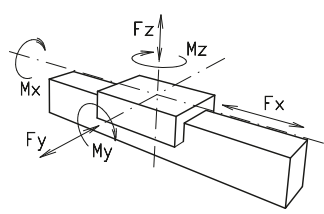
### Unit mounting:

By T-slots or tapped holes in the bearing block, mounting sets.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

### Forces and torques



Size	ELZ 30		ELZ 40		ELZ 60		ELZ 60 S		ELZ 80		ELZ 80 S		ELZ 100		ELZ 125	
Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
F <sub>x</sub> (N)	200	180	390	350	894	800	894	800	1900	1800	1900	1800	4000	3800	5900	5750
F <sub>y</sub> (N)	90	60	1200	700	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500	12000	9000
F <sub>z</sub> (N)	90	60	900	650	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200	6000	4500
M <sub>x</sub> (Nm)	10	5	25	20	67	43	88	65	90	55	170	140	300	230	600	450
M <sub>y</sub> (Nm)	13	6	32	18	90	70	190	140	110	80	270	230	400	270	750	600
M <sub>z</sub> (Nm)	14	7	35	25	120	100	230	170	150	120	300	220	750	500	1350	1150

### All forces and torques relate to the following:

existing values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

table values

### No-load torque

Nm	0,2	0,3	0,6	0,7	0,9	1,2	1,4	1,8
----	-----	-----	-----	-----	-----	-----	-----	-----

### Speed

(m/s) max	2	4	5	7	6	8	10	10
-----------	---	---	---	---	---	---	----	----

### Tensile force

permanent (N)	200	390	900	900	1900	1900	4000	5900
0,2 s (N)	280	480	1000	1000	2090	2090	4300	6350

### Geometrical moments of inertia of aluminium profile

I <sub>x</sub> mm <sup>4</sup>	4,09x10 <sup>4</sup>	1,32x10 <sup>5</sup>	6,79x10 <sup>5</sup>	6,79x10 <sup>5</sup>	18,99x10 <sup>5</sup>	18,99x10 <sup>5</sup>	44,4x10 <sup>5</sup>	101,5x10 <sup>5</sup>
I <sub>y</sub> mm <sup>4</sup>	4,00x10 <sup>4</sup>	1,34x10 <sup>5</sup>	6,97x10 <sup>5</sup>	6,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	44,8x10 <sup>5</sup>	101,5x10 <sup>5</sup>
E-Modulus N/mm <sup>2</sup>	70000	70000	70000	70000	70000	70000	70000	70000

For life-time calculation of rollers use our homepage.

### Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

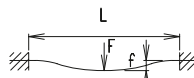
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

### Deflection:

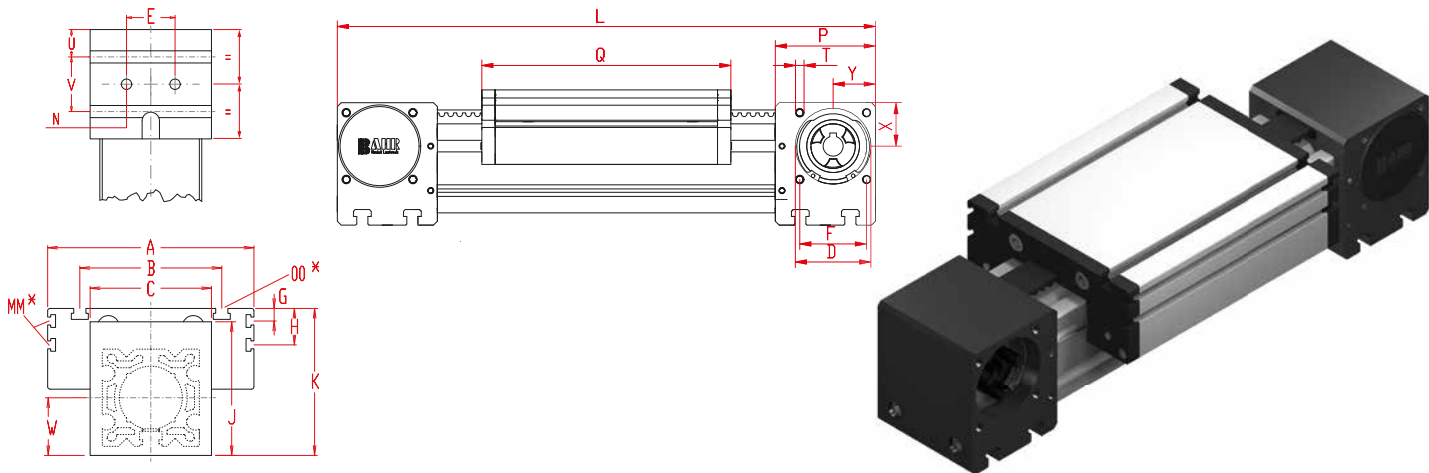
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Linear system ELZ 30, 40, 60, 60S, 80, 80S, 100, 125

Dimensions (mm)



3.1

\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

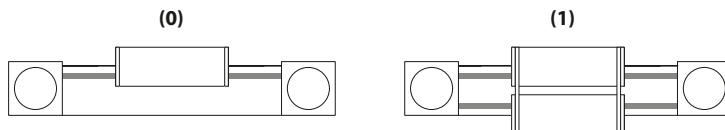
Size	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	MM for	N	OO for	P	Q	T	U	V	W	X	Y	Basic weight	Weight per 100 mm
ELZ 30	158	70	56	42	28	13	25	-	-	44	47	-	M 5	M 6	36	82	M 4	10	16	21	16	16	0,8 kg	0,13 kg
ELZ 40	225	100	66	58	37	18	32	-	-	58	64	-	M 6	M 6	49	122	M 5	12,5	24	29	20,5	20,5	1,9 kg	0,24 kg
ELZ 60	290	144	96	80	47	30	42	-	-	82	90	-	M 8	M 8	59	168	M 6	15	30	41	27	26	4,8 kg	0,62 kg
ELZ 60 S	315	170	108	80	47	30	42	-	-	82	94	-	M 8	M 8	59	194	M 6	15	30	41	27	26	5,8 kg	0,62 kg
ELZ 80	375	170	117	100	68	40	60	10,5	30,5	110	121	M 6	M 10	M 10	90	194	M 8	22,5	45	51	39	38	10,0 kg	1,00 kg
ELZ 80 S	395	190	126	100	68	40	60	12,5	30	110	122	M 6	M 10	M 8	90	214	M 8	22,5	45	51	39	38	11,0 kg	1,00 kg
ELZ 100	530	230	155	130	90	50	80	-	29	135	154	M 10	M 12	M 10	110	300	M 10	23	64	65	50	50	24,0 kg	1,60 kg
ELZ 125	625	295	200	160	110	60	100	-	30	167	191	M 10	M 12	M 12	130	365	M 10	38	50	82	60	60	37,0 kg	2,10 kg

**0 Choice of guide body profile:**

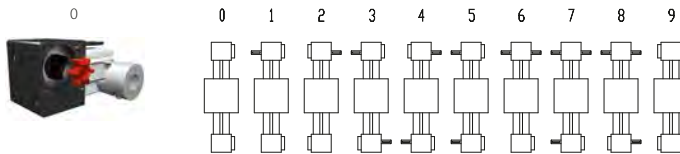
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

Size	Version 1	
	Q	L
30	94	170
40	138	241
60	184	306
60S	214	335
80	210	391
80S	234	415
100	316	546
125	389	649

**0 Choice of carriages:**



**0 Drive version:**



Version 9 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 100 and 125).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 1	30	3M12	75	25
0 3	40	5M15	100	20
0 4	60 (S)	5M25	130	26
0 7	80 (S)	8M30	192	24
0 9	100	8M50	256	32
1 0	125	8M70	304	38

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
30	6 x 15	2x2x12	7
40	10 x 27	3x3x22	9
60 (S)	14 x 35	5x5x28	14
80 (S)	18 x 45	6x6x40	19
100	22 x 45	6x6x40	24
125	30 x 55	8x7x50	28

ELZ 40 1 0 0 0 0 3 1 1500

Basic length + stroke = total length

For combination kits and connecting elements refer to chapter 2.2

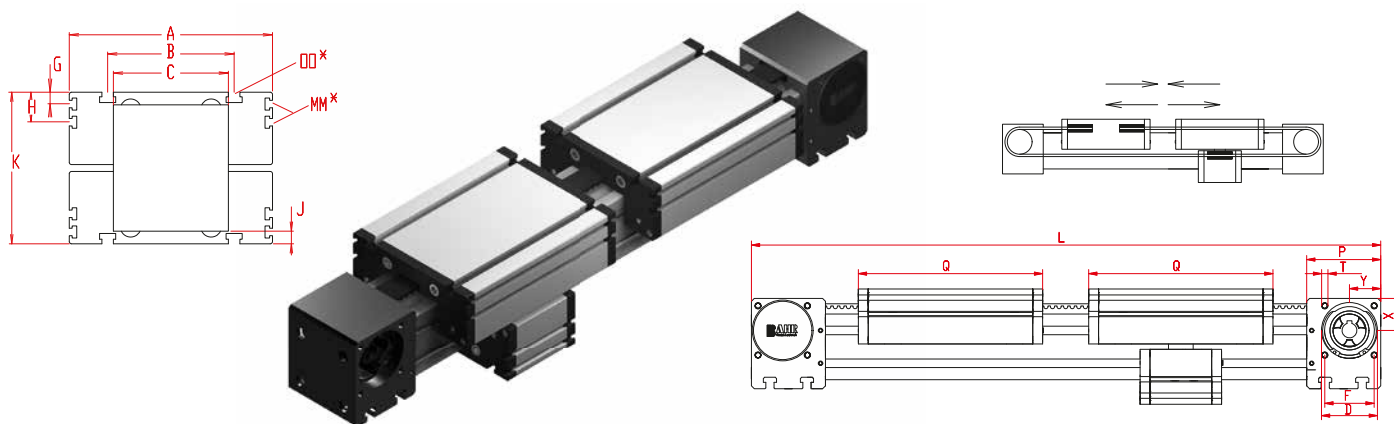
Sample ordering code:

ELZ 40 with standard body profile, standard carriage, coupling claw on one side, 1275 mm stroke.

# Linear system **ELZ 30, 40, 60, 60S, 80, 80S, 100, 125**

## BELT DRIVE WITH TWO CARRIAGES MOVING IN OPPOSITE DIRECTIONS

3.1



\*For slide nuts refer to chapter 2.2 page 2

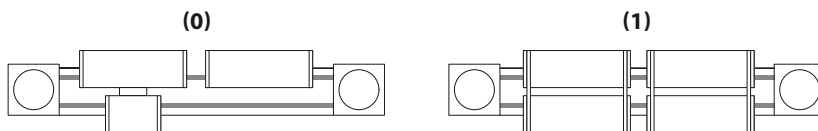
Increasing the carriage length will increase the basic length by the same amount.

Size □	Basic length L	A	B	C	D -0,05	F	G	H	J	K	MM for	OO for	P	Q	T	X	Y	Basic weight	Weight per 100 mm
ELZ 30	250	70	56	42	28	25	-	-	5	52	-	M 6	36	82	M 4	16	16	1,2 kg	0,13 kg
ELZ 40	350	100	66	58	37	32	-	-	6	70	-	M 6	49	122	M 5	20,5	20,5	2,8 kg	0,24 kg
ELZ 60	460	144	96	80	47	42	-	-	8	98	-	M 8	59	168	M 6	27	26	7,4 kg	0,62 kg
ELZ 60S	510	170	108	80	47	42	-	-	12	106	-	M 8	59	194	M 6	27	26	7,4 kg	0,62 kg
ELZ 80	570	170	117	100	68	60	10,5	30,5	19	140	M 6	M10	90	194	M 8	39	39	15,0 kg	1,00 kg
ELZ 80S	610	190	126	100	68	60	12,5	30	21	142	M 6	M 8	90	214	M 8	39	39	17,0 kg	1,00 kg
ELZ 100	830	230	155	130	90	80	-	29	24	178	M10	M10	110	300	M10	50	50	34,0 kg	1,60 kg
ELZ 125	990	295	200	160	110	100	-	30	25,5	216	M10	M12	130	365	M10	60	60	53,5 kg	2,10 kg

**0 Choice of guide body profile:**

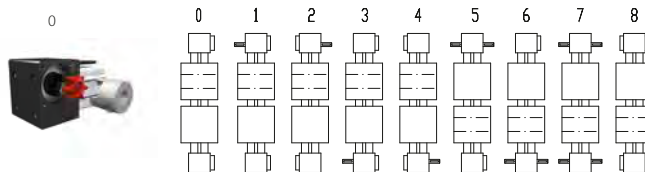
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 1	
	Q	L
30	94	274
40	138	382
60	184	492
60S	214	554
80	210	602
80S	234	650
100	316	862
125	389	1038

**0 Coupling - shaft mounting:**



Version 8 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 100 and 125).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 1	30	3M12	75	25
0 3	40	5M15	100	20
0 4	60 (S)	5M25	130	26
0 7	80 (S)	8M30	192	24
0 9	100	8M50	256	32
1 0	125	8M70	304	38

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
30	6 x 15	2x2x12	7
40	10 x 27	3x3x22	9
60 (S)	14 x 35	5x5x28	14
80 (S)	18 x 45	6x6x40	19
100	22 x 45	6x6x40	24
125	30 x 55	8x7x50	28

**ELZ 40 3 0 0 0 0 3 1 1500**

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7




Sample ordering code:

ELZ 40, right/left hand with standard body profile, standard carriage, coupling claw on one side, 1150 mm stroke.

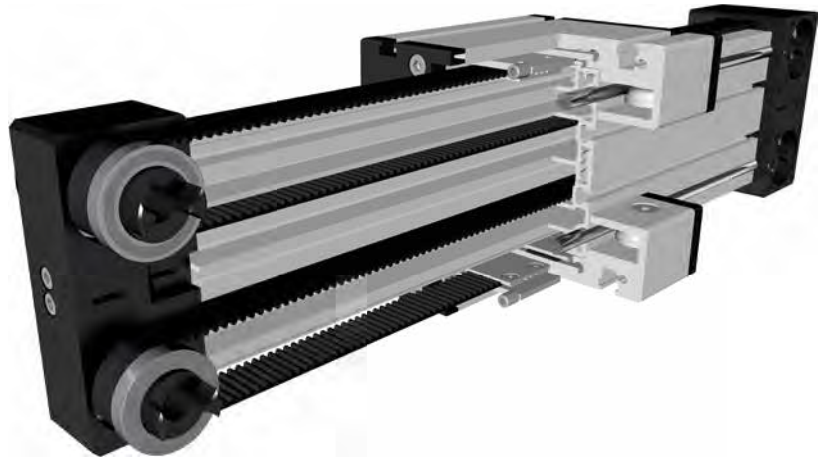
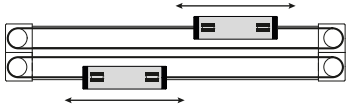
For combination kits and connecting elements refer to chapter 2.2

# Linear system **ELZD 60 (S) W**

## BELT DRIVE WITH TWO SEPARATELY DRIVEN CARRIAGES

-  HIGHER PROFILE STABILITY
-  INDEPENDENT CARRIAGES
-  HIGHER FORCE FIXTURE

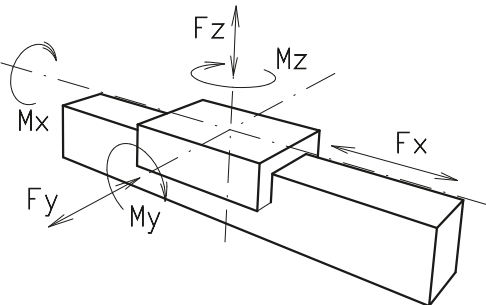
3.1



**Function:**

The guide body consists of an aluminium square profile with lateral, parallel, form-fit, internal hardened steel rods. Two carriages, which are driven individually by a timing belt, move along the guide body independently of one another. Due to the rectangular profile high torques and loads can be taken up. In addition, a very high stability and low deflection are ensured for long axis systems. The belt tension can be easily readjusted via a tensioning device within the carriage. This device also helps to adjust the symmetry of the carriages in applications where two parallel linear units are used.

- Fitting position:** As required. Max. length 3.000 mm without joints.
- Carriage mounting:** By T-slots.
- Unit mounting:** By T-slots or mounting sets.
- Belt type:** HTD with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

Forces and torques	Size	60		60 S	
	Forces/Torques	static	dynamic	static	dynamic
	$F_x$ (N)	894	800	894	800
	$F_y$ (N)	3000	2000	4100	3100
	$F_z$ (N)	1700	1100	2160	1600
	$M_x$ (Nm)	67	43	88	65
	$M_y$ (Nm)	90	70	190	140
	$M_z$ (Nm)	120	100	230	170
	<b>All forces and torques relate to the following:</b> existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$ table values				
<b>No-load torque</b>					
Nm	0,6		0,7		
<b>Speed</b>					
(m/s) max	5		7		
<b>Tensile force</b>					
permanent (N)	900		900		
0,2 s (N)	1000		1000		
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_x$ mm <sup>4</sup>	2,8 x 10 <sup>6</sup>		2,8 x 10 <sup>6</sup>		
$I_y$ mm <sup>4</sup>	9,6 x 10 <sup>5</sup>		9,6 x 10 <sup>5</sup>		
E-Modulus N/mm <sup>2</sup>	70000		70000		

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

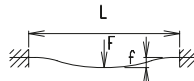
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- $S_i$  = safety factor 1, 2 ... 2
- $M_n$  = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- $M_o$  = driving torque (Nm)
- $P_o$  = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

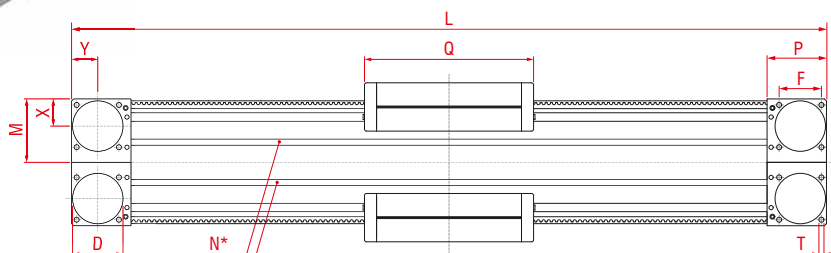
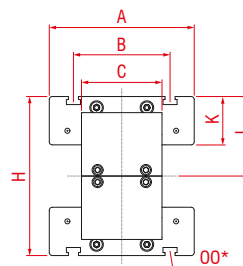
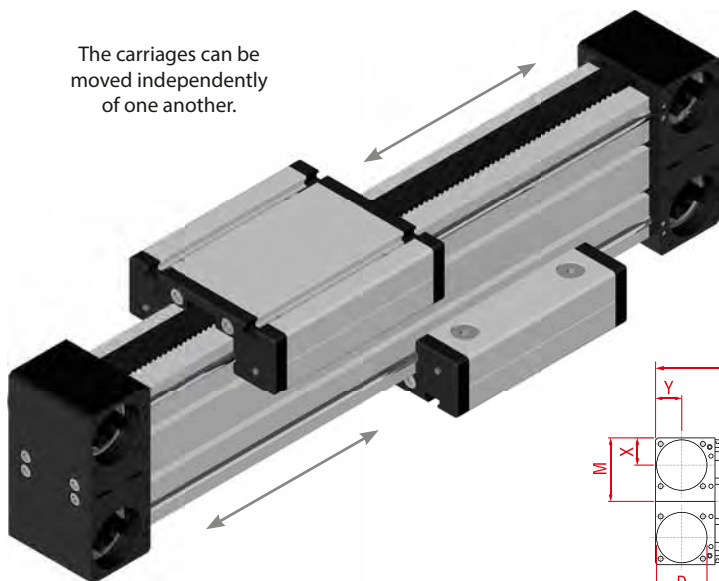
- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Linear system ELZD 60 (S) W

Dimensions (mm)

The carriages can be moved independently of one another.



