### Screw Driven Tables

# **ZP200 Series Vertical Lift "Wedge" Table**

#### Features

- Precision platform for vertical (Z-axis) positioning
- Continuous duty High dynamic performance
- Precision straightness (±5 arc-sec) throughout range of motion
- Precision ground ballscrew drive 5, 10, or 20 mm lead
- Multi-axis compatibility with XR and LXR tables
- Laser tested and certified with calibrated lead value

### **Quality Design and Construction**

The ZP200 Z axis lift table is a stable support platform which provides precise vertical translation and positioning, while maintaining X-Y integrity. Recirculating square rail bearings are incorporated into a unique variation of "wedge" mechanics to enable reliable high dynamic performance without the potential loss of travel encountered with cross roller bearings. The ZP200 is compatible with XR and LXR tables for multi-axis systems, and it can be utilized as the system base axis or top axis to fit the motion requirements of the application. Standard mounting holes and dowel pin holes accommodate repeatable mounting.

#### Options

- Linear Encoder option with selectable resolutions of 0.1, 0.5, 1.0 μm
- Fail-safe brake (field installable mounts directly to the ballscrew drive)
- Class 10 cleanroom preparation
- Selectable motor mounting and couplings for SM16 or NEMA 23 servo or stepper motors
- Easily adjusted travel "limit" and "home" sensors are provided in an enclosed sensor pack



ZP200 utilized in a laser test set-up



Encoder



## 北京润诚时代科技有限公司

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#### **ZP200 Specifications**

	Precision	Standard							
Travel (Z-axis)	25 mm (limit to limit)	25 mm (limit to limit)							
Positional Accuracy with no encoder <sup>1,2,7</sup> with linear encoder <sup>3,6,7</sup>	8 µm 8 µm	20 µm							
Positional Repeatability with no encoder <sup>1,7</sup> with 1.0 µm linear encoder <sup>6,7</sup> with 0.5 µm linear encoder <sup>6,7</sup> with 0.1 µm linear encoder <sup>6,7</sup>	± 3 μm ± 5 μm ± 4 μm ± 3 μm	± 10 µm 							
Lift Lead Ratio <sup>4</sup> 5 mm lead ballscrew drive 10 mm lead ballscrew drive 20 mm lead ballscrew drive	1.8199 mm/rev 3.6397 mm/rev 7.2794 mm/rev								
Lift Velocity 5 mm lead ballscrew drive 10 mm lead ballscrew drive 20 mm lead ballscrew drive	110 mm/sec 220 mm/sec 440 mm/sec								
Load Capacity (normal)	15 kg (33 lb)	75 kg (165 lb)							
Duty Cycle	100%								
Max Acceleration	7.2 m/sec <sup>2</sup>								
Efficiency	90%								
Max Breakaway Torque <sup>5</sup>	0.15 Nm								
Max Running Torque⁵	0.13 Nm								
Linear Bearing – Coefficient Of Friction	0.01								
Ballscrew Diameter	16 mm								
Unit Weight	5.82 kg								
Top Plate Weight	2.25 kg								
Pitch <sup>7</sup>	± 15 Arc-sec	± 45 Arc-sec							
Roll <sup>7</sup>	± 15 Arc-sec	± 25 Arc-sec							
Input Inertia 5 mm lead ballscrew drive 10 mm lead ballscrew drive 20 mm lead ballscrew drive	2.32 x 10 <sup>-5</sup> Kg-m² 2.51 x 10 <sup>-5</sup> Kg-m² 3.12 x 10 <sup>-5</sup> Kg-m²								

- 1) Measured 38 mm directly above the true center of the top mounting surface.
- Measured using calibrated lead value (provided).
  Slope correction value provided
- Lift per 1 motor shaft revolution. Lift lead listed is nominal. All units are provided with calibrated lead value.
- 5) Torque ratings are measured with unit unloaded, traveling upward.
- 6) Measured directly over encoder on outer edge.
- 7) Pitch and Roll Specifications are measured with <1kg load. Addition of load increases pitch and roll error by 10 arc-sec per 5 kg of load assuming the load center of gravity is located at the center of the stage platform. Cantilevered loading increases these errors more.</p>

#### Table Life/Compression (Normal) Load

The graph provides a preliminary evaluation of the support bearing life/load characteristics. The curves show the life/load relationship when the applied load is centered on the carriage, normal (perpendicular) to the carriage mounting surface. For final evaluation of life vs load, including off center, tension, and side loads contact Parker Applications Engineering at 800-245-6903.







#### Dimensions - inches (mm)

### **ZP200 Series Dimensions**





#### 100-9274-01 XR Adapter Plate

A multi-axis adapter plate is available to mount the ZP200 to an XR/LXR table or, mount an XR/LXR table to the ZP200. This plate is 9.53 mm thick and includes standard dowel pin holes for repeatable alignment.

	ZP200 as Base	ZP200 as Top Axis
404XR	Yes	-*
404LXR	Yes	_*
406XR	Yes	Yes
406LXR	Yes	Yes
206 Rotary	Yes	_*

\*Not recommended - consult factory.



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Screw Driven Tables

Fill in an order code from each of the numbered fields to create a complete model order code.

			1	2	3	4	5	6	7	8	9	10	11	12	(13)	
		Order Example:	ZP200	T01	М	S	D2	H12	2 L12	C3	М3	E3	B2	R1	P1	
1	<mark>Series</mark> ZP200							<pre></pre>	Coupling C1 No coupling C3 0.25" bore bellows							
2	<b>Travel</b> T01	25 mm						(	C5      0.38" bore bellows        C23      9.0 mm (0.35") bore bellows							
3	<mark>Mounti</mark> M	<b>ng</b> Metric						9 1 1	<mark>Viotor I</mark> V11 V12	r Mount No motor mounts SM16/BE16 motor						
4	<mark>Grade</mark> P S	Precision Standard						ľ	VI3 VI61	NEM/ BE23	A 23 aı motor	nd SN <sup>-</sup> mour	123 ma nt	otors		
_								1 (i)	_inear E		ler Op	otion				
5	Drive S	Crew 5 mm lood						E	= 1 = 2	1.0 m	icron					
	D2 D3	o mm lead						E	<b>E</b> 3	0.5 m	icron					
	D4	20 mm lead						E	Ξ4	0.1 m	icron					
								E	<b>E</b> 5	5.0 m	icron					
6	Home S	Sensor						E	<b>E</b> 7	Sine/	cosine	encod	der			
	H1	No sensor						~ ·	Duelte C							
	H11	N.C. current sinking, se	nsor pack						Srake C	No br	ako					
	H12	N.O. current sinking, se	nsor pack	,				Ē	32	Shaft	brake					
	ніз ні <i>д</i>	N.C. current sourcing, s	sensor paci	х 2												
		N.O. Current Sourcing, a		N N				12	Environ	ment	al					
ര	Travel I	imit Sensors						F	R1	Class	1000					
Ŭ	L1	No sensor						F	72	Class	10					
	L11	N.C. current sinking, se	nsor pack					(13) I	21	Place	holde	r				
	L13 L14	N.C. current sourcing, s N.O. current sourcing, s	sensor pack sensor pack	< <				-								



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