\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	F	H	J	K	M	N for	OO for	P	Q	T	X	Y	Basic weight	Weight per 100 mm
ELZD 60 W	290	144	96	80	47	42	158	79	48	71	M5	M8	59	168	M6	27	26	9,6 kg	1,0 kg
ELZD 60S W	315	170	108	80	47	42	166	83	52	71	M5	M8	59	194	M6	27	26	11,6 kg	1,0 kg

**0 Choice of guide body profile:**

- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

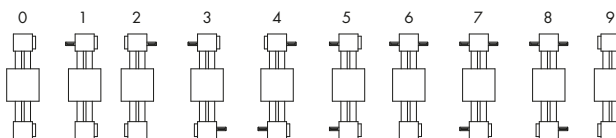
**0 Choice of carriages:**

(0)

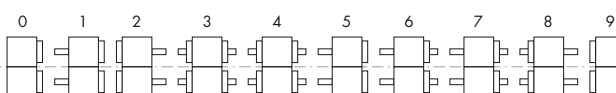


**0 Drive version:**

(0)

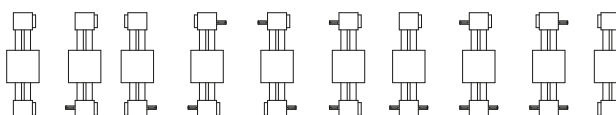


**Top drive version:**  
Version 9 is the same as 0, but with double sided coupling claw.



**Mirror plane**  
Drive version (top and bottom identical)

(0)



**Bottom drive version:**  
Version 9 is the same as 0, but with double sided coupling claw.

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	60 (S)	5M25	130	26

**Shaft dimensions / Coupling claw:**

Size	Shaft $\phi$ h6 x length	Key	Coupling
60 (S)	14 x 35	5x5x28	14

**ELZD 60 W 1 0 0 0 0 4 1 1500**

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

ELZD 60 W, standard body profile, standard carriage, coupling claw on one side, 1210 mm stroke


For combination kits and connecting elements refer to chapter 2.2



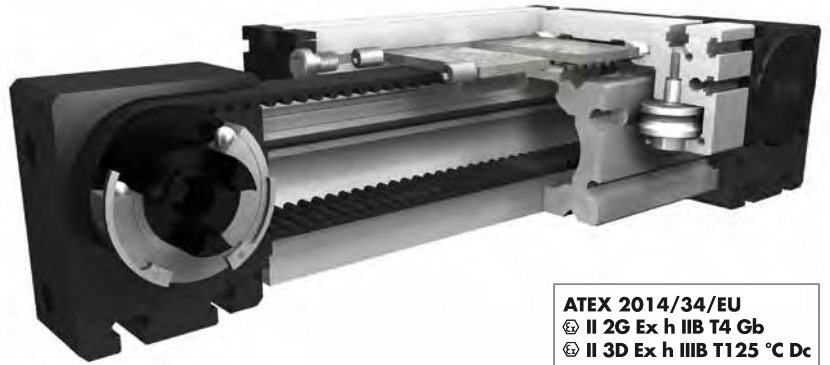
# Linear system **ELZ** **30, 40, 60, 60S, 80, 80S, 100, 125**



## BELT DRIVE - EX GUIDE

 UNIVERSAL SYSTEM

 EX-GUIDE

 HIGH SPEED



**ATEX 2014/34/EU**  
 **II 2G Ex h IIB T4 Gb**  
 **II 3D Ex h IIIB T125 °C Dc**



### Function:

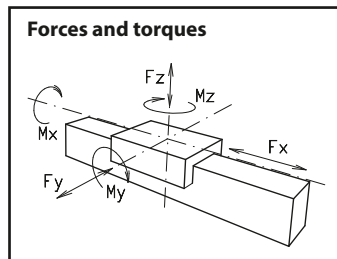
Like ELZ. The positioning system is suitable for use according to the intended purpose in potentially explosive areas (see ATEX 2014/34/EU marking). An operating manual is included in the scope of delivery. The system is certified for the following areas:

#### **ATEX 2014/34/EU** **II 2G EX h IIB T4 Gb:**

All application areas except for underground mining. Gas atmosphere category 2, explosion protection category: protection due to secure construction (design security). Equipment group IIB. Temperature class T4=135°C, EPL Gb.

#### **ATEX 2014/34/EU** **II 3D EX h IIIB T125 °C Dc:**

All application areas except for underground mining. Dust atmosphere category 3. Maximum permissible surface temperature: 125°C, EPL Dc.



**Fitting position:** As required, max. length 6.000 mm.

**Carriage mounting:** T-slots

**Unit mounting:** By T-slots or tapped holes in the bearing block, mounting sets.

**Belt type:** HTD with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

Size	ELZex 40		ELZex 60		ELZex 60 S		ELZex 80		ELZex 80 S		ELZex 100		ELZex 125	
Forces/Torques	static	dynamic	static	dynamic	statisch	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
$F_x$ (N)	178	142	312	250	312	250	1083	866	1083	866	1127	902	2067	1654
$F_y$ (N)	517	414	1330	1064	1910	1528	1584	1267	2219	1775	3100	2480	4980	3984
$F_z$ (N)	355	284	742	594	935	748	613	490	1052	842	1292	1034	2190	1752
$M_x$ (Nm)	12	10	36	29	52	41	36	29	67	54	101	81	220	176
$M_y$ (Nm)	13	11	39	32	66	53	39	32	87	70	136	109	280	224
$M_z$ (Nm)	19	15	70	56	137	110	100	81	182	146	326	260	636	509

**All forces and torques relate to the following**

existing values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

table values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

No-load torque	ELZex 40		ELZex 60		ELZex 60 S		ELZex 80		ELZex 80 S		ELZex 100		ELZex 125	
Nm	0,3		0,6		0,7		0,9		1,2		1,4		1,8	
<b>Speed</b>														
(m/s) max	1		1		1		1		1		1		1	
<b>Tensile force</b>														
permanent (N)	178		312		312		1083		1083		1127		2067	
<b>Geometrical moments of inertia of aluminium profile</b>														
$I_x$ mm <sup>4</sup>	1,32x10 <sup>5</sup>		6,79x10 <sup>5</sup>		6,79x10 <sup>5</sup>		18,99x10 <sup>5</sup>		18,99x10 <sup>5</sup>		44,4x10 <sup>5</sup>		101,5x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>	1,34x10 <sup>5</sup>		6,97x10 <sup>5</sup>		6,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		44,8x10 <sup>5</sup>		101,5x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>	70000		70000		70000		70000		70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

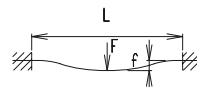
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 Si = safety factor 1,2 ... 2  
 Mn = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 Mo = driving torque (Nm)  
 Po = motor power (KW)

Deflection:

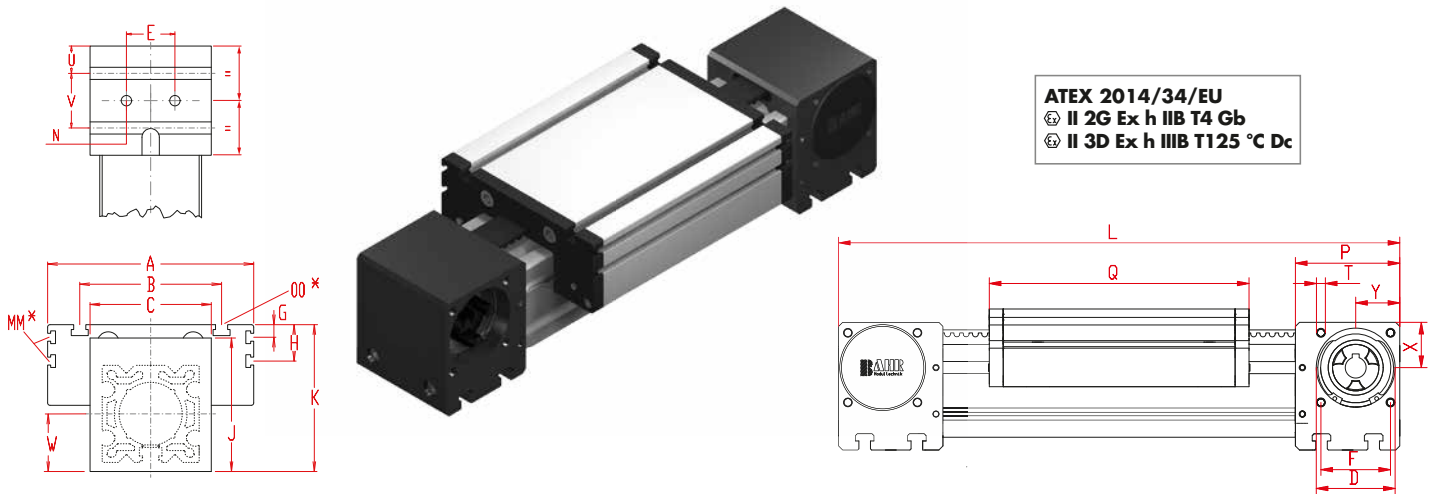
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **ELZ** **30, 40, 60, 60S, 80, 80S, 100, 125**

Dimensions (mm)



3.1

\*For slide nuts refer to chapter 2.2 page 2

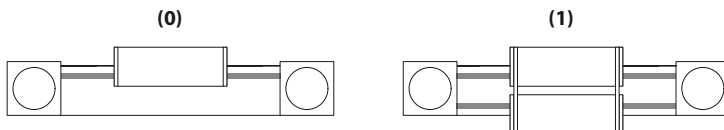
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	MM for	N	OO for	P	Q	T	U	V	W	X	Y	Basic weight	Weight per 100 mm
ELZex 40	225	100	66	58	37	18	32	-	-	58	64	-	M 6	M 6	49	122	M 5	12,5	24	29	20,5	20,5	1,9 kg	0,24 kg
ELZex 60	290	144	96	80	47	30	42	-	-	82	90	-	M 8	M 8	59	168	M 6	15	30	41	27	26	4,8 kg	0,62 kg
ELZex 60 S	315	170	108	80	47	30	42	-	-	82	94	-	M 8	M 8	59	194	M 6	15	30	41	27	26	5,8 kg	0,62 kg
ELZex 80	375	170	117	100	68	40	60	10,5	30,5	110	121	M 6	M 10	M 10	90	194	M 8	22,5	45	51	39	38	10,0 kg	1,00 kg
ELZex 80 S	395	190	126	100	68	40	60	12,5	30	110	122	M 6	M 10	M 8	90	214	M 8	22,5	45	51	39	38	11,0 kg	1,00 kg
ELZex 100	530	230	155	130	90	50	80	-	29	135	154	M 10	M 12	M 10	110	300	M 10	23	64	65	50	50	24,0 kg	1,60 kg
ELZex 125	625	295	200	160	110	60	100	-	30	167	191	M 10	M 12	M 12	130	365	M 10	38	50	82	60	60	37,0 kg	2,10 kg

**0 Choice of guide body profile:**

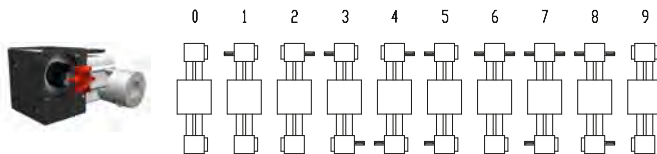
(0) Standard (2) corrosion-protected guide rods and screws

**0 Choice of carriages:**



Size	Version 1	
	Q	L
40	138	241
60	184	306
60S	214	335
80	210	391
80S	234	415
100	316	546
125	389	649

**0 Drive version:**



Version 9 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 100 and 125).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 3	40	5M15	100	20
0 4	60 (S)	5M25	130	26
0 7	80 (S)	8M30	192	24
0 9	100	8M50	256	32
1 0	125	8M70	304	38

**Shaft dimensions / Coupling claw:**

Size	Shaft $\phi$ h6 x length	Key	Coupling
40	10 x 27	3x3x22	9
60 (S)	14 x 35	5x5x28	14
80 (S)	18 x 45	6x6x40	19
100	22 x 45	6x6x40	24
125	30 x 55	8x7x50	28

**ELZex 40 1 0 0 0 0 3 1 1500**

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

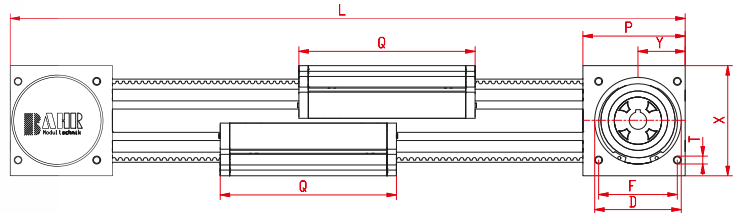
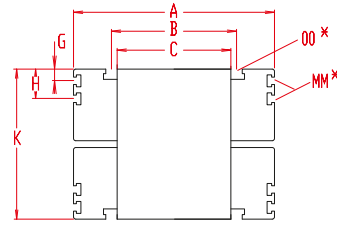
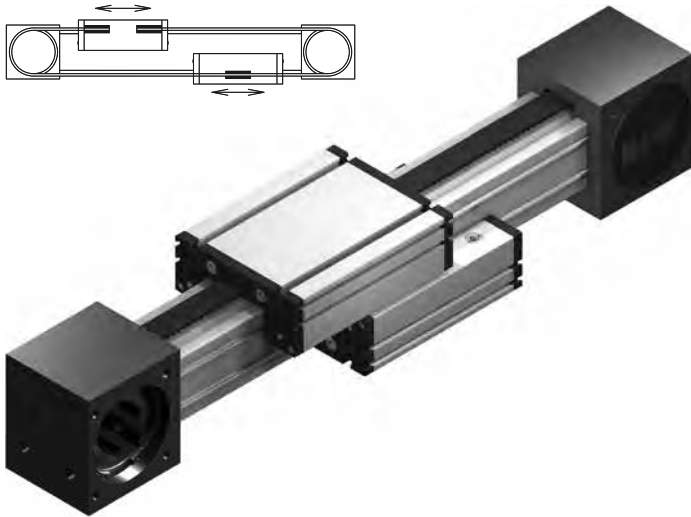
ELZex 40, standard body profile, standard carriage, coupling claw on one side, 1275 mm stroke.

For combination kits and connecting elements refer to chapter 2.2

# Positioning system ELZG 30, 40, 60, 60S, 80, 80S

Belt drive

Dimensions (mm)



\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size □	Basic length L	A	B	C	D -0,05	F	G	H	K	MM for	OO for	P	Q	T	X	Y	Basic weight	Weight per 100 mm
ELZG 30	195	70	56	48	47	42	-	-	52	-	M 6	55	82	M 6	52	27	1,1 kg	0,13 kg
ELZG 40	265	100	66	60	55	55	-	-	70	-	M 6	70	122	M 6	70	33	4,0 kg	0,29 kg
ELZG 60	365	144	96	88	80	70	-	-	98	-	M 8	95	168	M 8	98	46	10,3 kg	0,65 kg
ELZG 60S	390	170	108	88	80	70	-	-	106	-	M 8	95	194	M 8	98	46	12,3 kg	0,65 kg
ELZG 80	460	170	117	118	110	100	10,5	30,5	140	M 6	M 10	130	194	M 10	140	60	20,5 kg	1,15 kg
ELZG 80S	480	190	126	118	110	100	12,5	30	142	M 6	M 8	130	214	M 10	140	60	21,5 kg	1,15 kg

**0 Choice of guide body profile:**

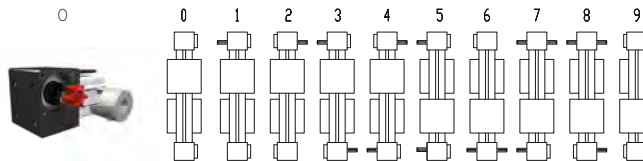
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



For standard carriage length see 'Q' in table. The carriages can be delivered in any non-standard length upon request; the longer the carriage, the higher the load capacity.

**0 Drive version:**



Version 9 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 80).

**Belt table**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 1	30	3M12	120	40
0 3	40	5M15	160	32
0 4	60 (S)	5M25	220	44
0 7	80 (S)	8M30	320	40

**Shaft dimensions / Coupling claw**

Size	Shaft Ø h6 x length	Key	Coupling
30	10 x 27	3x3x25	9
40	14 x 35	5x5x28	14
60 (S)	18 x 45	6x6x40	19
80 (S)	22 x 45	6x6x40	24

ELZG 40 1 0 0 0 0 3 1 01500

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

ELZG 40, standard body profile, standard carriage and coupling claw on one side, 1235 mm stroke.

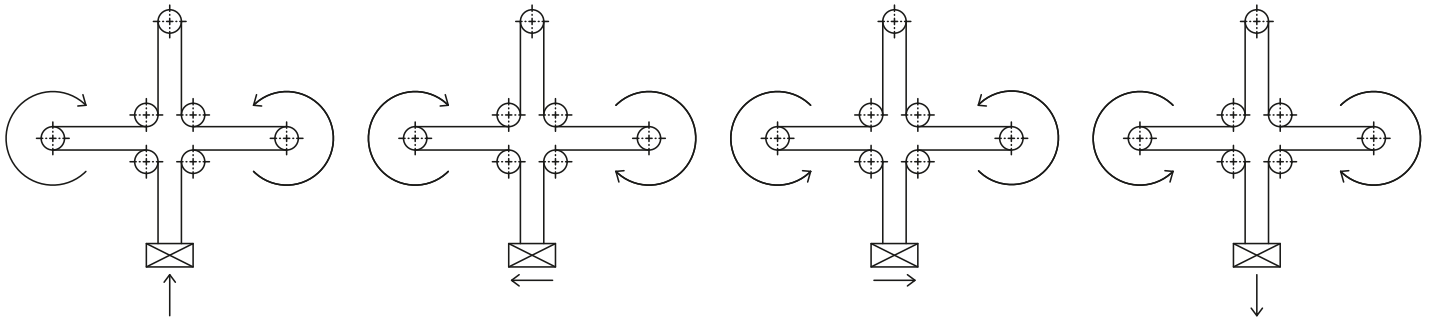
For combination kits and connecting elements refer to chapter 2.2

3.1

# Linear system **ELZI 30, 40, 60**

## X/Z - PORTAL

3.1



### Function:

X/Z gantry consisting of a double guide in the horizontal X level and a vertical Z axis. The belt is fixed and tensioned at the load end. The unit is driven by a rotating belt, which remains connected through various deflection points. The movement is realised by two motors. The coordinate lies diagonal to the deflection points of the X axes and the Z axis.

**Advantage:** Only small masses are moved and thus it is possible to achieve high accelerations.

### Fitting position:

As required, max. length for x-axes 2000mm, for z-axis 1000mm

### Unit mounting:

By tapped holes in the bearing block, mounting sets.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability:  $\pm 0,1$  mm.

Forces and torques	Size	ELZI 30		ELZI 40		ELZI 60	
	Forces/torques	static	dynam.	static	dynam.	static	dynam.
$F_x$ (N)		390	350	894	800	1900	1800
$F_z$ (N)		180	160	1200	900	1600	1200
$M_x$ (Nm)		15	9	25	20	67	43
$M_y$ (Nm)		20	13	32	22	90	70
$M_z$ (Nm)		23	18	35	25	120	100
<b>All forces and torques relate to the following:</b>							
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$							
<b>No-load torque horizontal movement</b>							
Nm		2 x 0,4		2 x 0,6		2 x 1,1	
<b>Speed</b>							
(m/s) max		2		4		5	
<b>Tensile force (please use necessarily the Mulco life-time calculation, see Chapter 4.2)</b>							
permanent (N)		390		894		1900	
0,2 s (N)		480		1000		2090	
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup> (X-/Z-Achse)		0,31x10 <sup>5</sup> / 0,41x10 <sup>5</sup>		1,12x10 <sup>5</sup> / 1,32x10 <sup>5</sup>		4,06x10 <sup>5</sup> / 6,79x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup> (X-/Z-Achse)		1,70x10 <sup>5</sup> / 0,40x10 <sup>5</sup>		7,20x10 <sup>5</sup> / 1,34x10 <sup>5</sup>		24,3x10 <sup>5</sup> / 6,97x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

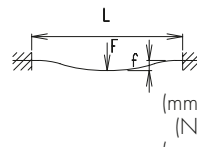
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

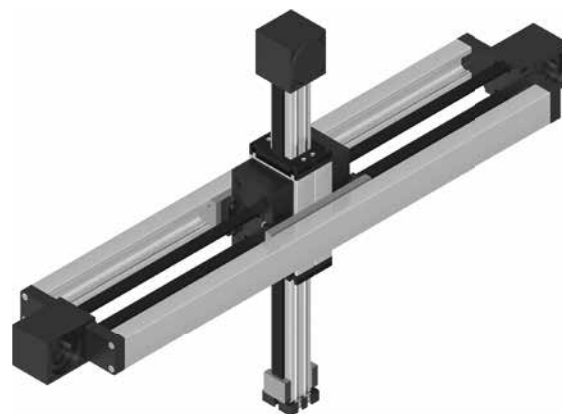
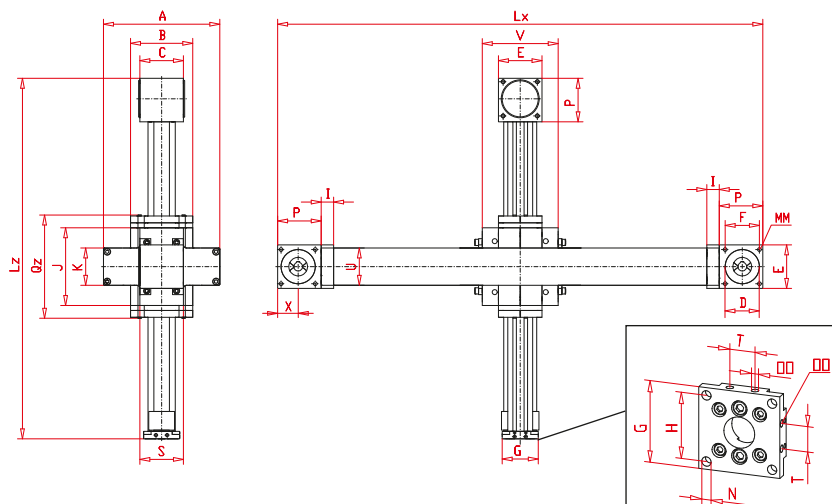
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



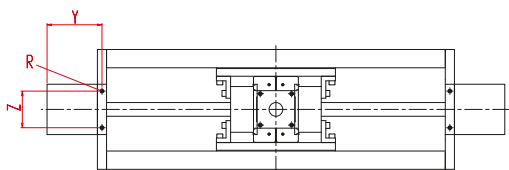
# Linear system ELZI 30, 40, 60

Dimensions (mm)



3.1

Endpiece for gripper



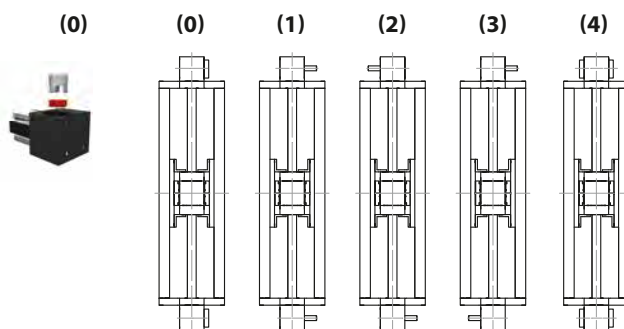
Size	X-Axis		Z-Axis	
	Profile	moving mass	Profile	moving mass
30	2 x UL40	4,5 kg	EL30	1,0 kg
40	2 x UL60	7,0 kg	EL40	2,4 kg
60	2 X UL80	19,0 kg	EL60	6,5 kg

Size	Basic length		A	B	C	D -0,05	E	F	G	H	I	J	K	MM for	N Ø	OO for	P	Qz	R for	S	T	U	V	X	Y	Z	Basic weight	Weight per 100 mm X-/Z-axis
	Lx	Lz																										
ELZI 30	290	245	137	70	51	47	52	42	42	35	15	114	40	M6	4,2	M6	55	144	M6	60	-	40	112	26,5	62,5	35	5,20 kg	0,32/0,18 kg
ELZI 40	380	290	187	100	70	55	70	55	58	47	20	125	60	M6	6,6	M6	70	165	M8	70	18	60	122	33	80	50	11,5 kg	0,68/0,3 kg
ELZI 60	525	425	262	144	110	90	100	80	82	69	20	192	80	M10	8,5	M8	110	235	M10	100	30	80	198	50	120	80	33,0 kg	1,13/0,67 kg

**0 Choice of guide body profile:**

- (0) Standard
- (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Drive version:**



**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 3	30	5M15	120	24
0 4	40	5M25	160	32
0 6	60	8M30	224	28

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
30	10x27	3x3x25	9
40	14x35	5x5x28	14
60	22x45	6x6x35	24

**X-Axis** Basic length + stroke = total length

**Y-Axes** Basic length + stroke = total length

ELZI 40 0 0 0 0 0 4 1 1500

ELZI 40 1 0 0 0 0 4 1 700

Pos. 1 2 3 4 5 6 7

Sample ordering code:

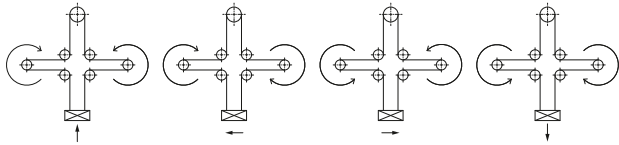
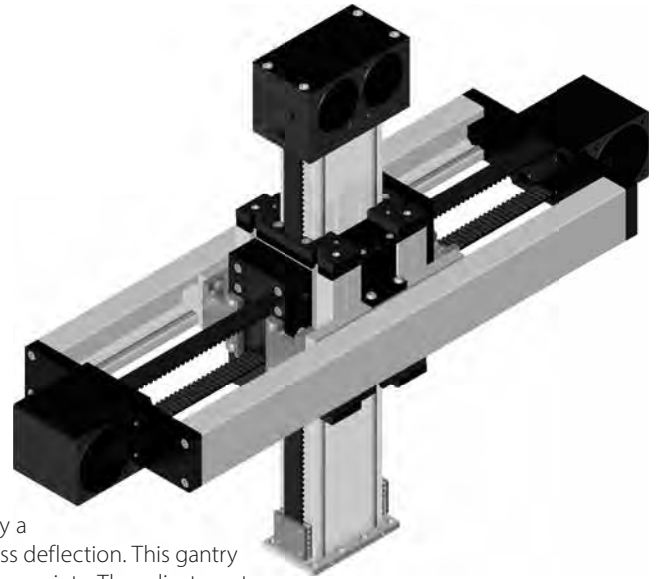
ELZI 40, with standard body profile, coupling claw on one side, stroke X = 1120 / Z = 410mm

# Linear system **ELZI 60 SW**

## X/Z - PORTAL - REINFORCED VERSION

- ✔ BELT DRIVE
- ✂ COMPACT DESIGN
- 🔧 GRIPPER ADAPTATION
- ⚙ HIGH SPEED

3.1



**Function:**

X/Y-gantry system that consists of a double guided X-axis and a vertical Z-axis. Compared to the ELZI series (standard version), the vertical Z-axis is reinforced by a rectangular profile, which absorbs higher torques, ensures greater stability and less deflection. This gantry system is driven by only one single timing belt that runs through various deflection points. The adjustment is realized by two motors whose coordinates are diagonally orientated to these deflection points. Key advantageous: this compact design allows high accelerations due to low movable masses.

- Fitting position:** As required, max. length for x-axes 2000mm, for z-axis 2000mm
- Unit mounting:** By tapped holes in the bearing block, mounting sets.
- Belt type:** HTD with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

Forces and torques	Size		
	60 S		
	<b>Forces/torques</b>		
	static	dynam.	
	$F_x$ (N)	1900	1800
	$F_z$ (N)	1600	1200
	$M_x$ (Nm)	67	43
	$M_y$ (Nm)	190	140
$M_z$ (Nm)	230	170	
<b>All forces and torques relate to the following:</b>			
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$ table values			
<b>No-load torque horizontal movement</b>			
Nm	2 x 1,1		
<b>Speed</b>			
(m/s) max	5		
<b>Tensile force</b>			
Dauer (N)	1900		
0,2 s (N)	2090		
<b>Geometrical moments of inertia of aluminium profile</b>			
$I_x$ mm <sup>4</sup> (X-/Z-Achse)	4,06x10 <sup>5</sup> / 9,6x10 <sup>5</sup>		
$I_y$ mm <sup>4</sup> (X-/Z-Achse)	24,3x10 <sup>5</sup> / 2,8 x10 <sup>6</sup>		
E-Modul N/mm <sup>2</sup>	70000		

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

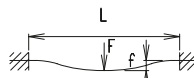
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- $S_i$  = safety factor 1,2 ... 2
- $M_n$  = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- $M_o$  = driving torque (Nm)
- $P_o$  = motor power (KW)

Deflection:

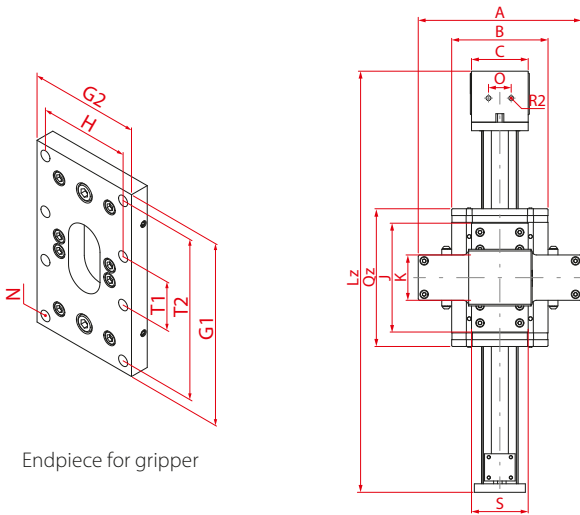
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)

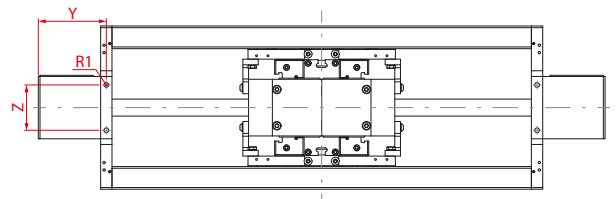
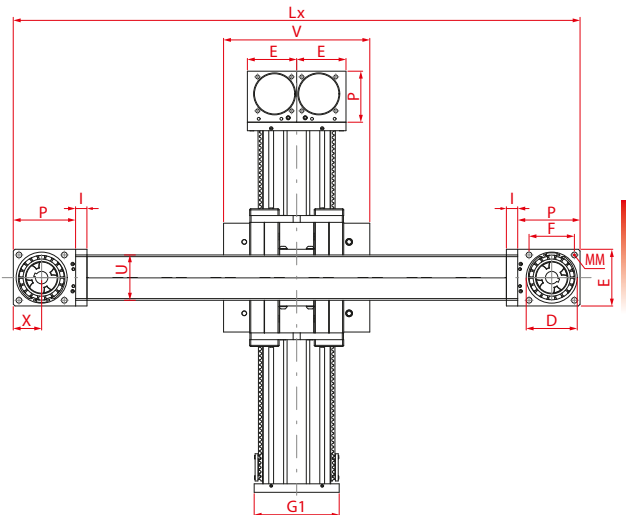


# Linear system **ELZI 60 SW**

Dimensions (mm)



Endpiece for gripper



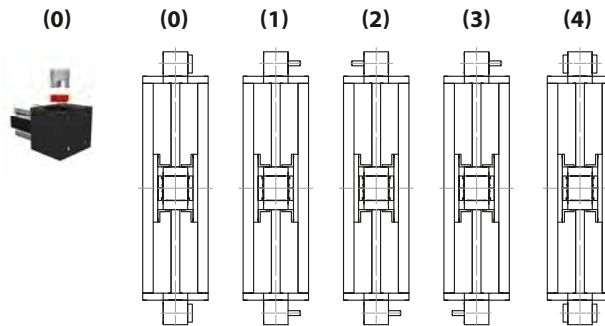
Size	G1	G2	H	N Ø	T1	T2
60 S	150	90	74	8,6	40	132

Size	X-Axis		Z-Axis	
	Profile	moving mass	Profile	moving mass
60 S	2x UL 80	26,3 kg	EL 60	11,7 kg

Size	Basic length		A	B	C	D -0,05	E	F	I	J	K	MM for	O	P	Qz	R1	R2	S	U	X	Y	Z	Basic weight	Weight per 100 mm X-/Z-Achse
	Lx	Lz																						
ELZI 60 SW	540	420	288	170	100	90	100	80	20	195	80	M10	40	110	243	M10	M10	100	80	50	120	80	35 kg	1,15 kg / 0,85 kg

- 0 Choice of guide body profile:**  
 (0) Standard (2) corrosion-protected guide rods and screws  
 (4) expanded corrosion-protected version (depending on the availability of components)

**0 Drive version:**



**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 6	60	8M30	224	28

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
60 S	22x45	6x6x35	24

ELZI 60SW 0 0 0 0 0 6 1 1500 — X-Achse Basic length + stroke = total length

ELZI 60SW 1 0 0 0 0 6 1 700 — Z-Achse Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

ELZI 60-SW, with standard body profile, standard carriage, coupling claw on one side, stroke X = 960 mm / Z = 280 mm

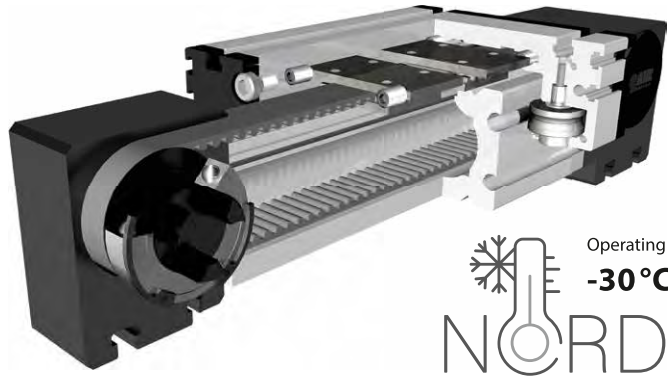
3.1

# Linear system **ELZ-NK 60, 60S, 80, 80S, 100**

## BELT DRIVE - DEEP-FREEZE AREA

- DEEP-FREEZE CONDITIONS
- LONG SERVICE LIFE
- FOOD INDUSTRY
- RELIABILITY

3.1



Operating temperature range  
**-30°C ≤ -10°C**  
**NORDKAP**

**Function:**

Highly dynamic linear unit with toothed belt drive and external roller guides. Reliable and low-maintenance guide system with robust track roller guide, suitable for the intended uses in deep temperature applications. Can be used without restriction in the deep temperature range between -30°C and -10°C. An operating manual is included in the scope of delivery.

**Fitting position:**

As required. Max. length 6.000 mm without joints.

**Carriage mounting:**

By T-slots.

**Unit mounting:**

By T-slots or tapped holes in the bearing block, mounting sets.

**Belt type:**

HTD with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

**Forces and torques**

Size	ELZ 60		ELZ 60 S		ELZ 80		ELZ 80 S		ELZ 100	
	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
F <sub>x</sub> (N)	715	640	715	640	1520	1440	1520	1440	3200	3040
F <sub>y</sub> (N)	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500
F <sub>z</sub> (N)	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200
M <sub>x</sub> (Nm)	67	43	88	65	90	55	170	140	300	230
M <sub>y</sub> (Nm)	90	70	190	140	110	80	270	230	400	270
M <sub>z</sub> (Nm)	120	100	230	170	150	120	300	220	750	500

**All forces and torques relate to the following:**

existing values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

table values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

**Geometrical moments**

I <sub>x</sub> mm <sup>4</sup>	6,79x10 <sup>5</sup>	6,79x10 <sup>5</sup>	18,99x10 <sup>5</sup>	18,99x10 <sup>5</sup>	44,4x10 <sup>5</sup>
I <sub>y</sub> mm <sup>4</sup>	6,97x10 <sup>5</sup>	6,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	44,8x10 <sup>5</sup>
E-Modulus N/mm <sup>2</sup>	70000	70000	70000	70000	70000

**Area of application Nordkap**

Temperature-dependent length adjustment per 1000 mm in mm

ΔL <sub>Aluminium</sub>	ΔT	ΔL <sub>Steel</sub>	ΔL
0,119	5 K	0,080	0,039
0,238	10 K	0,160	0,078
0,357	15 K	0,240	0,117
0,476	20 K	0,320	0,156
0,595	25 K	0,400	0,195
0,714	30 K	0,480	0,234
0,833	35 K	0,560	0,273
0,952	40 K	0,640	0,312
1,071	45 K	0,720	0,351
1,190	50 K	0,800	0,390
1,309	55 K	0,880	0,429
1,428	60 K	0,960	0,468
1,547	65 K	1,040	0,507
1,666	70 K	1,120	0,546

**Speed**

(m/s) max	3	5	5	6	8
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For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

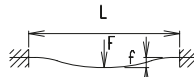
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1, 2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

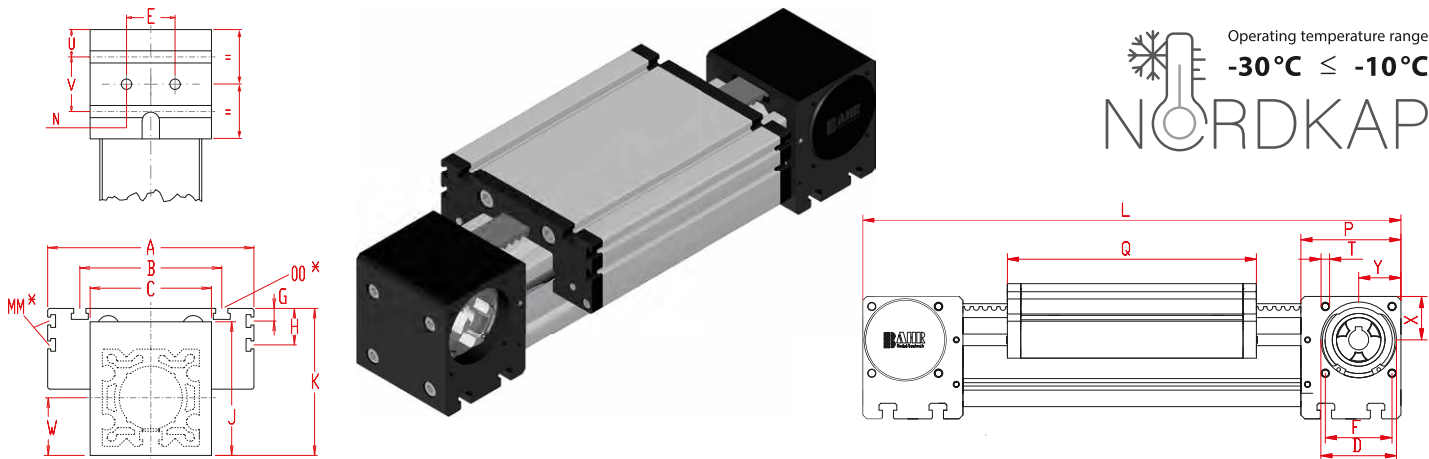
- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)





# Linear system **ELZ-NK 60, 60S, 80, 80S, 100**

Dimensions (mm)



3.1

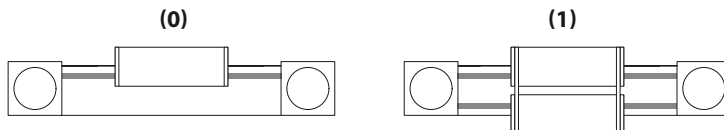
\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	MM for	N	OO for	P	Q	T	U	V	W	X	Y	Basic weight	Weight per 100 mm
60	290	144	96	80	47	30	42	-	-	82	90	-	M 8	M 8	59	168	M 6	15	30	41	27	26	4,8 kg	0,62 kg
60 S	315	170	108	80	47	30	42	-	-	82	94	-	M 8	M 8	59	194	M 6	15	30	41	27	26	5,8 kg	0,62 kg
80	375	170	117	100	68	40	60	10,5	30,5	110	121	M 6	M 10	M 10	90	194	M 8	22,5	45	51	39	38	10,0 kg	1,00 kg
80 S	395	190	126	100	68	40	60	12,5	30	110	122	M 6	M 10	M 8	90	214	M 8	22,5	45	51	39	38	11,0 kg	1,00 kg
100	530	230	155	130	90	50	80	-	29	135	154	M 10	M 12	M 10	110	300	M 10	23	64	65	50	50	24,0 kg	1,60 kg

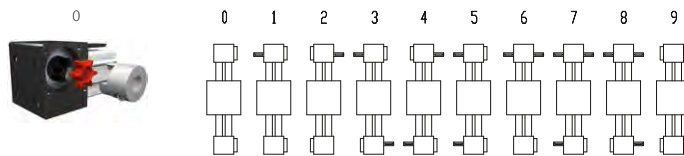
- 0 Choice of guide body profile:**  
 (0) Standard (2) corrosion-protected guide rods and screws  
 (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 1	
	Q	L
60	184	306
60S	214	335
80	210	391
80S	234	415
100	316	546

**0 Drive version:**



Version 9 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 100).

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	60 (S)	5M25	130	26
0 7	80 (S)	8M30	192	24
0 9	100	8M50	256	32

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
60 (S)	14 x 35	5x5x28	14
80 (S)	18 x 45	6x6x40	19
100	22 x 45	6x6x40	24

**ELZ-NK 60 1 0 0 0 0 4 1 1500**

Basic length + stroke = total length

For combination kits and connecting elements refer to chapter 2.2

Sample ordering code:  
 ELZ-NK 60, standard body profile, standard carriage, coupling claw on one side, 1210 mm stroke.

# Linear system **ELZT 40, 60, 60S, 80, 80S, 100**

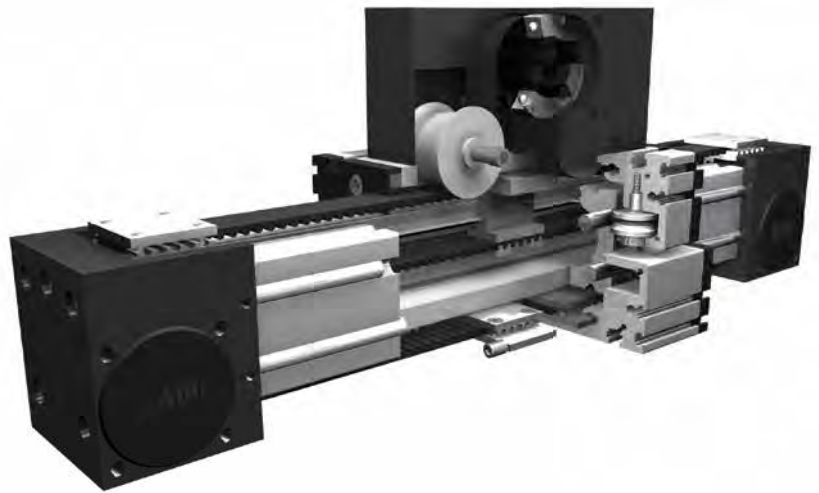
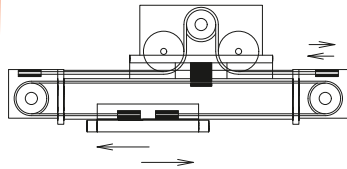
## TELESCOPIC BELT DRIVE

Ω OMEGA SYSTEM

➡ TELESCOPIC SYSTEM

⊥ VERTICAL INSTALLATION POSITION

↔ CANTILEVER AXIS



### Function:

This unit consists of an aluminium square profile with integrated, hardened steel guide rods. Two carriages, which have internal linear ball bearings that can be adjusted free of play, are driven along the guide rods in opposite directions by 2 belts. The pulleys include maintenance-free ball bearings. One belt is tensioned by a tensioning device within the carriage. The other timing belt is tensioned by a tensioning device within the bearing block. The carriage with the drive block (with motor) is screwed to the crosshead.

### Fitting position:

Vertical, conditionally horizontal; Max. length 3.000 mm.

### Unit mounting:

By T-slots in the carriage, extension arm

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

Forces and torques	Size	ELZT 40		ELZT 60		ELZT 60 S		ELZT 80		ELZT 80 S		ELZT 100	
	Forces/torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
$F_x$ (N)		360	300	580	470	580	470	1800	1570	1800	1570	4000	3500
$F_y$ (N)		1200	700	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500
$F_z$ (N)		900	650	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200
$M_x$ (Nm)		25	20	67	43	88	65	90	55	170	140	300	230
$M_y$ (Nm)		32	18	90	70	190	140	110	80	270	230	400	270
$M_z$ (Nm)		35	25	120	100	230	170	150	120	370	310	750	500
<b>All forces and torques relate to the following:</b>													
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$													
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$													
<b>No-load torque</b>													
Nm		0,9		1,1		1,1		1,3		1,2		2,4	
<b>Speed</b>													
(m/s) max		4		5		7		6		8		8	
<b>Tensile force</b>													
permanent (N)		360		580		580		1800		1800		4000	
0,2 s (N)		450		700		700		2200		2200		4300	
<b>Geometrical moments of inertia of aluminium profile</b>													
$I_x$ mm <sup>4</sup>		1,32x10 <sup>5</sup>		6,79x10 <sup>5</sup>		6,79x10 <sup>5</sup>		18,99x10 <sup>5</sup>		18,99x10 <sup>5</sup>		44,4x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		1,34x10 <sup>5</sup>		6,97x10 <sup>5</sup>		6,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		44,8x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000		70000		70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

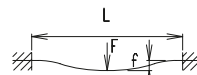
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

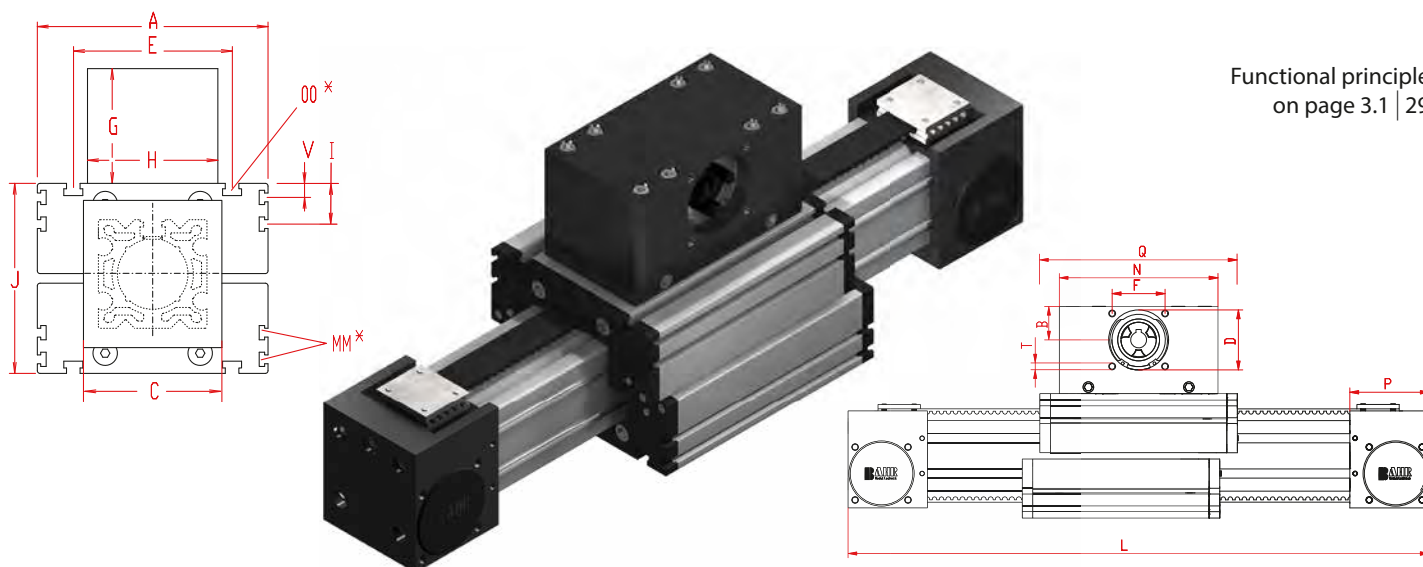
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **ELZT 40, 60, 60S, 80, 80S, 100**

Dimensions (mm)



3.1

\*For slide nuts refer to chapter 2.2 page 2

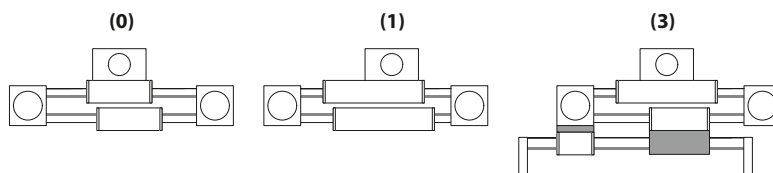
Increasing the carriage length will increase the basic length by the same amount.

Size □	Basic length L	A	B	C	D -0,05	F	G	H	I	J	MM for	N	OO for	P	Q	T	V	Basic weight	Weight per 100 mm
ELZT 40	265	100	30	58	47	42	83	80	-	70	-	130	M 6	49	164	M 6	-	3,6 kg	0,31 kg
ELZT 60	345	144	39	80	68	60	105	100	-	98	-	180	M 8	59	218	M 8	-	9,1 kg	0,73 kg
ELZT 60S	370	170	39	80	68	60	105	100	-	106	-	180	M 8	59	220	M 8	-	10,1 kg	0,73 kg
ELZT 80	494	170	60	100	90	80	140	130	30,5	140	M 6	270	M 10	90	304	M 10	10,5	24,0 kg	1,14 kg
ELZT 80S	494	190	60	100	90	80	140	130	30	142	M 6	270	M 8	90	304	M 10	12,5	26,0 Kg	1,14 kg
ELZT 100	570	230	62	130	110	100	143	160	29	178	M 10	310	M 10	110	350	M 10	-	40,6 kg	1,95 kg

**0 Choice of guide body profile:**

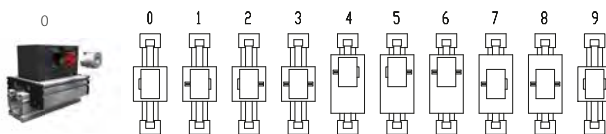
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 1		Version 3	
	Q	L	Q	L
40	257	360	257	360
60	353	480	353	480
60S	379	506	379	506
80	469	659	469	659
80S	489	679	489	679
100	575	795	575	795

**0 Drive version:**



The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 80 + 100). Version 9 is the same as 0, but with double sided coupling claw.

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	40	5M25	130	26
0 7	60 (S)	8M30	192	24
0 9	80 (S)	8M50	256	32
1 0	100	8M70	304	38

**Shaft dimensions / Coupling Claw:**

Size	Shaft ø h6 x length	Key	Coupling
40	14 x 35	5x5x28	14
60 (S)	18 x 45	6x6x40	19
80 (S)	22 x 45	6x6x40	24
100	30 x 55	8x7x40	28

**ELZT 60 6 0 0 0 0 4 1 1500**

Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

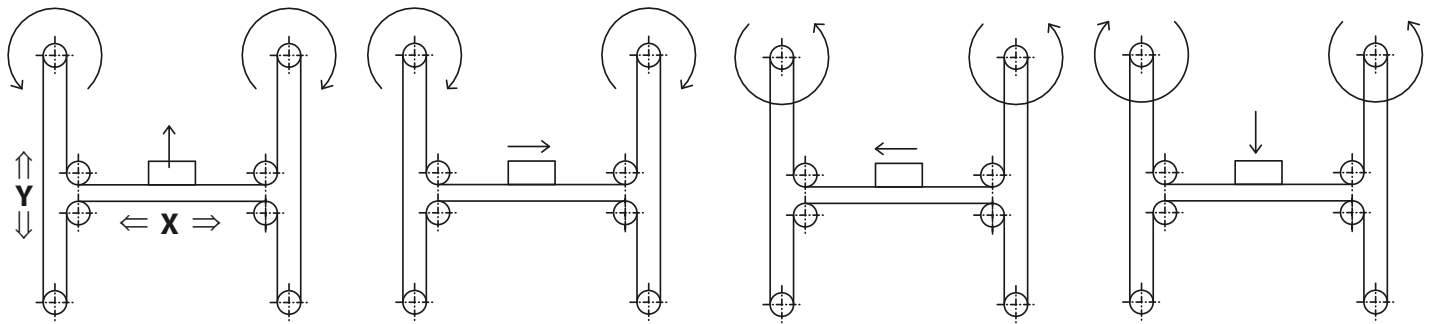
Sample ordering code:

ELZT 60 with standard body profile, standard carriage and coupling claw on one side, 2310 mm stroke

For combination kits and connecting elements refer to chapter 2.2

# Linear system **ELZU 30, 40, 60, 60S, 80, 80S, 100**

## SURFACE PORTAL

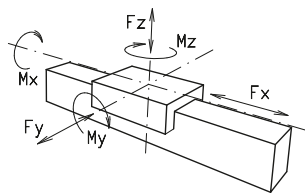


### Function:

Surface portal, consisting of 2 Y-axes and 1 X-axis, driven by one rotating belt. This belt runs around different deflection pulleys. Positioning is achieved by two motors. The coordinate is diagonal to the deflection points of the Y-axis.

Advantage: Only small weights are moved, thus enabling high accelerations to be achieved.

### Forces and torques



### Fitting position:

As required. Max. length and width 3.000 mm.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots or tapped holes in the bearing block, mounting sets.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability:  $\pm 0,1$  mm.

Size	ELZU 30		ELZU 40		ELZU 60		ELZU 60 S		ELZU 80		ELZU 80 S		ELZU 100	
Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
$F_x$ (N)	200	180	390	350	894	800	894	800	1900	1800	1900	1800	4000	3800
$F_y$ (N)	90	60	1200	700	3000	2000	4100	3100	3000	2000	4600	3600	8000	6500
$F_z$ (N)	90	60	900	650	1700	1100	2160	1600	1700	1100	3000	1800	3600	2200
$M_x$ (Nm)	10	5	25	20	67	43	88	65	90	55	170	140	300	230
$M_y$ (Nm)	13	6	32	18	90	70	190	140	110	80	270	230	400	270
$M_z$ (Nm)	14	7	35	25	120	100	230	170	150	120	300	220	750	500

**All forces and torques relate to the following:**

existing values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

table values  $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$

No-load torque							
Nm	0,2	0,6	1,2	1,2	1,8	1,8	2,6
Speed							
(m/s) max	2	4	5	5	6	6	8
Tensile force							
permanent (N)	200	390	900	900	1900	1900	3600
0,2 s (N)	280	480	1000	1000	2090	2090	4000
Geometrical moments of inertia of aluminium profile							
$I_x$ mm <sup>4</sup>	4,09x10 <sup>4</sup>	1,32x10 <sup>5</sup>	6,79x10 <sup>5</sup>	6,79x10 <sup>5</sup>	18,99x10 <sup>5</sup>	18,99x10 <sup>5</sup>	44,4x10 <sup>5</sup>
$I_y$ mm <sup>4</sup>	4,00x10 <sup>4</sup>	1,34x10 <sup>5</sup>	6,97x10 <sup>5</sup>	6,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	18,97x10 <sup>5</sup>	44,8x10 <sup>5</sup>
E-Modulus N/mm <sup>2</sup>	70000	70000	70000	70000	70000	70000	70000

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

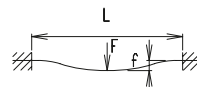
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

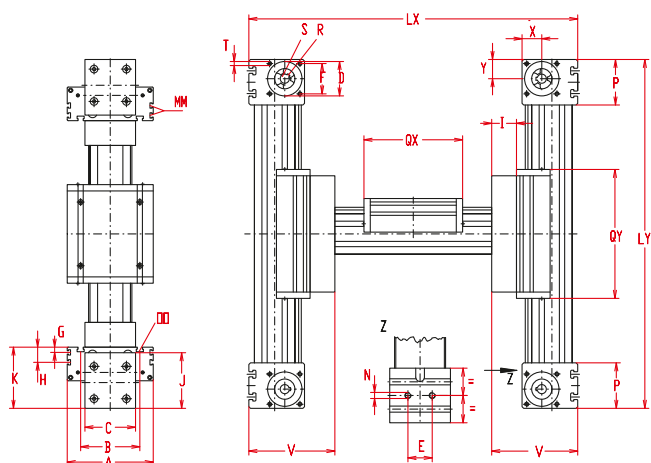
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **ELZU 30, 40, 60, 60S, 80, 80S, 100**

Dimensions (mm)



3.1

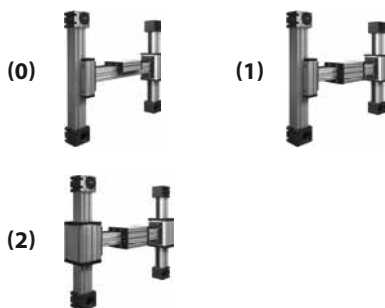
\*For slide nuts refer to chapter 2.2 page 2

Size	Basic length		A	B	C	D -0,05	E	F	G	H	I	J	K	MM for	N for	OO for	P	Qx	Qy	T	V	X	Y	Basic weight	Weight per 100 mm
	Lx	Ly																							
ELZU 30	240	210	70	56	42	28	13	25	-	-	27	44	47	-	M 5	M 6	36	82	126	M 5	74	16	16	6,3 kg	0,13 kg
ELZU 40	304	250	100	66	58	37	18	32	-	-	26	58	64	-	M 6	M 6	49	122	147	M 5	90	20,5	20,5	6,8 kg	0,24 kg
ELZU 60	426	330	144	96	80	47	30	42	-	-	33	82	90	-	M 8	M 8	59	168	210	M 6	123	27	26	14,7 kg	0,62 kg
ELZU 60S	450	330	170	108	80	47	30	42	-	-	33	82	94	-	M 8	M 8	59	194	210	M 6	127	27	26	17,7 kg	0,62 kg
ELZU 80	535	435	170	117	100	68	40	60	10,5	30,5	44	110	121	M 6	M 10	M 10	90	194	244	M 8	165	39	38	31,0 kg	1,00 kg
ELZU 80S	555	455	190	126	100	68	40	60	12,5	30	44	110	122	M 6	M 10	M 8	90	214	264	M 8	166	39	38	32,0 kg	1,00 kg
ELZU 100	758	590	230	155	130	90	50	80	-	29	69	135	154	M 10	M 12	M 10	110	300	360	M 10	223	50	50	47,3 kg	1,40 kg

## 0 Choice of guide body profile:

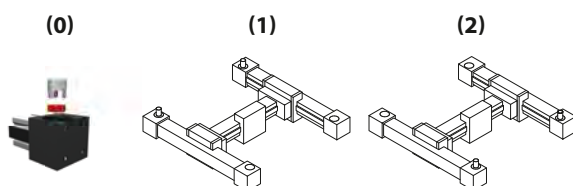
- (0) Standard (2) corrosion-protected guide rods and screws  
(4) expanded corrosion-protected version (depending on the availability of components)

## 0 Choice of carriages:



Size	Version 1				Version 2			
	Qx	Lx	Qy	Ly	Qx	Lx	Qy	Ly
30	94	252	126	210	94	252	138	222
40	138	320	147	250	138	320	163	266
60	184	442	210	330	184	442	226	346
60S	214	468	210	330	214	468	230	350
80	210	551	244	435	210	551	260	451
80S	234	575	264	455	234	575	284	475
100	316	774	360	590	316	774	376	606

## 0 Drive version:



The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings.

## Belt table:

Code No.	Size	Belt	mm/rev.	Number of teeth
0 1	30	3M12	75	25
0 3	40	5M15	100	20
0 4	60 (S)	5M25	130	26
0 7	80 (S)	8M30	192	24
0 9	100	8M50	256	32

## Shaft dimensions / Coupling claw:

Size	Shaft ø h6 x length	Key	Coupling
30	6 x 15	2x2x12	7
40	10 x 27	3x3x25	9
60 (S)	14 x 35	5x5x28	14
80 (S)	18 x 45	6x6x40	19
100	22 x 45	6x6x40	24

ELZU 60 7 0 0 0 0 4 1 1500

ELZU 60 8 0 0 0 0 4 1 700

Pos. 1 2 3 4 5 6 7

X-Axis Basic length + stroke = total length

Y-Axes Basic length + stroke = total length

Sample ordering code:

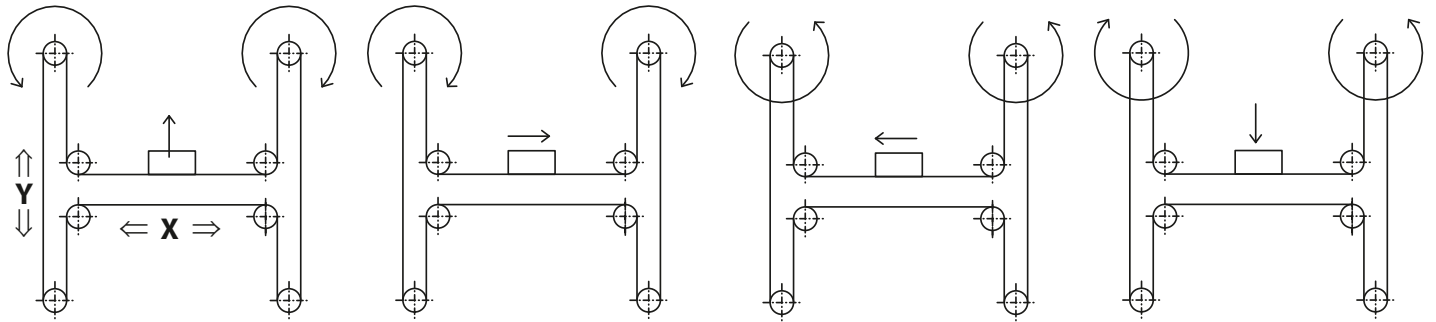
ELZU 60 with standard body profile, standard carriage, coupling claw on one side, stroke X = 1074 / Y = 370 mm

For combination kits and connecting elements refer to chapter 2.2

# Linear system **ELZU 60 S W**

## SURFACE PORTAL - STRENGTHENED CONSTRUCTION

3.1



**Function:**

Surface gantry consisting of two Y axes and one X axis. The unit is driven by a rotating belt, which remains connected through various deflection points. Due to the rectangular profile high torques and loads can be taken up. In addition, a very high stability and low deflection are ensured for long axis systems. The belt tension can be easily readjusted via a tensioning device within the carriage. The movement is realised by two motors. The coordinate lies diagonal to the deflection points of the X axis. Advantage: Only small masses are moved and thus it is possible to achieve high accelerations.

**Fitting position:**

As required. Max. length and width 3.000 mm.

**Carriage mounting:**

By T-slots.

**Unit mounting:**

By T-slots or tapped holes in the bearing block, mounting sets.

**Belt type:**

HTD with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

Forces and torques	Size		
	60 S		
	<b>Forces/Torques</b>		
		static	dynamic
	$F_x$ (N)	894	800
	$F_y$ (N)	4100	3100
	$F_z$ (N)	2160	1600
	$M_x$ (Nm)	88	65
	$M_y$ (Nm)	190	140
$M_z$ (Nm)	230	170	
<b>All forces and torques relate to the following:</b>			
existing values	$\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$		
table values			
<b>No-load torque</b>			
Nm	1,2		
<b>Speed</b>			
(m/s) max	5		
<b>Tensile force</b>			
permanent (N)	900		
0,2 s (N)	1000		
<b>Geometrical moments of inertia of aluminium profile - Y-Axis</b>			
$I_y$ mm <sup>4</sup>	6,79x10 <sup>5</sup>		
$I_z$ mm <sup>4</sup>	6,97x10 <sup>5</sup>		
E-Modul N/mm <sup>2</sup>	70000		
<b>Geometrical moments of inertia of aluminium profile - X-Axis</b>			
$I_x$ mm <sup>4</sup>	2,8 x 10 <sup>6</sup>		
$I_y$ mm <sup>4</sup>	9,6 x 10 <sup>5</sup>		
E-Modulus N/mm <sup>2</sup>	70000		

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

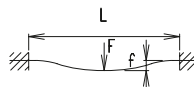
$$P_o = \frac{M_o \cdot n}{9550}$$

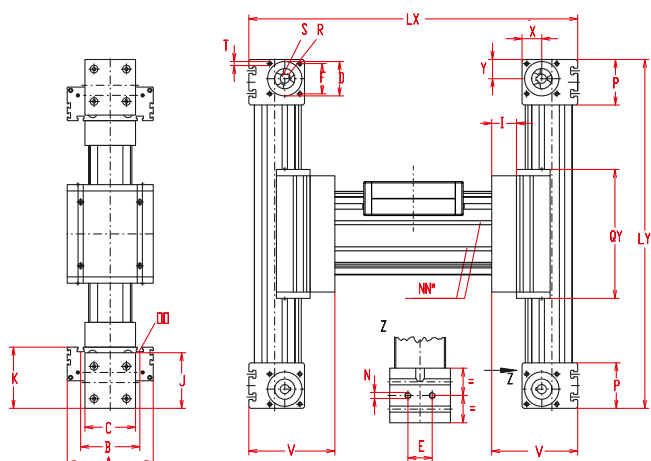
- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)





\*For slide nuts refer to chapter 2.2 page 2

Size	Basic length		A	B	C	D -0,05	E	F	I	J	K	N for	NN for	OO for	P	Qx	Qy	T	V	X	Y	Basic weight	Weight per 100 mm
	Lx	Ly																					
ELZU 60 S W	450	400	170	108	80	47	30	42	33	82	94	M 8	M 5	M 8	59	194	280	M 6	127	27	26	17,9 kg	0,9 kg

#### 0 Choice of guide body profile:

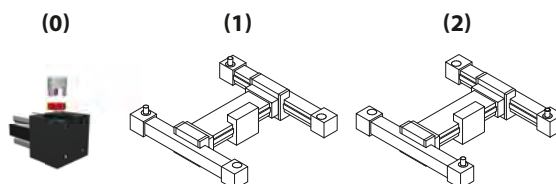
- (0) Standard (2) corrosion-protected guide rods and screws  
(4) expanded corrosion-protected version (depending on the availability of components)

#### 0 Choice of carriages:



Size	Version 1				Version 2			
	Qx	Lx	Qy	Ly	Qx	Lx	Qy	Ly
60 S	214	470	280	400	214	470	300	420

#### 0 Drive version:



The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings.

#### Belt table:

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	60 S	5M25	130	26

#### Shaft dimensions / Coupling claw:

Size	Shaft ø h6 x length	Key	Coupling
60 S	14 x 35	5x5x28	14

**X-Axis** Basic length + stroke = total length  
**Y-Axes** Basic length + stroke = total length

ELZU 60S W 7 0 0 0 0 4 1 01500

ELZU 60S W 8 0 0 0 0 4 1 00700

Pos. 1 2 3 4 5 6 7




Sample ordering code:

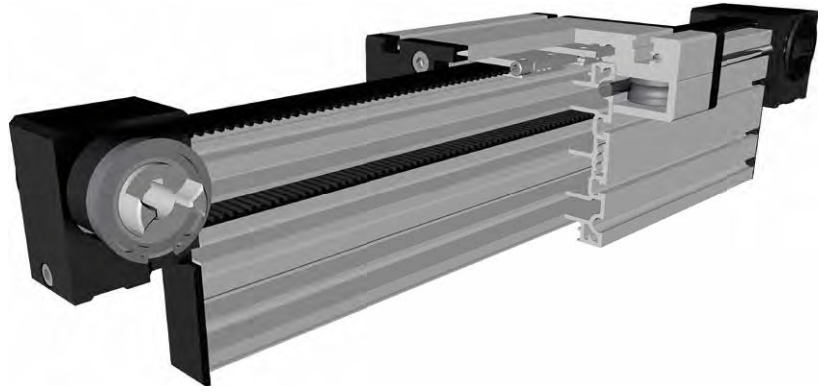
ELZU 60S W, standard body profile, standard carriage, coupling claw on one side, stroke X = 1080 / Y = 298 mm

For combination kits and connecting elements refer to chapter 2.2

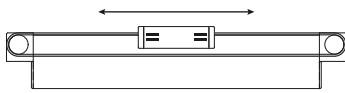
# Linear system **ELZ 60 (S) W**

## BELT DRIVE

-  HIGHER PROFILE STABILITY
-  HIGHER FORCE FIXTURE
-  LONG TRAVERSE PATH



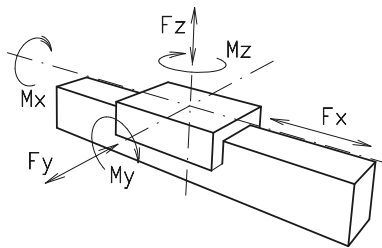
3.1



**Function:**

The guide body consists of an aluminium square profile with lateral, parallel, form-fit, internal hardened steel rods. The guide carriage, which is driven along the shafts by a timing belt, moves on the guide body with internal linear ball bearings that are adjustable free of play. Due to the rectangular profile high torques and loads can be taken up. In addition, a very high stability and low deflection are ensured for long axis systems. The belt tension can be easily readjusted via a tensioning device within the carriage. This device also helps to adjust the symmetry of the carriages in applications where two parallel linear units are used.

- Fitting position:** As required. Max. length 3.000 mm without joints.
- Carriage mounting:** By T-slots.
- Unit mounting:** By T-slots or tapped holes in the bearing block, mounting sets.
- Belt type:** HTD with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

Forces and torques	Size	60		60 S	
	Forces/Torques	static	dynamic	static	dynamic
	$F_x$ (N)	894	800	894	800
	$F_y$ (N)	3000	2000	4100	3100
	$F_z$ (N)	1700	1100	2160	1600
	$M_x$ (Nm)	67	43	88	65
	$M_y$ (Nm)	90	70	190	140
	$M_z$ (Nm)	120	100	230	170
<b>All forces and torques relate to the following:</b>					
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$					
table values					
<b>No-load torque</b>					
Nm	0,6		0,7		
<b>Speed</b>					
(m/s) max	5		7		
<b>Tensile force</b>					
permanent (N)	900		900		
0,2 s (N)	1000		1000		
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_x$ mm <sup>4</sup>	2,8 x 10 <sup>6</sup>		2,8 x 10 <sup>6</sup>		
$I_y$ mm <sup>4</sup>	9,6 x 10 <sup>5</sup>		9,6 x 10 <sup>5</sup>		
E-Modulus N/mm <sup>2</sup>	70000		70000		

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

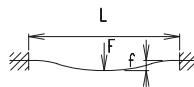
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- $S_i$  = safety factor 1,2 ... 2
- $M_n$  = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- $M_o$  = driving torque (Nm)
- $P_o$  = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

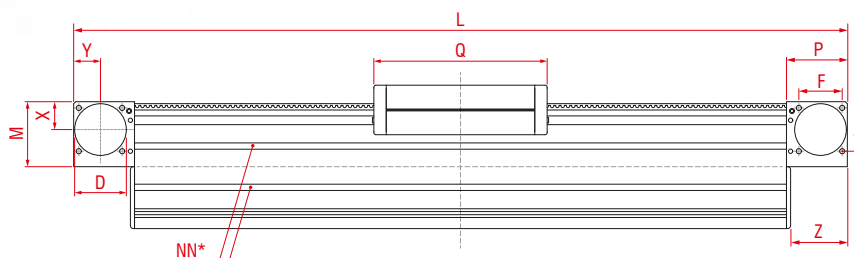
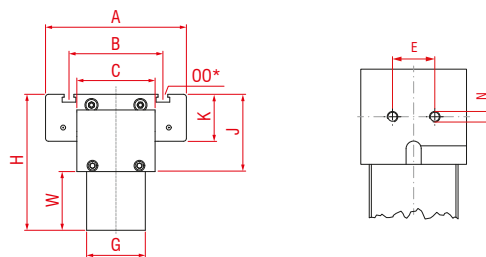
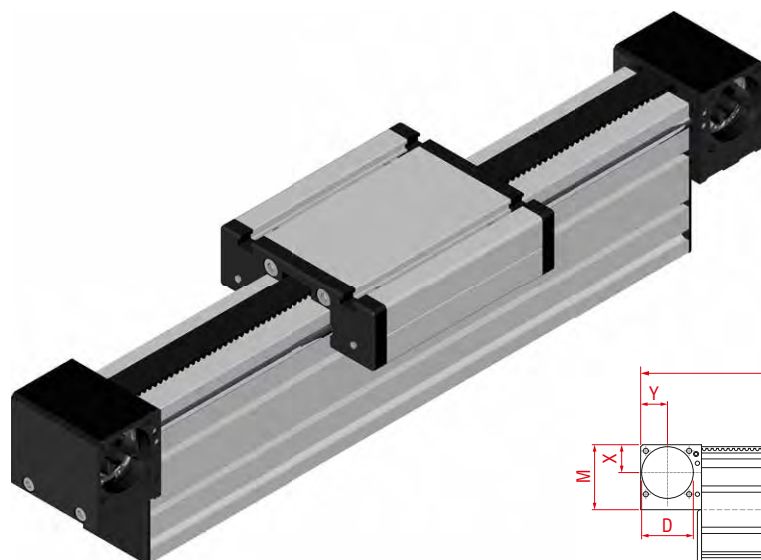
- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)





# Linear system **ELZ 60 (S) W**

Dimensions (mm)



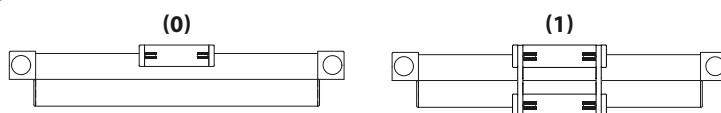
\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	M	N	NN for	OO for	P	Q	T	W	X	Y	Z	Basic weight	Weight per 100 mm
<b>ELZ 60 W</b>	290	144	96	80	47	30	42	60	139	79	48	71	M8	M5	M8	59	168	M6	60	27	26	55	5,4 kg	0,8 kg
<b>ELZ 60S W</b>	315	170	108	80	47	30	42	60	143	83	52	71	M8	M5	M8	59	194	M6	60	27	26	55	6,4 kg	0,8 kg

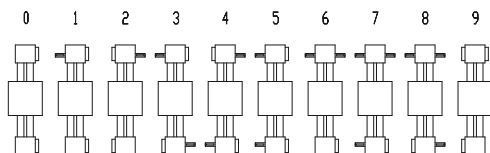
- 0** Choice of guide body profile:  
**(0)** Standard **(2)** corrosion-protected guide rods and screws  
**(4)** expanded corrosion-protected version (depending on the availability of components)

**0** Choice of carriages:



Size	Version 1	
	Q	L
<b>60</b>	184	306
<b>60 S</b>	214	335

**0** Drive version:



Version 9 is the same as 0, but with double sided coupling claw.

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
<b>0 4</b>	<b>60 (S)</b>	5M25	130	26

**Shaft dimensions / Coupling claw:**

Size	Shaft $\varnothing$ h6 x length	Key	Coupling
<b>60 (S)</b>	14 x 35	5x5x28	14

**ELZ 60 W 1 0 0 0 0 4 1 1500**





Basic length + stroke = total length

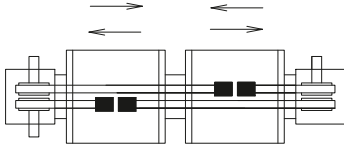
For combination kits and connecting elements refer to chapter 2.2

Sample ordering code:  
 ELZ 60 W, standard body profile, standard carriage, coupling claw on one side, 1210 mm stroke

# Linear system **ELZZ 60, 60S, 80, 80S, 100, 125**

## BELT DRIVE - TWO SEPARATELY DRIVEN CARRIAGES

-  UNIVERSAL SYSTEM
-  INDEPENDENT CARRIAGES
-  HIGHER FORCE FIXTURE
-  COMPACT DESIGN



**Function:**

This linear unit consists of an aluminium square profile with integrated, hardened steel guide rods. Each carriage can be moved separately by its own drive. This unit has twin pulleys, which run on separate bearings, and two independent, parallel drive belts, one for each carriage.

**Fitting position:**

As required. Max. length 4.000 mm without joints.

**Carriage mounting:**

By T-slots.

**Unit mounting:**

By T-slots or tapped holes in the bearing block, mounting sets.

**Belt type:**

HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.

Forces and torques	Size	ELZZ 60		ELZZ 60 S		ELZZ 80		ELZZ 80 S		ELZZ 100		ELZZ 125	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
$F_x$ (N)		298	250	298	250	679	500	679	500	1210	1100	1900	1800
$F_y$ (N)		3000	2000	4100	3100	3000	2000	4600	3600	8000	6500	12000	9000
$F_z$ (N)		1700	1100	2160	1600	1700	1100	3000	2600	3600	2200	6000	4500
$M_x$ (Nm)		67	43	88	65	90	55	170	140	300	230	600	450
$M_y$ (Nm)		90	70	190	140	110	80	270	230	400	270	750	600
$M_z$ (Nm)		120	100	230	170	150	120	300	220	750	500	1350	1150
<b>All forces and torques relate to the following:</b>													
existing values		$\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$											
table values													
<b>No-load torque</b>													
Nm		0,6		0,7		0,9		1,2		1,4		1,8	
<b>Speed</b>													
(m/s) max		5		5		6		8		10		10	
<b>Tensile force</b>													
permanent (N)		298		298		679		679		1210		1900	
0,2 s (N)		333		333		746		746		1331		2090	
<b>Geometrical moments of inertia of aluminium profile</b>													
$I_x$ mm <sup>4</sup>		6,79x10 <sup>5</sup>		6,79x10 <sup>5</sup>		18,99x10 <sup>5</sup>		18,99x10 <sup>5</sup>		44,4x10 <sup>5</sup>		101,5x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		6,97x10 <sup>5</sup>		6,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		18,97x10 <sup>5</sup>		44,8x10 <sup>5</sup>		101,5x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000		70000		70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

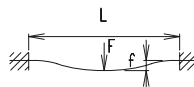
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

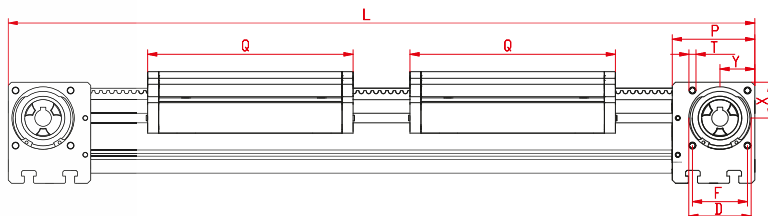
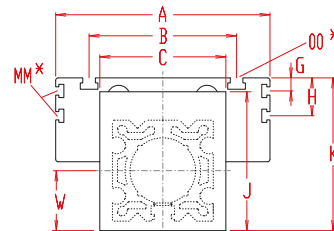
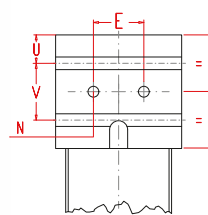
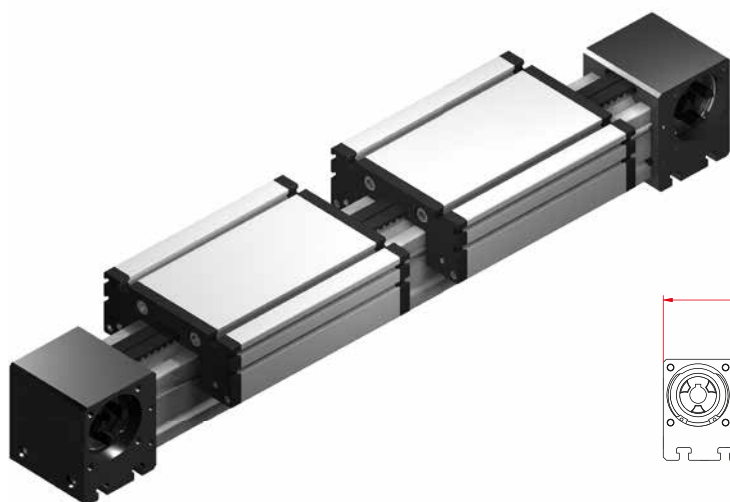
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Linear system ELZZ 60, 60S, 80, 80S, 100, 125

Dimensions (mm)



3.1

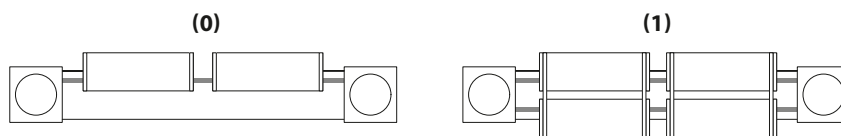
\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size □	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	MM for	N	OO for	P	Q	T	U	V	W	X	Y	Basic weight	Weight per 100 mm
ELZZ 60	460	144	96	80	47	30	42	-	-	82	90	-	M 8	M 8	59	168	M 6	15	30	41	27	26	7,4 kg	0,62 kg
ELZZ 60S	510	170	108	80	47	30	42	-	-	82	94	-	M 8	M 8	59	194	M 6	15	30	41	27	26	9,4 kg	0,62 kg
ELZZ 80	570	170	117	100	68	40	60	10,5	30,5	110	121	M 6	M 10	M 10	90	194	M 8	22,5	45	51	39	38	12,8 kg	1,00 kg
ELZZ 80S	610	190	126	100	68	40	60	12,5	30	110	122	M 6	M 10	M 8	90	214	M 8	22,5	45	51	39	38	14,8 kg	1,00 kg
ELZZ 100	830	230	155	130	90	50	80	-	29	135	154	M 10	M 12	M 10	110	300	M 10	23	64	65	50	50	33,0 kg	1,60 kg
ELZZ 125	990	295	200	160	110	60	100	-	30	167	191	M 10	M 12	M 12	130	365	M 10	38	50	82	60	60	52,0 kg	2,10 kg

**0** Choice of guide body profile:  
**(0)** Standard **(2)** corrosion-protected guide rods and screws

**0** Choice of carriages:

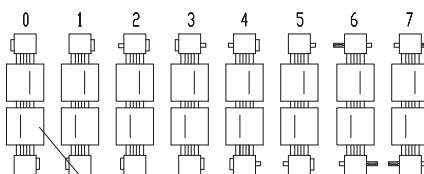


Size	Version 1	
	Q	L
60	184	492
60S	214	550
80	210	602
80S	234	650
100	316	862
125	389	1038

**0** Drive version:



The standard version is supplied without shaft.



connected with the left belt

- Coupling claw on one side
- Standard-shaft<sup>1</sup>
- Shaft one size smaller<sup>2</sup>

**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 2	60 (S)	5M09	130	26
0 5	80 (S)	8M12	192	24
0 6	100	8M20	256	32
0 7	125	8M30	304	38

**Shaft dimensions / Coupling claw:**

Size	Shaft ø h6 x length	Key	Coupling
60 (S) <sup>1</sup>	14 x 35	5x5x30	14
60 (S) <sup>2</sup>	10 x 27	3x3x25	14
80 (S) <sup>1</sup>	18 x 45	6x6x40	19
80 (S) <sup>2</sup>	14 x 35	5x5x28	19
100 <sup>1</sup>	22 x 45	6x6x40	24
100 <sup>2</sup>	18 x 45	6x6x40	24
125 <sup>1</sup>	30 x 55	8x7x50	28
125 <sup>2</sup>	22 x 45	6x6x40	28

**ELZZ 60 4 0 0 0 0 2 1 1500**

Pos. 1 2 3 4 5 6 7

Basic length + stroke = total length





For combination kits and connecting elements refer to chapter 2.2

Sample ordering code:

ELZZ 60 with standard body profile, standard carriage and coupling claw on one side, 1040 mm stroke

# Linear system **LLN 60, 80**

## BELT DRIVE

-  LOW OPERATING VOLUME
-  INDEPENDENT INSTALLATION POSITION
-  NUBBED BELT
-  LOW-VIBRATION RUN



### Function:

The guide body consists of an aluminium square profile, with an integrated roller guide. The carriage is moved by a revolving interior nubbed belt. The advantage of this system: The belt is guided within the profile, so that the system is independent of the mounting position. The nubbed belt is self-tracking and has a very low operating noise level thanks to its nobs being offset by 45°. Furthermore, it is almost vibration-free in the transition sections. At the front face there is a timing belt deflection unit containing a toothed pulley with two coupling claws in the standard version. On the opposite side there is a bearing piece plate containing a tensioning device for the timing belt.

### Mounting position:

Variable, max. one-piece-length: 6.000 mm.

### Carriage connection:

By threaded holes.

### Fixation:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

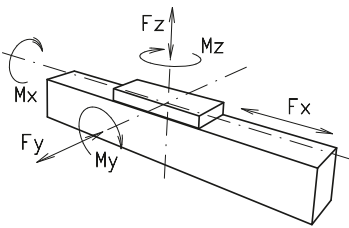
### Timing belt:

N10 with reinforcing steel mesh, no backlash when changing direction, repeatability  $\pm 0.1$  mm.

### Carriage support:

The carriage runs on 5 rollers which can be adjusted and serviced at each central servicing position. Two grease nipples at the carriage enable relubrication of the positioning system.

### Forces and torques



Size	60		80	
	static	dynamic	static	dynamic
<b>Forces/Torques</b>				
$F_x$ (N)	1073	960	1900	1800
$F_y$ (N)	780	650	1900	1500
$F_z$ (N)	1170	845	2100	1700
$M_x$ (Nm)	20	13	85	60
$M_y$ (Nm)	78	65	140	110
$M_z$ (Nm)	52	39	110	90
<b>All forces and torques related to the following:</b>				
existing values	$\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$			
table values				
<b>No-load torque</b>				
Nm	0,6		0,8	
<b>Speed</b>				
(m/s) max	6		10	
<b>Geometrical moments of inertia of aluminium profile</b>				
$I_x$ mm <sup>4</sup>	4,47x10 <sup>5</sup>		15,83x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>	5,59x10 <sup>5</sup>		20,68x10 <sup>5</sup>	
Elastic modulus N/mm <sup>2</sup>	70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

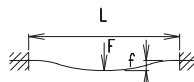
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 Si = safety factor 1,2 ... 2  
 Mn = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 Mo = driving torque (Nm)  
 Po = motor power (KW)

Deflection:

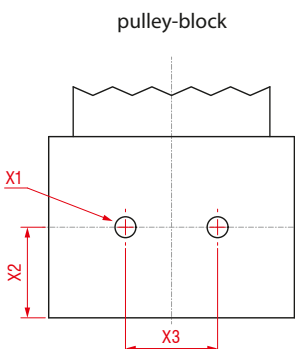
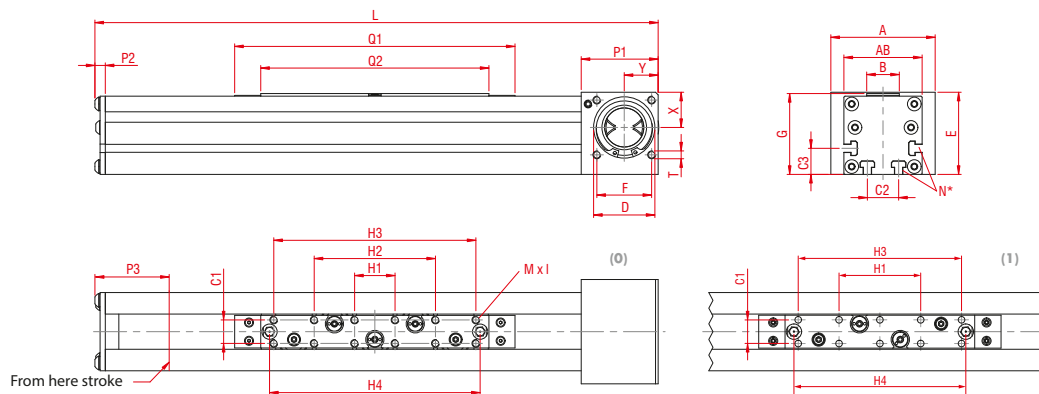
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)

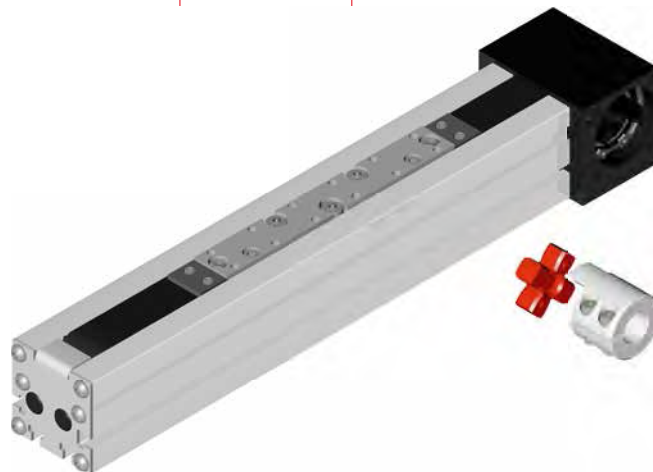


# Linear system LLN 60, 80

Dimensions (mm)



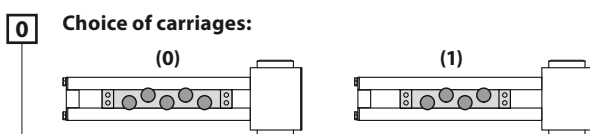
Size	X1	X2	X3
LL 60	M8	29,5	30
LL 80	M10	47,5	40



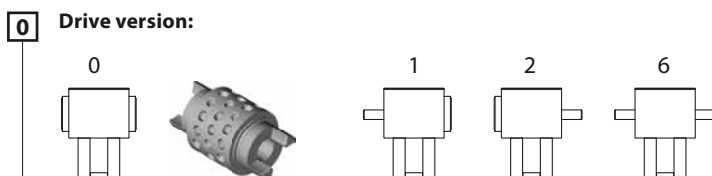
\*For slide nuts refer to chapter 2.2 page 2

Size	Basic length L	A	AB	B	C1	C2	C3	D -0,05	E	F	G	M	N for	P1	P2	P3	T	X	Y	Basic weight	Weight per 100 mm
LLN 60	330	80	60	25	18	24	20	47	63	42	62,5	M6x6	M5	59	6	55	M6	27	26	2,75 kg	0,41 kg
LLN 80	495	100	80	25	18	30	22	68	93	60	83	M6x10	M6	90	9	84	M8	45	40	8,45 kg	0,90 kg

**0** Choice of guide body profile:  
 (0) Standard (2) corrosion-protected guide rods and screws  
 (4) expanded corrosion-protected version (depending on the availability of components)



Carriage	L	Q1	Q2	H1	H2	H3	H4
LL 60 Vers. (0)	330	215	171	31	93	155	161,5
LL 60 Vers. (1)	299	184	140	62	---	124	130,5
LL 80 Vers. (0)	495	320	245	30	90	150	228
LL 80 Vers. (1)	435	260	185	40	---	120	168



**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 8	60	Nubbed belt N10	130	13
0 8	80	Nubbed belt N10	176	18

**Shaft dimensions / Coupling claw:**

Size	Shaft Ø h6 x length	Feather key	Coupling
60	14 x 35	5x5x28	14
80	18 x 45	6x6x45	19

**LLN 60 1 0 0 0 0 8 1 1500** — Basic length + stroke = total length  
 Pos. 1 2 3 4 5 6 7

Sample ordering code:  
 LLN60, standard body profile, double-sided coupling claw, 1170 mm stroke

11.1

# Linear system **LLZ 40, 60, 80, 100**

## BELT DRIVE

 INDEPENDENT INSTALLATION POSITION

 LONG TRAVERSE PATH > 6000 MM

 INTERNAL GUIDE

 SIMPLE & SOLID



### Function:

The guide body consists of an aluminium square profile, with an integrated roller guide. The carriage is moved by means of an internal rotating toothed belt. On one end there is a pulley block with coupling claws on both sides (standard version). On the opposite end there is a plate with a retensioning device for the toothed belt.

### Fitting position:

As required. Max. length 6.000 mm without joints.

### Carriage mounting:

By tapped holes.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

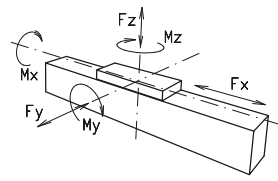
### Belt performance:

HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.

### Carriage support:

The carriage runs on 5 rollers which can be adjusted and serviced at each central servicing position. Two grease nipples at the carriage enable relubrication of the positioning system.

11.1

Forces and torques	Size	40		60		80		100	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic
	F <sub>x</sub> (N)	800	250	1073	960	1900	1800	4000	3800
	F <sub>y</sub> (N)	130	65	780	650	1900	1500	1900	1500
	F <sub>z</sub> (N)	400	210	1170	845	2100	1700	2100	1700
	M <sub>x</sub> (Nm)	3	1	20	13	85	60	85	60
	M <sub>y</sub> (Nm)	13	6	78	65	140	110	150	110
	M <sub>z</sub> (Nm)	24	12	52	39	110	90	120	90
<b>All forces and torques related to the following:</b>									
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$									
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$									
<b>No-load torque</b>									
	Nm	0,4		0,6		0,8		1,2	
<b>Speed</b>									
	(m/s) max	4		6		10		10	
<b>Geometrical moments of inertia of aluminium profile</b>									
	I <sub>x</sub> mm <sup>4</sup>	1,01x10 <sup>5</sup>		4,47x10 <sup>5</sup>		15,83x10 <sup>5</sup>		35,51x10 <sup>5</sup>	
	I <sub>y</sub> mm <sup>4</sup>	1,31x10 <sup>5</sup>		5,59x10 <sup>5</sup>		20,68x10 <sup>5</sup>		46,41x10 <sup>5</sup>	
	Elastic modulus N/mm <sup>2</sup>	70000		70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

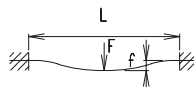
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

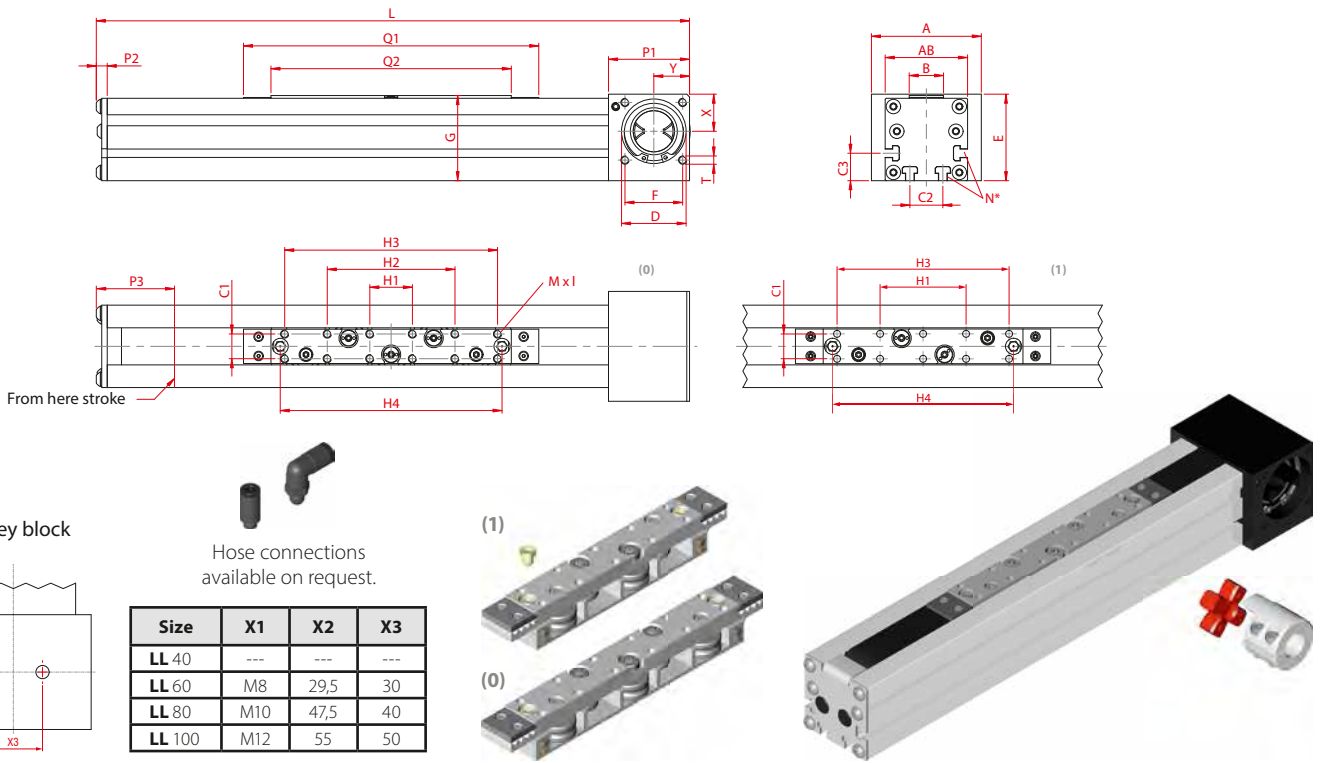
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Linear system LLZ 40, 60, 80, 100

Dimensions (mm)



2 cupped-type lubricating nipples for each carriage

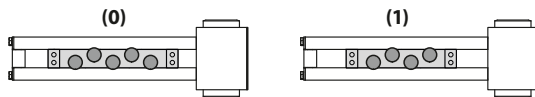
\*For slide nuts refer to chapter 2.2 page 2

Size	Basic length L	A	AB	B	C1	C2	C3	D -0,05	E	F	G	M	N for	P1	P2	P3	T	X	Y	Basic weight	Weight per 100 mm
LLZ 40	222	52	40	15	10	12	14	28	41	25	42	M4x6	M4	36	4	34	M4	16	16	0,69 kg	0,22 kg
LLZ 60	330	80	60	25	18	24	20	47	63	42	62,5	M6x6	M5	59	6	55	M6	27	26	2,75 kg	0,41 kg
LLZ 80	495	100	80	25	18	30	22	68	93	60	83	M6x10	M6	90	9	84	M8	45	40	8,45 kg	0,90 kg
LLZ 100	540	130	100	42	26	40	30	90	110	80	103	M8x12	M8	110	11	109	M10	49,4	50	14,56 kg	1,18 kg

**0 Choice of guide body profile:**

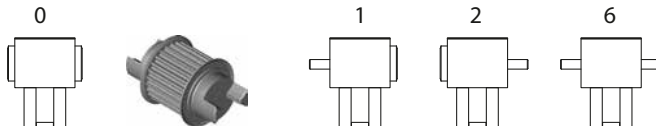
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Carriage	L	Q1	Q2	H1	H2	H3	H4
LL 40 Vers. (0)	222	152	122	21	63	105	111
LL 40 Vers. (1)	200	130	100	42	---	84	90
LL 60 Vers. (0)	330	215	175	31	93	155	161,5
LL 60 Vers. (1)	299	184	144	62	---	124	130,5
LL 80 Vers. (0)	495	320	251	30	90	150	228
LL 80 Vers. (1)	435	260	191	40	---	120	168
LL 100 Vers. (0)	540	320	250	30	90	150	242
LL 100 Vers. (1)	481	261	191	30	90	150	183

**0 Drive version:**



**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 2	40	3M 20	75	25
0 3	60	5M 30	130	26
0 4	80	8M 30	176	22
0 7	100	8M 50	224	28

**Shaft dimensions / Coupling claw:**

Size	Shaft Ø h6 x length	Feather key	Coupling
40	6 x 15	2x2x12	7
60	14 x 35	5x5x28	14
80	18 x 45	6x6x40	19
100	22 h6 x 45	6x6x40	24

LLZ 60 1 0 0 0 0 3 1 1500 — Basic length + stroke = total length

Sample ordering code:  
LLZ60, standard body profile, double-sided coupling claw, 1170 mm stroke

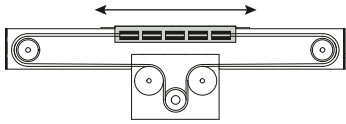
# Linear system **LLZS 60**

## BELT DRIVE

⊕ INDEPENDENT INSTALLATION POSITION

Ω OMEGA SYSTEM

↔ VARIABLE DRIVE BLOCK



**Function:**

The guide body consists of an aluminium square profile, with an integrated roller guide. The carriage is moved by means of an rotating toothed belt. The toothed belt is diverted within a drive block positioned centrally. The result is an enormous compactness with regard to the overall system length. There is a plate on both sides with a tensioning device for the toothed belt.

**Fitting position:**

As required. Max. length 6.000 mm without joints.

**Carriage mounting:**

By tapped holes.

**Unit mounting:**

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

**Belt performance:**

HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.

**Carriage support:**

The carriage runs on 5 rollers which can be adjusted and serviced at each central servicing position. Two grease nipples at the carriage enable relubrication of the positioning system.

11.1

Forces and torques	Size	60	
	Forces/Torques	static	dynamic
	$F_x$ (N)	1073	960
	$F_y$ (N)	780	650
	$F_z$ (N)	1170	845
	$M_x$ (Nm)	20	13
	$M_y$ (Nm)	78	65
	$M_z$ (Nm)	52	39
<b>All forces and torques related to the following:</b>			
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$			
table values			
<b>No-load torque</b>		Nm	
		0,6	
<b>Speed</b>		(m/s) max	
		6	
<b>Tensile force</b>		permanent (N)	
		1050	
		0,2 s (N)	
		1150	
<b>Geometrical moments of inertia of aluminium profile</b>			
		$I_x$ mm <sup>4</sup>	
		4,47x10 <sup>5</sup>	
		$I_y$ mm <sup>4</sup>	
		5,59x10 <sup>5</sup>	
		Elastic modulus N/mm <sup>2</sup>	
		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

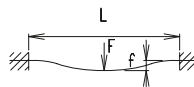
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- $S_i$  = safety factor 1,2 ... 2
- $M_n$  = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- $M_o$  = driving torque (Nm)
- $P_o$  = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

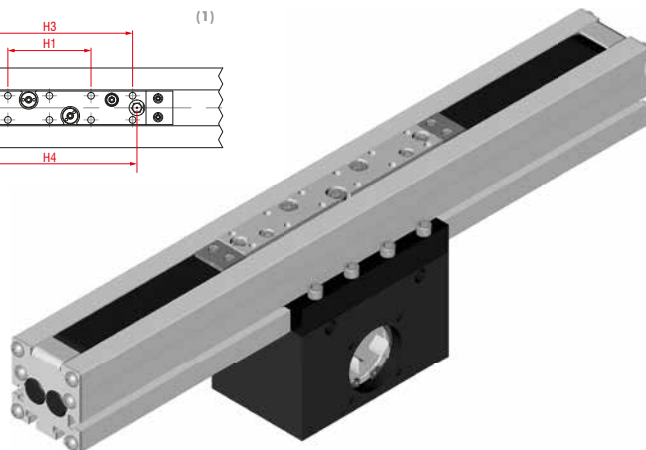
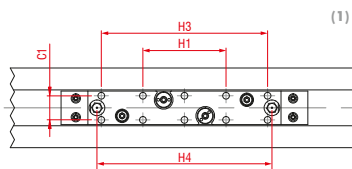
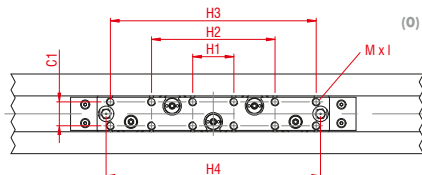
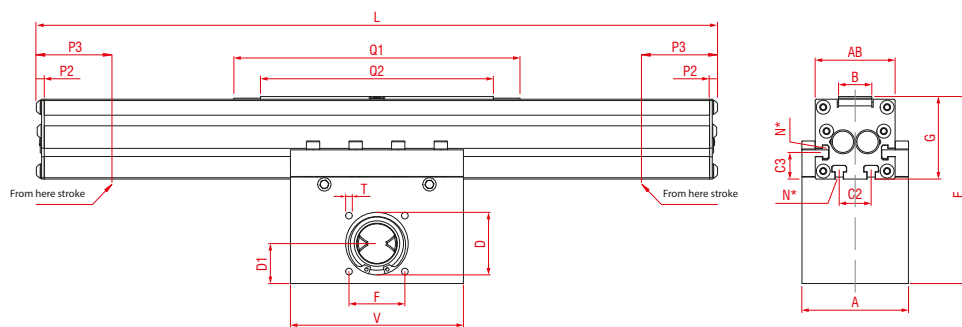
- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)





# Linear system LLZS 60

Dimensions (mm)

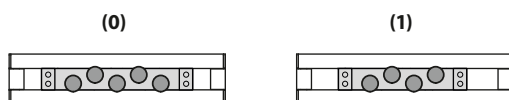


\*For slide nuts refer to chapter 2.2 page 2

Size	Basic length L	A	AB	B	C1	C2	C3	D -0,05	D1	E	F	G	M	N for	P2	P3	T	V	Basic weight	Weight per 100 mm
LLZS 60	325	80	60	25	18	24	20	47	30	140,5	42	62	M6x6	M5	6	55	M6	130	4,1 kg	0,41 kg

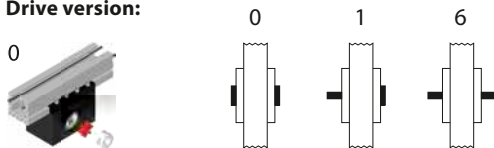
**0 Choice of guide body profile:**  
 (0) Standard (2) corrosion-protected guide rods and screws  
 (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Carriage	L	Q1	Q2	H1	H2	H3	H4
LL 60 Vers. (0)	325	215	175	31	93	155	161,5
LL 60 Vers. (1)	294	184	144	62	---	124	130,5

**0 Drive version:**



**Belt table:**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 3	60	5M 30	130	26

**Shaft dimensions / Coupling claw:**

Size	Shaft Ø h6 x length	Feather key	Coupling
60	14 x 35	5x5x28	14

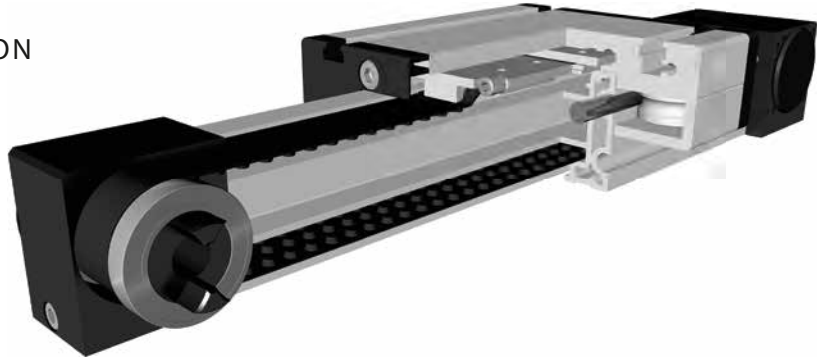
**LLZS 60 1 0 0 0 0 3 1 1500** — Basic length + stroke = total length  
 Pos. 1 2 3 4 5 6 7

Sample ordering code:  
 LLZS60, standard body profile, double-sided coupling claw, 1175 mm stroke

# Linear system **MLN 60, 60S**

## NUBBED BELT DRIVE

- ⊕ INDEPENDENT INSTALLATION POSITION
- ✓ NOBBED BELT
- 🔊 LOW OPERATING VOLUME
- 🛡️ PRECISION



5.1

**Function:**

The guide body consists of an aluminium square profile with lateral, parallel, form-fit, internal hardened steel rods. The guide carriage, which is driven along the shafts by a nubbled belt, moves on the guide body with internal linear ball bearings that are adjustable free of play. The advantage of this system: The belt is guided within the profile, so that the system is independent of the mounting position. The nubbled belt is self-tracking and has a very low operating noise level thanks to its nobs being offset by 45°. Furthermore, it is almost vibration-free in the transition sections.

**Fitting position:**

As required, max. length 6.000 mm without joints.

**Carriage mounting:**

By T-slots.

**Unit mounting:**

By T-slots or tapped holes in the bearing block, mounting sets.

**Belt type:**

N10 with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

Forces and torques	Size	60		60 S	
	Forces/Torques	static	dynamic	static	dynamic
	$F_x$ (N)	1950	1300	1950	1300
	$F_y$ (N)	3000	2000	4100	3100
	$F_z$ (N)	1700	1100	2160	1600
	$M_x$ (Nm)	67	43	88	65
	$M_y$ (Nm)	90	70	190	140
	$M_z$ (Nm)	120	100	230	170
<b>All forces and torques relate to the following:</b>					
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$					
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$					
<b>No-load torque</b>					
Nm		0,6		0,7	
<b>Speed</b>					
(m/s) max		5		7	
<b>Tensile force</b>					
permanent (N)		1050		1050	
0,2 s (N)		1150		1150	
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_x$ mm <sup>4</sup>		4,67x10 <sup>5</sup>		4,67x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		5,21x10 <sup>5</sup>		5,21x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

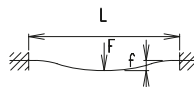
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- $S_i$  = safety factor 1, 2 ... 2
- $M_n$  = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- $M_o$  = driving torque (Nm)
- $P_o$  = motor power (KW)

Deflection:

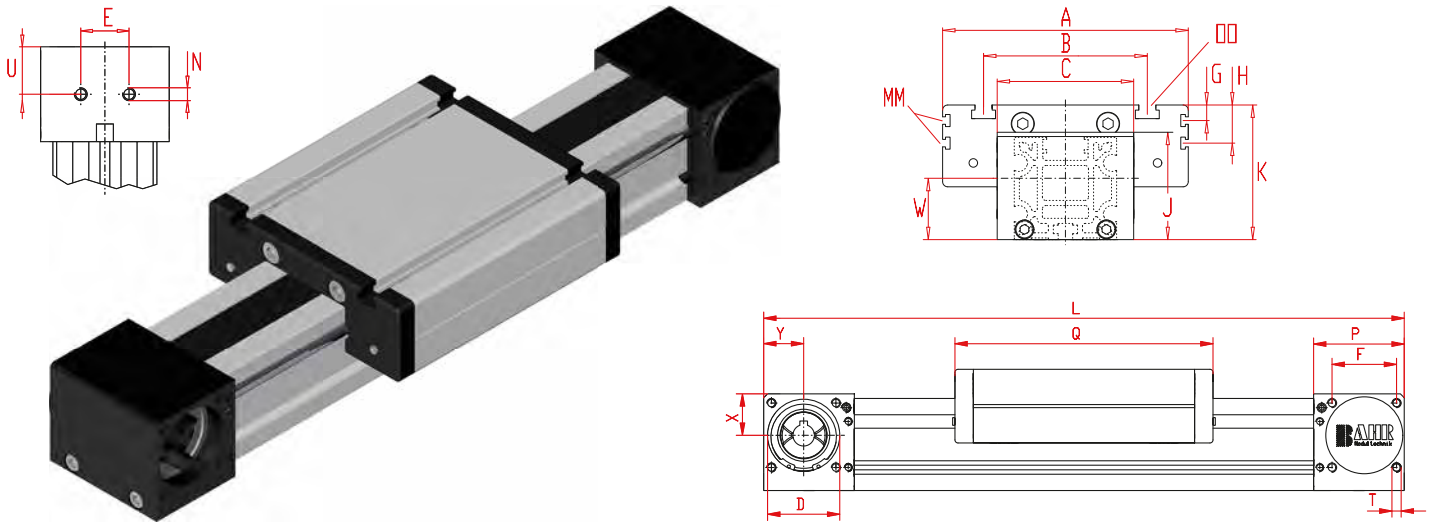
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Linear system **MLN 60, 60S**

Dimensions (mm)



\*For slide nuts refer to chapter 2.2 page 2

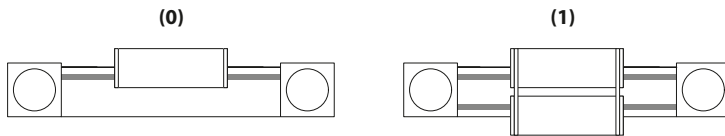
Increasing the carriage length will increase the basic length by the same amount.

Size □	Basic length L	A	B	C	D -0,05	E	F	J	K	N	OO for	P	Q	T	U	W	X	Y	Basic weight	Weight per 100 mm
<b>MLN 60</b>	290	144	96	80	47	30	42	63	79	M 8	M 8	59	168	M 6	29,5	30	27	26	4,7 kg	0,6 kg
<b>MLN 60S</b>	315	170	108	80	47	30	42	63	83	M 8	M 8	59	194	M 6	29,5	30	27	26	5,7 kg	0,6 kg

**0 Choice of guide body profile:**

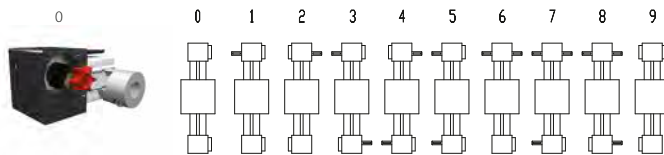
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 1	
	Q	L
<b>60</b>	184	306
<b>60S</b>	214	336

**0 Drive version:**



Version 9 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft.

**Belt table**

Code No.	Size	Belt	mm/rev.	Number of teeth
<b>0 8</b>	<b>60 (S)</b>	Nobbed belt N10	130	13/3

**Shaft dimensions / Coupling claw**

Size	Shaft ø h6 x length	Key	Coupling
<b>60 (S)</b>	14 x 35	5x5x28	14

**MLN 60 1 0 0 0 0 8 1 1500**

Pos. 1 2 3 4 5 6 7

Basic length + stroke = total length

For combination kits and connecting elements refer to chapter 2.2

Sample ordering code:

MLN 60, standard body profile, standard carriage, drive version 0, knobbelt belt, 1210 mm stroke

# Linear system **MLZ 60, 60S, 80, 80S, 100**

## BELT DRIVE

⊕ INDEPENDENT INSTALLATION POSITION

↔ UNIVERSALSYSTEM

📏 LONG TRAVERSE PATH > 6000 MM



5.1

### Function:

This linear unit consists of an aluminium square profile with integrated, hardened steel guide rods. The carriage, which has internal linear ball bearings, that can be adjusted free of play, is driven along the guide rods by a timing belt. The advantage of this system is that the belt is guided within the profile, ensuring that the belt is always tight and thus enabling the system to be operated e.g. when lying on its side. The pulleys have maintenance-free ball bearings. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. With this series, multi-part assembled units with long strokes can be realized.

### Fitting position:

As required, max. length 6.000 mm without joints.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots or tapped holes in the bearing block, mounting sets.

### Belt type:

HTD with steel reinforcement, no backlash when changing direction, repeatability:  $\pm 0,1$  mm.

Forces and torques	Size	MLZ 60		MLZ 60 S		MLZ 80		MLZ 80 S		MLZ 100	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic	static	dynamic	static	dynamic
$F_x$ (N)		894	800	894	800	1900	1800	1900	1800	4000	3800
$F_y$ (N)		3000	2000	4100	3100	3000	2000	4600	3600	8000	6500
$F_z$ (N)		1700	1100	2160	1600	1700	1100	3000	1800	3600	2200
$M_x$ (Nm)		67	43	88	65	90	55	170	140	300	230
$M_y$ (Nm)		90	70	190	140	110	80	270	230	400	270
$M_z$ (Nm)		120	100	230	170	150	120	300	220	750	500
<b>All forces and torques relate to the following:</b>											
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$											
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$											
<b>No-load torque</b>											
Nm		0,6		0,7		0,9		1,2		1,4	
<b>Speed</b>											
(m/s) max		5		7		6		8		10	
<b>Tensile force</b>											
permanent (N)		900		900		1900		1900		4000	
0,2 s (N)		1000		1000		2090		2090		4300	
<b>Geometrical moments of inertia of aluminium profile</b>											
$I_x$ mm <sup>4</sup>		4,83x10 <sup>5</sup>		4,83x10 <sup>5</sup>		17,49x10 <sup>5</sup>		17,49x10 <sup>5</sup>		39,4x10 <sup>5</sup>	
$I_y$ mm <sup>4</sup>		5,03x10 <sup>5</sup>		5,03x10 <sup>5</sup>		18,02x10 <sup>5</sup>		18,02x10 <sup>5</sup>		43,5x10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000		70000		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

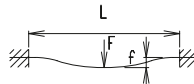
$$P_o = \frac{M_o \cdot n}{9550}$$

F = force (N)  
 P = pulley action perimeter (mm)  
 S<sub>i</sub> = safety factor 1,2 ... 2  
 M<sub>n</sub> = no-load torque (Nm)  
 n = rpm pulley (min<sup>-1</sup>)  
 M<sub>o</sub> = driving torque (Nm)  
 P<sub>o</sub> = motor power (KW)

Deflection:

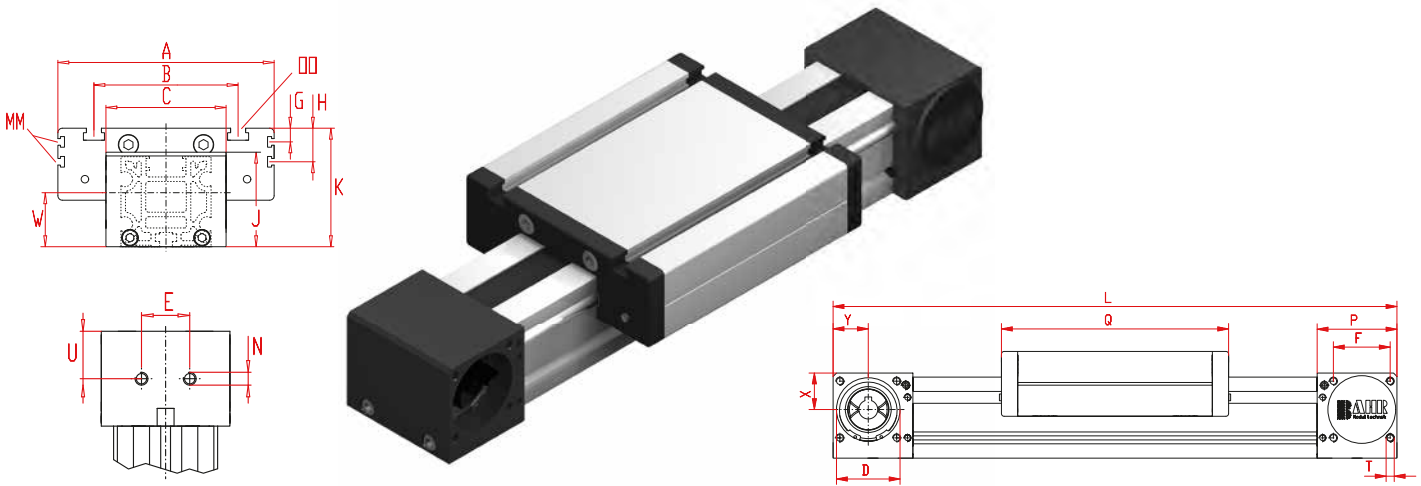
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)



# Linear system **MLZ 60, 60S, 80, 80S, 100**

Dimensions (mm)



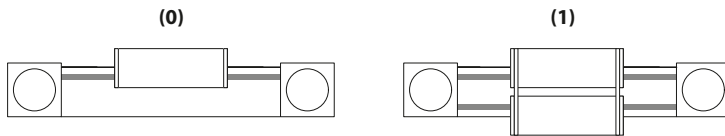
\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	MM for	N	OO for	P	Q	T	U	W	X	Y	Basic weight	Weight per 100 mm
MLZ 60	290	144	96	80	47	30	42	-	-	63	79	-	M 8	M 8	59	168	M 6	29,5	36	27	26	4,7 kg	0,6 kg
MLZ 60S	315	170	108	80	47	30	42	-	-	63	83	-	M 8	M 8	59	194	M 6	29,5	30	27	26	5,7 kg	0,6 kg
MLZ 80	375	170	117	100	68	40	60	10,5	30,5	93	110	M 6	M 10	M 10	90	194	M 8	47,5	40	45	40	9,6 kg	1,0 kg
MLZ 80 S	395	190	126	100	68	40	60	12,5	30	93	111	M 6	M 10	M 8	90	214	M 8	47,5	40	45	40	10,8 kg	1,0 kg
MLZ 100	530	230	155	130	90	50	80	-	29	110	139	M 10	M 12	M 10	110	300	M 10	55	50	49	50	22,5 kg	1,55 kg

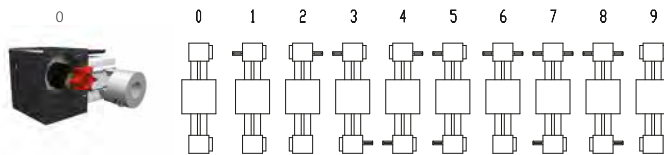
- 0** Choice of guide body profile:  
**(0)** Standard **(2)** corrosion-protected guide rods and screws  
**(4)** expanded corrosion-protected version (depending on the availability of components)

**0** Choice of carriages:



Size	Version 1	
	Q	L
60	184	306
60S	214	336
80	210	391
80S	234	415
100	316	546

**0** Drive version:



Version 9 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft.

**Belt table**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	60 (S)	5M25 (5M19)*	130	26
0 7	80 (S)	8M30 (8M25)*	176	22
0 9	100	8M50 (8M40)*	224	28

\* effective toothed belt width

**Shaft dimensions / Coupling claw**

Size	Shaft ø h6 x length	Key	Coupling
60 (S)	14 x 35	5x5x28	14
80 (S)	18 x 45	6x6x40	19
100	22 x 45	6x6x40	24

**MLZ 60 1 0 0 0 0 4 1 1500**

Pos. 1 2 3 4 5 6 7

Basic length + stroke = total length





For combination kits and connecting elements refer to chapter 2.2

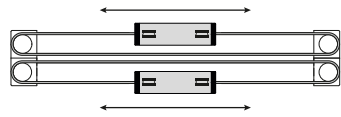
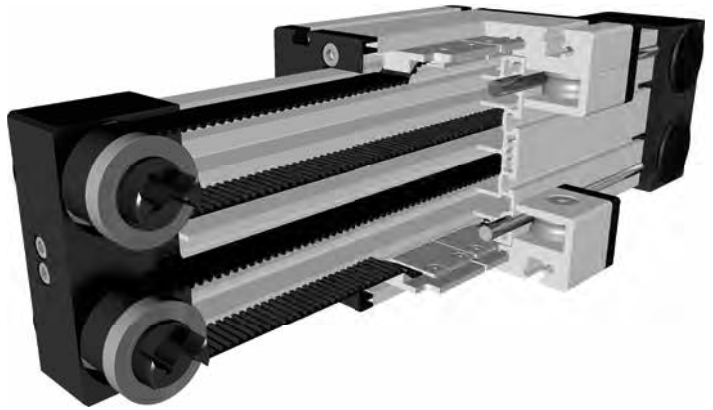
Sample ordering code:

MLZ 60 with standard body profile, standard carriage, coupling claw on one side, 1210 mm stroke.

# Linear system **MLZD 60 (S) W**

## BELT DRIVE - TWO SEPARATELY DRIVEN CARRIAGES

-  HIGHER PROFILE STABILITY
-  INDEPENDENT CARRIAGES
-  HIGHER FORCE FIXTURE
-  INDEPENDENT INSTALLATION POSITION



5.1

**Function:**

The guide body consists of an aluminium square profile with lateral, parallel, form-fit, internal hardened steel rods. Two guide carriages, each with its own drive, move along the guide body. The timing belt is guided within the profile, so that it is independent of the mounting position. Due to the high rectangular profile high torques and loads can be taken up. In addition, a very high stability is ensured for long axis systems. The toothed pulleys have maintenance-free ball bearings. The belt tension can be easily readjusted via a tensioning device within the carriage. This device also helps to adjust the symmetry of the carriages in applications where two parallel linear units are used.

**Fitting position:**

As required, max. length 6.000 mm without joints.

**Carriage mounting:**

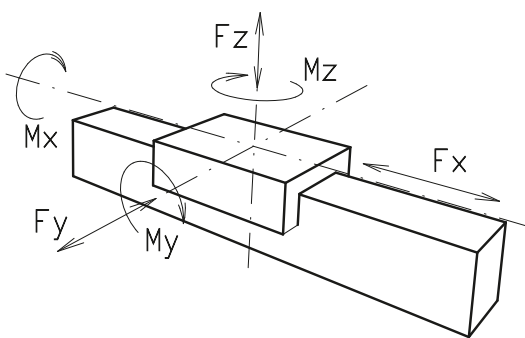
By T-slots.

**Unit mounting:**

By T-slots or tapped holes in the bearing block, mounting sets.

**Belt type:**

HTD with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

Forces and torques	Size	60		60 S	
	Forces/Torques	static	dynamic	static	dynamic
	$F_x$ (N)	894	800	894	800
	$F_y$ (N)	3000	2000	4100	3100
	$F_z$ (N)	1700	1100	2160	1600
	$M_x$ (Nm)	67	43	88	65
	$M_y$ (Nm)	90	70	190	140
	$M_z$ (Nm)	120	100	230	170
	<b>All forces and torques relate to the following:</b> existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$ table values				
<b>No-load torque</b>					
Nm	0,6		0,7		
<b>Speed</b>					
(m/s) max	5		7		
<b>Tensile force</b>					
permanent (N)	900		900		
0,2 s (N)	1000		1000		
<b>Geometrical moments of inertia of aluminium profile</b>					
$I_x$ mm <sup>4</sup>	2,8 x 10 <sup>6</sup>		2,8 x 10 <sup>6</sup>		
$I_y$ mm <sup>4</sup>	9,6 x 10 <sup>5</sup>		9,6 x 10 <sup>5</sup>		
E-Modulus N/mm <sup>2</sup>	70000		70000		

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

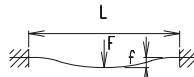
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- $S_i$  = safety factor 1,2 ... 2
- $M_n$  = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- $M_o$  = driving torque (Nm)
- $P_o$  = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

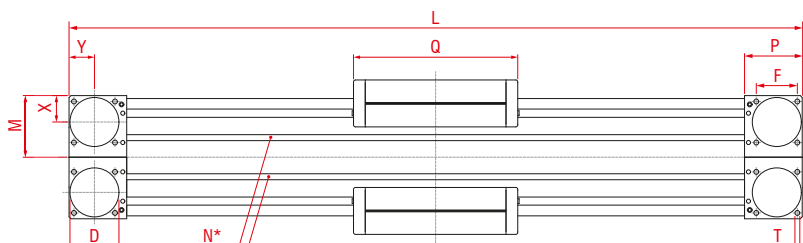
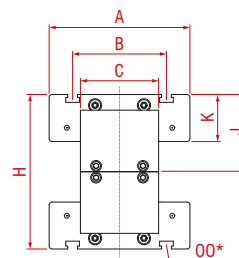
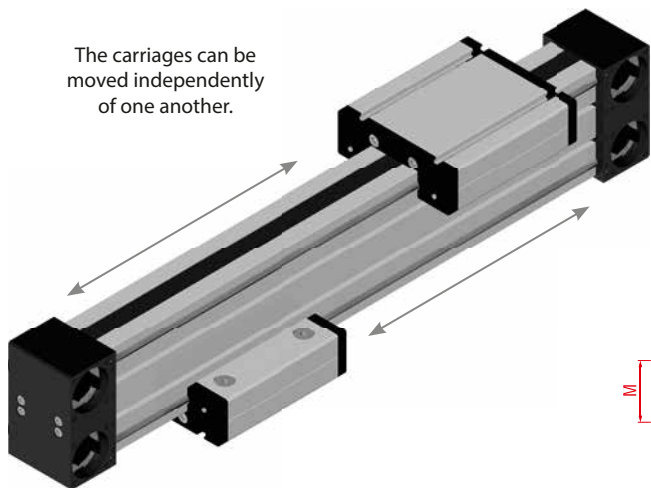
- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Linear system **MLZD 60 (S) W**

Dimensions (mm)

The carriages can be moved independently of one another.



**5.1**

\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

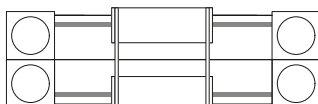
Size	Basic length L	A	B	C	D -0,05	F	H	J	K	M	N for	OO for	P	Q	T	X	Y	Basic weight	Weight per 100 mm
<b>MLZD 60 W</b>	290	144	96	80	47	42	158	79	48	71	M5	M8	59	168	M6	27	26	9,3 kg	1,0 kg
<b>MLZD 60S W</b>	315	170	108	80	47	42	166	83	52	71	M5	M8	59	194	M6	27	26	11,3 kg	1,0 kg

**0 Choice of guide body profile:**

- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

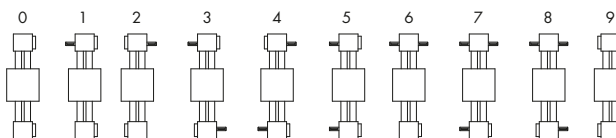
**0 Choice of carriages:**

(0)

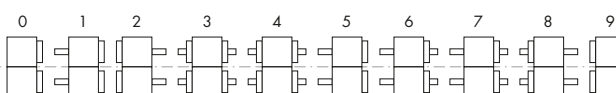


**0 Drive version:**

(0)

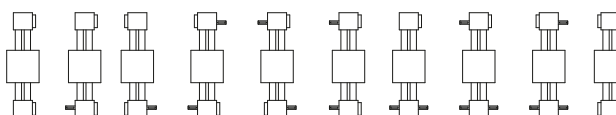


**Top drive version:**  
Version 9 is the same as 0, but with double sided coupling claw.



**Mirror plane**  
Drive version (top and bottom identical)

(0)



**Bottom drive version:**  
Version 9 is the same as 0, but with double sided coupling claw.

**Belt table**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	60 (S)	5M25	130	26

\* effective toothed belt width

**Shaft dimensions / Coupling claw**

Size	Shaft ø h6 x length	Key	Coupling
60 (S)	14 x 35	5x5x28	14

**MLZD 60 W 1 0 0 0 0 4 1 1500**

Pos. 1 2 3 4 5 6 7

Basic length + stroke = total length





For combination kits and connecting elements refer to chapter 2.2

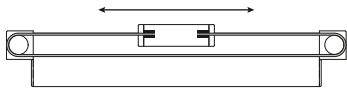
Sample ordering code:

MLZD 60 W, standard body profile, standard carriage, coupling claw on one side, 1210 mm stroke

# Linear system **MLZ 60 (S) W**

## BELT DRIVE

-  INDEPENDENT INSTALLATION POSITION
-  HIGHER PROFILE STABILITY
-  HIGHER FORCE FIXTURE
-  LONG TRAVERSE PATH



5.1

**Function:**

The guide body consists of an aluminium square profile with lateral, parallel, form-fit, internal hardened steel rods. The guide carriage, which is driven along the shafts by a timing belt, moves on the guide body with internal linear ball bearings that are adjustable free of play. The advantage of this system: The timing belt is guided within the profile, so that the system is independent of the mounting position. Due to the rectangular profile high torques and loads can be taken up. In addition, a very high stability and low deflection are ensured for long axis systems. The belt tension can be easily readjusted via a tensioning device within the carriage. This device also helps to adjust the symmetry of the carriages in applications where two parallel linear units are used.

**Fitting position:**

As required, max. length 6.000 mm without joints.

**Carriage mounting:**

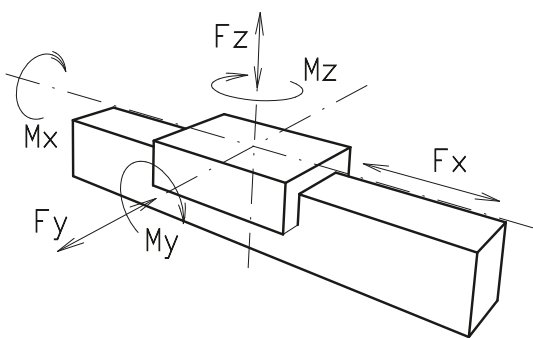
By T-slots.

**Unit mounting:**

By T-slots or tapped holes in the bearing block, mounting sets.

**Belt type:**

HTD with steel reinforcement, no backlash when changing direction, repeatability: ± 0,1 mm.

Forces and torques	Size	60		60 S	
	Forces/Torques	static	dynamic	static	dynamic
	F <sub>x</sub> (N)	894	800	894	800
	F <sub>y</sub> (N)	3000	2000	4100	3100
	F <sub>z</sub> (N)	1700	1100	2160	1600
	M <sub>x</sub> (Nm)	67	43	88	65
	M <sub>y</sub> (Nm)	90	70	190	140
	M <sub>z</sub> (Nm)	120	100	230	170
<b>All forces and torques relate to the following:</b>					
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$					
table values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$					
<b>No-load torque</b>					
Nm		0,6		0,7	
<b>Speed</b>					
(m/s) max		5		7	
<b>Tensile force</b>					
permanent (N)		900		900	
0,2 s (N)		1000		1000	
<b>Geometrical moments of inertia of aluminium profile</b>					
I <sub>x</sub> mm <sup>4</sup>		2,8 x 10 <sup>6</sup>		2,8 x 10 <sup>6</sup>	
I <sub>y</sub> mm <sup>4</sup>		9,6 x 10 <sup>5</sup>		9,6 x 10 <sup>5</sup>	
E-Modulus N/mm <sup>2</sup>		70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

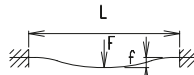
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S<sub>i</sub> = safety factor 1,2 ... 2
- M<sub>n</sub> = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- M<sub>o</sub> = driving torque (Nm)
- P<sub>o</sub> = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

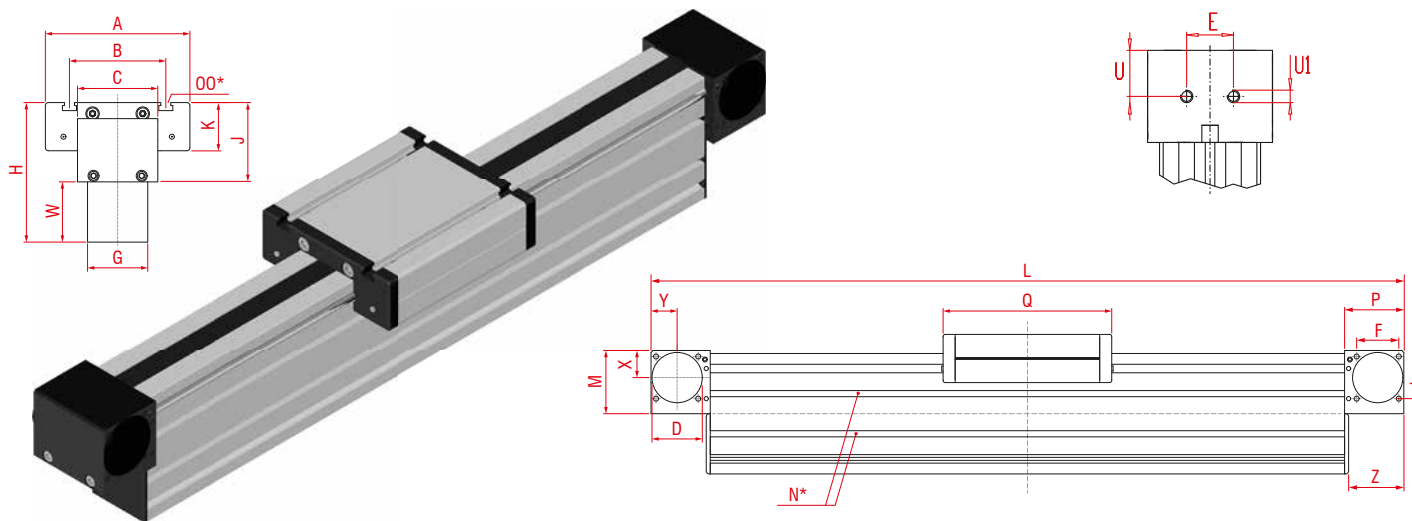
- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)





# Positioning MLZ 60 (S) W

Dimensions (mm)



\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	M	N for	OO for	P	Q	T	U	U1	W	X	Y	Z	Basic weight	Weight per 100 mm
MLZ 60 W	290	144	96	80	47	30	42	60	139	79	48	63	M5	M8	59	168	M6	29,5	M8	60	27	26	55	5,2 kg	0,8 kg
MLZ 60S W	315	170	108	80	47	30	42	60	143	83	52	63	M5	M8	59	194	M6	29,5	M8	60	27	26	55	6,2 kg	0,8 kg

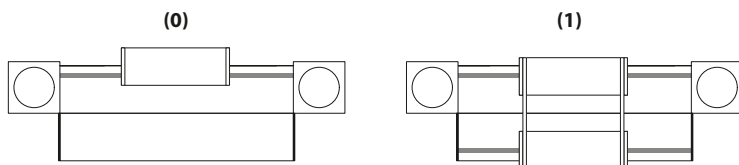
0

**Choice of guide body profile:**

- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

0

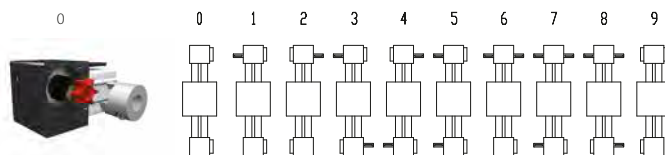
**Choice of carriages:**



Size	Version 1	
	Q	L
60	184	306
60 S	214	336

0

**Drive version:**



Version 9 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft.

**Belt table**

Code No.	Size	Belt	mm/rev.	Number of teeth
0 4	60 (S)	5M25	130	26

\* effective toothed belt width

**Shaft dimensions / Coupling claw**

Size	Shaft $\phi$ h6 x length	Key	Coupling
60 (S)	14 x 35	5x5x28	14

MLZ 60 W 1 0 0 0 0 4 1 1500

Pos. 1 2 3 4 5 6 7

Basic length + stroke = total length

For combination kits and connecting elements refer to chapter 2.2

Sample ordering code:

MLZ 60 W, standard body profile, standard carriage, coupling claw on one side, 1210 mm stroke

5.1

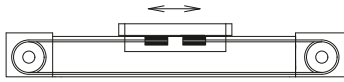
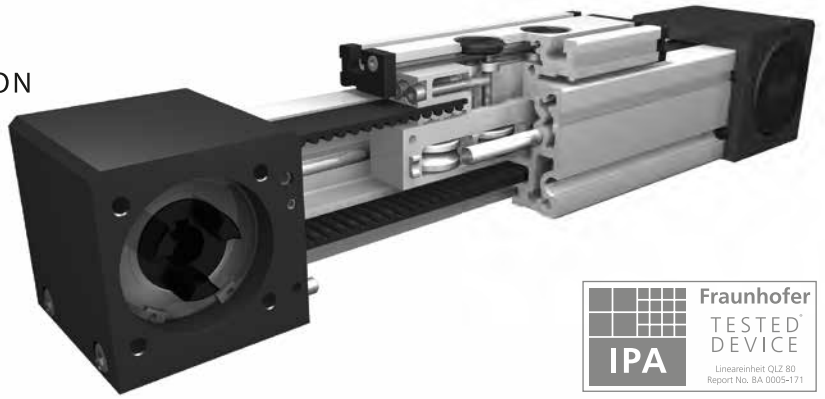
# Linear system **QLZ 60, 80, 100**

## BELT DRIVE

⊕ INDEPENDENT INSTALLATION POSITION

📏 LONG TRAVERSE PATH > 6000 MM

🧼 CLEAN ROOM



### Function:

This unit consists of a square aluminium profile with an integrated roller guide. The carriage is driven by a timing belt. Each standard pulley includes one coupling claw on one side. Belt tension can be readjusted by a simple screw adjustment device in the carriage. This device can also be used for symmetrical adjustment of two or more linear units running parallel. This linear unit is suitable for application in clean rooms of clean-room classification 1.000 (corresponding to US Fed. Standard 209 E). With this series, multi-part assembled units with long strokes can be realized.

### Fitting position:

As required. Max. length 6.000 mm without joints.

### Carriage mounting:

By T-slots.

### Unit mounting:

By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

### Belt performance:

HTD with steel reinforcement, no backlash when changing direction, repeatability  $\pm 0,1$  mm.

### Carriage support:

In the standard version, the carriage runs on 4 rollers which can be adjusted and serviced at a central servicing position. For longer carriages the number of rollers can be increased.

Forces and torques	Size	60		80		100	
	Forces/Torques	static	dynamic	static	dynamic	static	dynamic
	$F_x$ (N)	894	800	1900	1800	4000	3800
	$F_y$ (N)	600	500	1600	1240	1900	1500
	$F_z$ (N)	900	650	1500	1200	2100	1700
	$M_x$ (Nm)	15	10	50	40	85	60
	$M_y$ (Nm)	60	50	100	80	140	110
	$M_z$ (Nm)	40	30	75	60	110	90
	<b>All forces and torques related to the following:</b> existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$ table values						
<b>No-load torque</b>							
Nm	0,6		0,8		1,2		
<b>Speed</b>							
(m/s) max	4		6		7		
<b>Tensile force</b>							
permanent (N)	900		1900		4000		
0,2 s (N)	1000		2090		4300		
<b>Geometrical moments of inertia of aluminium profile</b>							
$I_x$ mm <sup>4</sup>	4,3x10 <sup>5</sup>		16,5x10 <sup>5</sup>		34,93x10 <sup>5</sup>		
$I_y$ mm <sup>4</sup>	4,8x10 <sup>5</sup>		18,7x10 <sup>5</sup>		45,61x10 <sup>5</sup>		
Elastic modulus N/mm <sup>2</sup>	70000		70000		70000		

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

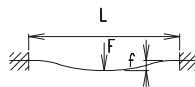
$$P_o = \frac{M_o \cdot n}{9550}$$

$F$  = force (N)  
 $P$  = pulley action perimeter (mm)  
 $S_i$  = safety factor 1,2 ... 2  
 $M_n$  = no-load torque (Nm)  
 $n$  = rpm pulley (min<sup>-1</sup>)  
 $M_o$  = driving torque (Nm)  
 $P_o$  = motor power (KW)

Deflection:

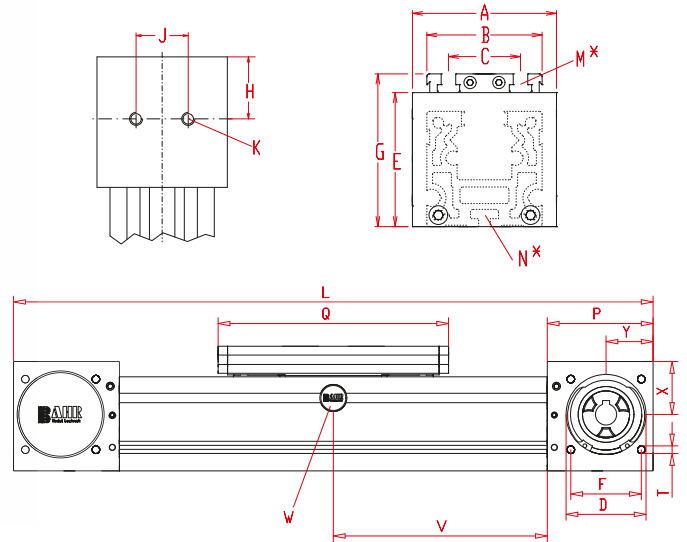
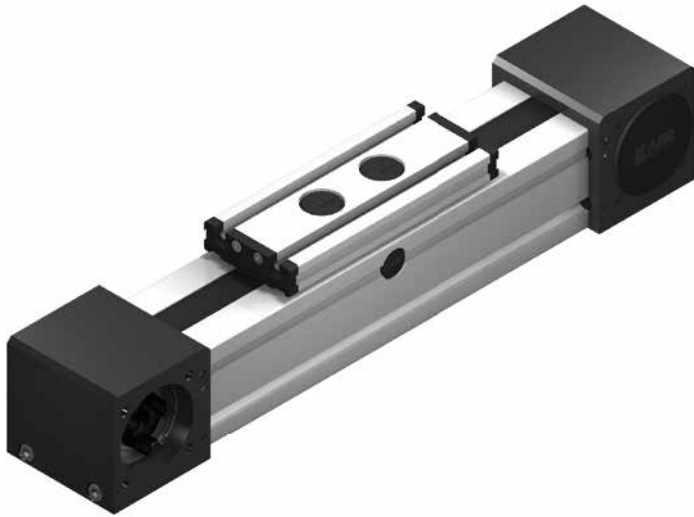
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

$f$  = deflection (mm)  
 $F$  = load (N)  
 $L$  = free length (mm)  
 $E$  = elastic modulus 70000 (N/mm<sup>2</sup>)  
 $I$  = second moment of area (mm<sup>4</sup>)



# Linear system **QLZ 60, 80, 100**

Dimensions (mm)



\*For slide nuts refer to chapter 2.2 page 2  
 $V = Q + 100 \text{ mm}$   $W = \text{servicing position}$

Increasing the carriage length will increase the basic length by the same amount.

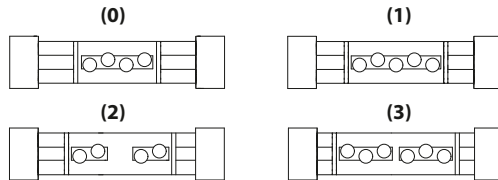
Size □	Basic length L	A	B	C	D -0,05	E	F	G	H	J	K	N for	M for	P	Q	T	X	Y	Basic weight	Weight per 100 mm
QLZ 60	280	80	60	36	47	63	42	79	29,5	30	M 8	M 5	M 6	59	152	M 6	27	26	3,2 Kg	0,39 kg
QLZ 80	390	100	80	50	68	93	60	106	47,5	40	M 10	M 6	M 8	90	196	M 8	45	40	9,6 Kg	0,86 Kg
QLZ 100	490	130	100	66	90	110	80	129	55	50	M 12	M 10	M 10	110	260	M 10	49	50	15,8 kg	1,23 Kg

6.1

**0 Choice of guide body profile:**

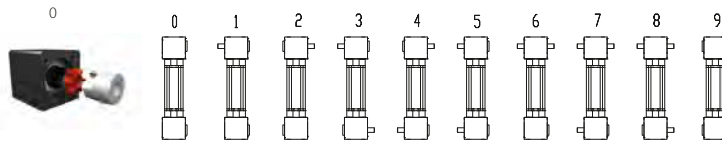
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

**0 Choice of carriages:**



Size	Version 1		Version 2		Version 3	
	Q	L	Q	L	Q	L
60	192	320	>232	>360	>232	>360
80	246	440	>296	>490	>296	>490
100	320	550	>388	>610	>388	>610

**0 Drive version:**



Size	Shaft ø h6 x length	Key
60	14 x 35	5x5x28
80	18 x 45	6x6x40
100	22 x 45	6x6x40

9 is as 0, but with coupling claws on both sides. The standard version is supplied without shaft. A shaft can be retrofitted by inserting it into the pulley bore and securing it with 2 locking rings or tension sets (size 100).

**Belt table / Coupling claw:**

Code No.	Size	Belt	Pulley		Coupling
			mm/rev.	Number of teeth	
0 3	60	5M25	130	26	14
0 4	80	8M30	176	22	19
0 7	100	8M50	224	28	24

**QLZ 80 1 0 0 0 0 4 1 1500** — Basic length + stroke = total length  
 Pos. 1 2 3 4 5 6 7

For additional accessories refer to chapter 2.2

Sample ordering code:  
 QLZ80, standard body profile, standard carriage, coupling claw on one side, 1110 mm stroke